

Obsidian Language Formalism

1 Language Overview

2 Obsidian Core Calculus Grammar

The grammar is shown in Figure ??.

$Ct ::= \text{contract } C \{ \overline{St} \ \overline{\tau f} \} \mid \text{contract } C \text{ managed_by } \overline{C'} \{ \overline{St} \ \overline{\tau f} \}$
$St ::= \text{state } S \{ \overline{\tau fMethDecl} \ \overline{MethBody} \}$
$p ::= \text{owned} \mid \text{readonly} \mid \text{shared}$
$\tau_s ::= C \mid C.S$
$\tau ::= p \triangleright \tau_s \mid \text{pack_to}[S, \tau]$
$TxLabel ::= \text{function} \mid \text{transaction}$
$MethDecl ::= TxLabel \ \tau \ m(\overline{\tau x}) \leftrightarrow \overline{S}$
$MethBody ::= \{ e \}$
$c ::= \text{case } S \{ e \}$
$e ::= \text{this.f} \mid x \mid \text{let } x = e \text{ in } e \mid \text{new } C.S(\overline{x}) \text{ as } p \mid \text{throw} \mid \text{try } \{ e \} \text{ catch } \{ e \}$ $\mid \text{pack_to } S(\overline{x}) \text{ returns } x \mid x.m(\overline{x}) \mid \text{unpack } \{ e \} \mid \text{switch } x \{ \overline{c} \}$

Fig. 1. Grammar

3 Static Semantics

Figure ?? defines auxiliary relations that are helpful in defining the typing relation; Figure ?? defines the typing relation for expressions; Figure ?? defines extra typing judgments to check fields, methods, and contracts.

The typing relation $\Delta \vdash_b e : \tau \dashv \Delta'$ is flow-sensitive: it outputs a typing context, in addition to giving a type to the expression e . The following invariant also holds for the typing relation: $x \in \text{dom}(\Delta)$ if and only if $x \in \text{dom}(\Delta')$. Informally, this says that the contexts Δ and Δ' have the exact same variables in them, only differing perhaps by the type assigned to those variables.

The boolean b in the typing judgment indicates whether the expression e should be typed as if it were inside an `unpack` statement: inside an `unpack`, $b = \mathbf{t}$, while outside of an `unpack`, $b = \mathbf{f}$. Some typing judgments are valid for only one or the other case (e.g. `T-PACK` and `T-INV`) but others are valid in either case (e.g. `T-LET`).

Types can either be of contract type or of a special `pack_to` type. Only the former sort of types, however, are allowed in the typing context. This is implicitly enforced by:

- `T-LET` - this rule requires the bound variable to be of contract type
- the method `Ok` judgment - this determines the initial value of the typing context when typechecking a method body, and prohibits `pack_to` types in the initial context
- the field `Ok` judgment - this ensures that fields aren't of type `pack_to`, and thus `pack_to` types cannot appear in the typing context via field unpacking.

It is assumed that the type rules have access to the helper function *lookup*, *fields*, and *methods*. These helper functions retrieve, respectively, the contract signature, the set of fields, and the set of methods of a contract given the contract's name. If the type specifies a specific tpestate, all the methods and fields that are available in that state (including those defined in the contract as a whole) are retrieved.

4 Dynamic Semantics

Auxiliary definitions for the dynamic semantics are shown in Figure ???. The small-step evaluation relation is defined in Figure ??. We augment the set of expressions e in the runtime to make it easier to express the desired semantics for exceptions: it is assumed that whole programs do not make use of the new `try-catch` and method call constructs.

$\boxed{\text{distinct}(\bar{x})}$	Distinct Variables
$\frac{\forall i, j. x_i \neq x_j \vee i = j}{\text{distinct}(\bar{x})}$	
$\boxed{\text{res}(p)}$	Residual Permission
$\text{res}(\text{owned}) = \text{readonly} \quad \text{res}(\text{readonly}) = \text{readonly} \quad \text{res}(\text{shared}) = \text{shared}$	
$\boxed{\text{res}(\tau)}$	Residual Type
$\text{res}(p \triangleright \tau_s) = \text{res}(p) \triangleright \tau_s$	
$\boxed{\text{res}(\bar{x}, \Delta)}$	Residual Context
$\frac{\Delta' = \Delta[x_i \mapsto \text{res}(\Delta(x_i))]}{\text{res}(\bar{x}, \Delta) = \Delta'}$	
$\boxed{\text{rm}(x, \Delta), \text{rm}(\bar{x}, \Delta)}$	
$\frac{p \neq \text{owned}}{\text{rm}(x, (\Delta, x : p \triangleright \tau)) = \Delta} \qquad \frac{x \notin \text{dom}(\Delta)}{\text{rm}(x, \Delta) = \Delta}$	
$\text{rm}(\emptyset, \Delta) = \Delta \quad \text{rm}(\{x_1, \dots, x_n, x_{n+1}\}, \Delta) = \text{rm}(\{x_1, \dots, x_n\}, \text{rm}(x_{n+1}, \Delta))$	
$\boxed{\tau <: \tau'}$	Subtyping
$\tau <: \tau \qquad p \triangleright C.S <: p \triangleright C$	
$\boxed{\text{trans}(\bar{S}, \tau_s)}$	
$\text{trans}(\{S\}, C) = C.S \qquad \text{trans}(\{S_2\}, C.S_1) = C.S_2$	
$\text{trans}(\{S_1, S_2, \dots\}, C.S) = C \qquad \text{trans}(\{S_1, S_2, \dots\}, C) = C$	
$\boxed{\text{mergeable}(\Delta; \Delta_1, \dots, \Delta_n)}$	
$\frac{\text{mergeable}(\Delta; \Delta_1, \dots, \Delta_n) \quad \exists \tau'. (\forall i. \Delta_i(x) <: \tau')}{\text{mergeable}((\Delta, x : \tau); \Delta_1, \dots, \Delta_n)} \quad \text{mergeable}(\emptyset; \Delta_1, \dots, \Delta_n)$	
$\boxed{\text{merge}(\Delta; \Delta_1, \dots, \Delta_n)}$	
$\frac{\text{mergeable}(\Delta; \Delta_1, \dots, \Delta_n)}{\text{merge}(\Delta; \Delta_1, \dots, \Delta_n) = \{(x, \tau) \mid x \in \Delta \ \& \ \Delta_i(x) <: \tau\}}$	

Fig. 2. Auxiliary Relations

$\Delta \vdash_b e : \tau \dashv \Delta'$	
$\frac{\tau <: \tau' \quad \Delta \vdash_b e : \tau \dashv \Delta'}{\Delta \vdash_b e : \tau' \dashv \Delta'} \text{T-SUB}$	$\frac{}{\Delta, x : \tau \vdash_b x : \tau \dashv \Delta, x : \text{res}(\tau)} \text{T-VAR}$
$\frac{x \notin \Delta \quad \Delta \vdash_b e_1 : p \triangleright \tau_s \dashv \Delta_1 \quad \Delta_1, x : p \triangleright \tau_s \vdash_b e_2 : \tau \dashv \Delta_2}{\Delta \vdash_b \text{let } x = e_1 \text{ in } e_2 : \tau \dashv \text{rm}(x, \Delta_2)} \text{T-LET}$	
$\frac{\text{lookup}(C) = \text{contract } C \text{ managed_by } \overline{C'} \Rightarrow \exists i, p'. \Delta(\text{this}) <: p' \triangleright C'_i \quad \tau \overline{f} = \text{fields}(C.S) \quad \forall i. \Delta(x_i) = \tau_i \quad \text{distinct}(\overline{x})}{\Delta \vdash_b \text{new } C.S(\overline{x}) \text{ as } p : p \triangleright C.S \dashv \text{res}(\overline{x}, \Delta)} \text{T-NEW}$	
$\frac{(\tau \ f) \in \text{fields}(\Delta(\text{this}))}{\Delta \vdash_f \text{this}.f : \text{res}(\tau) \dashv \Delta} \text{T-READ}$	$\frac{}{\Delta \vdash_b \text{throw} : \tau \dashv \Delta'} \text{T-THR}$
$\frac{(\text{TxLabel } \tau'' \ m(\overline{\tau}) \rightarrow \overline{S}) \in \text{methods}(\tau') \quad \text{distinct}(\overline{y}, x) \quad \forall i. \Delta(y_i) = \tau_i \quad p = \text{readonly} \Rightarrow \text{TxLabel} = \text{function}}{\Delta, x : p \triangleright \tau' \vdash_f x.m(\overline{y}) : \tau'' \dashv \text{res}(\overline{y}, \Delta), x : p \triangleright \text{trans}(\overline{S}, \tau')} \text{T-INV}$	
$\frac{\Delta(x) = p \triangleright C \quad \forall i. S_i \in \text{states}(C) \quad \forall i. \Delta, x : p \triangleright C.S_i \vdash_f e_i : \tau' \dashv \Delta_i}{\Delta \vdash_f \text{switch } x \ \{\text{case } S_1 \ \{e_1\} \ \dots\} : \tau' \dashv \text{merge}(\Delta; \Delta_1, \dots, \Delta_n)} \text{T-SWITCH}$	
$\frac{\Delta(\text{this}) = p \triangleright C.S_1 \quad p \neq \text{readonly} \quad \overline{\tau} \overline{f} = \text{fields}(C.S_1) \quad \forall i. f_i \notin \Delta \quad \Delta, f_1 : \tau_1, \dots, f_n : \tau_n \vdash_t e : \text{pack_to}[S_2, \tau] \dashv \Delta'}{\Delta \vdash_f \text{unpack } \{e\} : \tau \dashv \text{rm}(\overline{f}, \Delta')} \text{T-UNPACK}$	
$\frac{\overline{\tau} \overline{f} = \text{fields}(\text{trans}(S, \Delta(\text{this}))) \quad \forall i. \Delta(x_i) = \tau_i \quad \Delta(y) = \tau \quad \text{distinct}(\overline{x}, y)}{\Delta \vdash_t \text{pack_to } S(\overline{x}) \text{ returns } y : \text{pack_to}[S, \tau] \dashv \text{res}((\overline{x}, y), \Delta)} \text{T-PACK}$	
$\frac{\Delta \vdash_b e_1 : \tau \dashv \Delta_1 \quad \Delta \vdash_b e_2 : \tau \dashv \Delta_2}{\Delta \vdash_b \text{try } \{e_1\} \ \text{catch } \{e_2\} : \tau \dashv \text{merge}(\Delta; \Delta_1, \Delta_2)} \text{T-TRY}$	

Fig. 3. Statics

$(\tau f) \text{ Ok}$	Field Consistency
$\overline{(\text{owned} \triangleright_{\tau_s} f) \text{ Ok}} \qquad \overline{(p \triangleright_C f) \text{ Ok}}$	
$(\text{MethDecl MethBody}) \text{ Ok in } C.S$	Method Consistency
$\frac{\text{f}; \emptyset, \text{this} : \text{owned} \triangleright C.S, x_1 : \tau_1, \dots, x_n : \tau_n \vdash e : \tau \dashv \Delta}{\forall x, \tau'_s. \Delta(x) = \text{owned} \triangleright \tau'_s \text{ iff } x = \text{this}}$ $\frac{}{\text{transaction } \tau' m(\overline{\tau x}) \leftrightarrow \overline{S} \{e\} \text{ Ok in } C.S}$	
$\frac{\text{f}; \emptyset, \text{this} : \text{readonly} \triangleright C.S, x_1 : \tau_1, \dots, x_n : \tau_n \vdash e : \tau \dashv \Delta}{\forall x, \tau'_s. \Delta(x) \neq \text{owned} \triangleright \tau'_s}$ $\frac{}{\text{function } \tau' m(\overline{\tau x}) \{e\} \text{ Ok in } C.S}$	

Fig. 4. Auxiliary Judgments

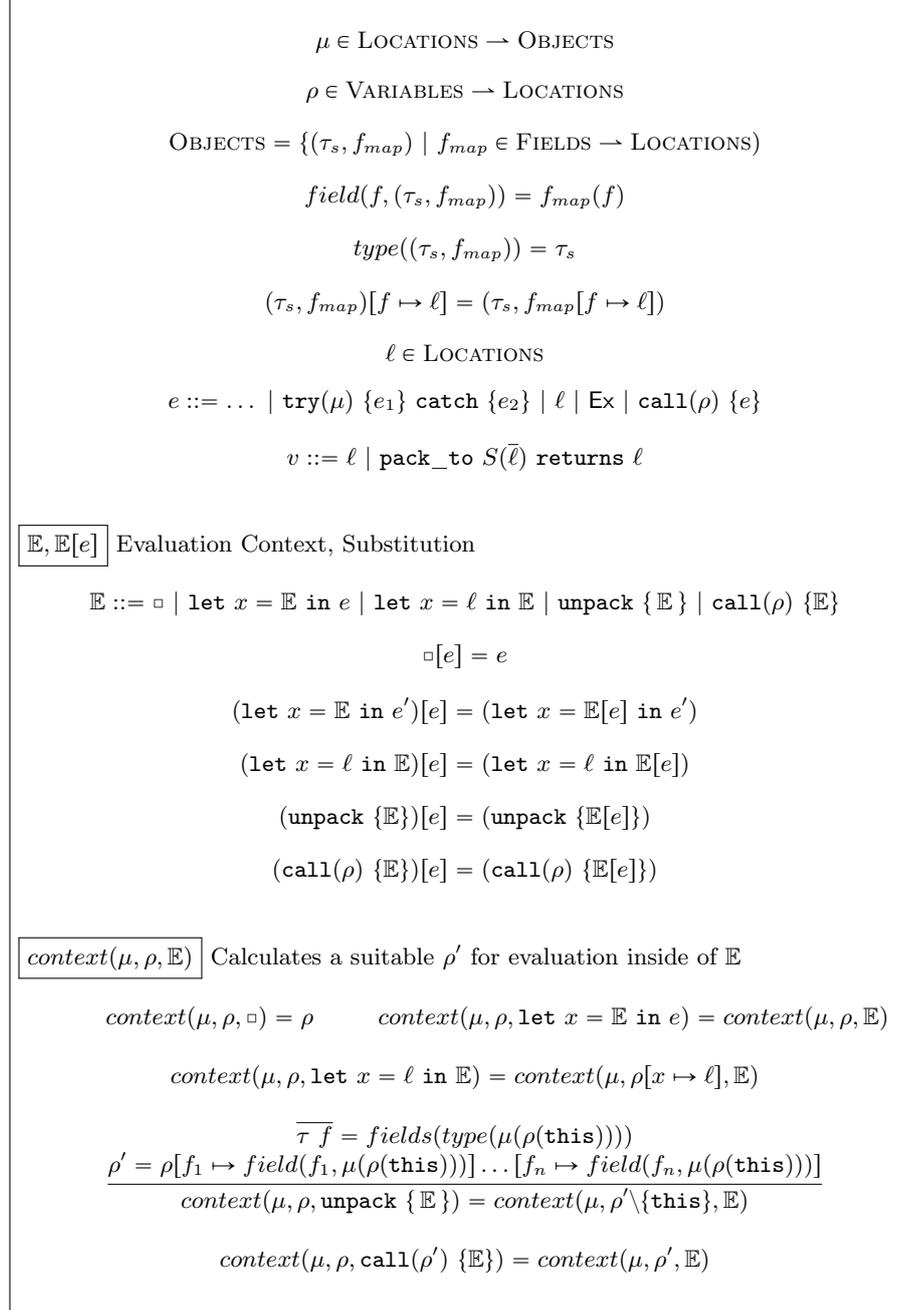


Fig. 5. Auxiliary Definitions

$$\boxed{\mu, \rho, e \rightarrow \mu, e}$$

$$\begin{array}{c}
\frac{}{\mu, \rho, x \rightarrow \mu, \rho(x)} \text{E-VAR} \qquad \frac{}{\mu, \rho, f \rightarrow \mu, \text{field}(f, \mu(\rho(\mathbf{this})))} \text{E-READ} \\
\frac{}{\mu, \rho, \mathbb{E}[\mathbf{Ex}] \rightarrow \mu, \mathbf{Ex}} \text{E-BUBBLE-UP} \qquad \frac{\text{context}(\mu, \rho, \mathbb{E}) = \rho' \quad \mu, \rho', e \rightarrow \mu', e'}{\mu, \rho, \mathbb{E}[e] \rightarrow \mu', \mathbb{E}[e']} \text{E-EV} \\
\frac{}{\mu, \rho, \mathbf{let } x = \ell \mathbf{ in } v \rightarrow \mu, v} \text{E-LET} \qquad \frac{}{\mu, \rho, \mathbf{throw} \rightarrow \mu, \mathbf{Ex}} \text{E-THROW} \\
\frac{\text{lookup}(\text{type}(\mu(\rho(x))), m) = \tau \quad m(\bar{\tau} \bar{z}) \hookrightarrow \bar{S} \{e\} \quad \rho' = \emptyset[z_i \mapsto \rho(y_i)][\mathbf{this} \mapsto \rho(x)]}{\mu, \rho, x.m(\bar{y}) \rightarrow \mu, \text{call}(\rho') \{e\}} \text{E-METHOD} \\
\frac{}{\mu, \rho, \text{call}(\rho') \{\ell\} \rightarrow \mu, \ell} \text{E-RETURN} \\
\frac{\ell \notin \text{Dom}(\mu) \quad \bar{\tau} \bar{f} = \text{fields}(C.S) \quad f_{\text{map}} = \{(f_1, \rho(x_1)), \dots, (f_n, \rho(x_n))\}}{\mu, \rho, \mathbf{new } C.S(\bar{x}) \mathbf{ as } p \rightarrow \mu[\ell \mapsto (C.S, f_{\text{map}})], \ell} \text{E-NEW} \\
\frac{\forall i. \rho(x_i) = \ell_i \quad \rho(y) = \ell'}{\mu, \rho, \mathbf{pack_to } S(\bar{x}) \mathbf{ returns } y \rightarrow \mu, \mathbf{pack_to } S(\bar{\ell}) \mathbf{ returns } \ell'} \text{E-PACK} \\
\frac{\bar{\tau} \bar{f} = \text{fields}(\text{type}(\mu(\rho(\mathbf{this})))) \quad O_{\text{this}} = \rho(\mathbf{this})[f_1 \mapsto \ell_1] \dots [f_n \mapsto \ell_n] \quad \mu' = \mu[\rho(\mathbf{this}) \mapsto O_{\text{this}}]}{\mu, \rho, \mathbf{unpack } \{\mathbf{pack_to } S(\bar{\ell}) \mathbf{ returns } \ell'\} \rightarrow \mu', \ell'} \text{E-TRANS} \\
\frac{}{\mu, \rho, \mathbf{try } \{e_1\} \mathbf{ catch } \{e_2\} \rightarrow \mu, \mathbf{try}(\mu) \{e_1\} \mathbf{ catch } \{e_2\}} \text{E-TRY-1} \\
\frac{\mu, \rho, e_1 \rightarrow \mu', e'_1}{\mu, \rho, \mathbf{try}(\mu_1) \{e_1\} \mathbf{ catch } \{e_2\} \rightarrow \mu', \mathbf{try}(\mu_1) \{e'_1\} \mathbf{ catch } \{e_2\}} \text{E-TRY-2} \\
\frac{}{\mu, \rho, \mathbf{try}(\mu) \{\ell\} \mathbf{ catch } \{e_2\} \rightarrow \mu, \ell} \text{E-TRY-3} \\
\frac{}{\mu, \rho, \mathbf{try}(\mu_1) \{\mathbf{Ex}\} \mathbf{ catch } \{e_2\} \rightarrow \mu_1, e_2} \text{E-CATCH}
\end{array}$$

Fig. 6. Dynamics