## NOTICE WARNING CONCERNING COPYRIGHT RESTRICTIONS:

The copyright law of the United States (title 17, U.S. Code) governs the making of photocopies or other reproductions of copyrighted material. Any copying of this document without permission of its author may be prohibited by law.

# NAMT <br> A GLOBAL METHOD FOR RELAXATION 

Guy Bouchitté
Département de Mathématiques, Université de Toulon et du Var-BP 132
83957 La Garde Cedex, France
Irene Fonseca
Department of Mathematical Sciences, Carnegie Mellon University
Pittsburgh, PA 15213, USA
Luisa Mascarenhas
C.M.A.F., Universidade de Lisboa, Av. Prof. Gama Pinto 2 1699 Lisboa Codex, Portugal


#### Abstract

A new method for the identification of the integral representation of some class of functionals defined on $B V\left(\Omega ; \mathbf{R}^{d}\right) \times \mathcal{A}(\Omega)$ (where $\mathcal{A}(\Omega)$ represents a family of open subsets of $\Omega$ ) is presented. Applications are derived, such as the integral representation of the relaxed energy in $B V\left(\Omega ; \mathbb{R}^{d}\right)$ corresponding to a functional defined in $W^{1.1}\left(\Omega ; \mathbb{R}^{d}\right)$ with a discontinuous integrand with linear growth; relaxation and homogenization results in $S B V\left(\Omega ; \mathbb{R}^{d}\right)$ are recovered in the case where bulk and surface energies are present.


AMS classification numbers : 49J45, 49Q20, 35B27.
Key words : relaxation, functions of (special) bounded variation, Besicovitch's Covering Theorems, Radon-Nikodym Theorem, homogenization, $\Gamma$-convergence.

## 1. Introduction.

Several problems in phase transitions, fracture mechanics, plasticity and image segmentation, may be studied within a framework where the underlying energy is given by a functional of the type

$$
\mathcal{F}: B V\left(\Omega ; \mathbb{R}^{d}\right) \times \mathcal{A}(\Omega) \longrightarrow[0,+\infty]
$$

where $\mathcal{A}(\Omega)$ stands for the family of open subsets A of a fixed bounded domain $\Omega$ of $\mathbb{R}^{N}$, with Lipschitz boundary $\partial A$, and $\mathcal{F}$ satisfies the following properties :
i) $\mathcal{F}(u ; \cdot)$ is the restriction to $\mathcal{A}(\Omega)$ of a Radon measure;
ii) $\mathcal{F}(\cdot ; A)$ is $L^{1}\left(A ; \mathbb{R}^{d}\right)$-lower semicontinuous;
iii) there exists $C>0$ such that, for some $p \geq 1$,

$$
0 \leq \mathcal{F}(u ; A) \leq C\left\{\int_{A}\left(1+|\nabla u|^{p}\right) d x+\left|D_{s} u\right|(A)\right\}
$$

The case where $p>1$ will be studied in a forthcoming paper. Here we treat the case where $p=1$.

An important example of such functionals is given by the relaxed energy corresponding to a discontinuous bulk energy density, precisely

$$
\begin{aligned}
\mathcal{F}(u ; A):=\inf \left\{\liminf _{n \rightarrow+\infty} \int_{A} f_{0}\left(x, u_{n}, \nabla u_{n}\right) d x\right. & \mid u_{n} \rightarrow u \text { in } L^{1}\left(\Omega ; \mathbb{R}^{d}\right), \\
& \left.u_{n} \in W^{1,1}\left(\Omega ; \mathbb{R}^{d}\right)\right\} .
\end{aligned}
$$

We may also consider the case where both bulk and surface energies are present in the underlying functional, namely

$$
\begin{array}{r}
\mathcal{F}(u ; A)=\inf \left\{\liminf _{n \rightarrow+\infty} \int_{A} f_{0}\left(x, u_{n}, \nabla u_{n}\right) d x+\int_{A \cap S\left(u_{n}\right)} g_{0}\left(x, u_{n}^{+}, u_{n}^{-}, \nu_{u_{n}}\right) d H^{N-1} \mid\right. \\
\left.u_{n} \rightarrow u \operatorname{in} L^{1}\left(\Omega ; \mathbb{R}^{d}\right) \quad, \quad u_{n} \in S B V\left(\Omega ; \mathbb{R}^{d}\right)\right\},
\end{array}
$$

where $S\left(u_{n}\right)$ denotes the jump set of $u_{n}$. Another example of a functional $\mathcal{F}$ to which our theory may be applied is provided by a sequence of functionals $F_{\varepsilon}$ (for instance, in the context of homogenization theory), where the energy $\mathcal{F}(u, A)$ that we want to identify reduces to the limit of $\left(F_{\varepsilon}\right)$ in the sense of $\Gamma$-convergence.

A natural question at the core of the Calculus of Variations concerns the search for an integral representation of $\mathcal{F}(u ; A)$. In this paper we propose a new method suitable to the study of all situations mentioned before; the main idea of this method consists in showing that $\mathcal{F}(u ; A)$ can be reconstructed in terms of the set function $m(u, \cdot)$ defined on $\mathcal{A}(\Omega)$ by

$$
m(u ; A):=\inf \left\{\mathcal{F}(v ; A)|v|_{\partial A}=\left.u\right|_{\partial A}, v \in B V\left(\Omega ; \mathbb{R}^{d}\right)\right\} .
$$

The reduction of the relaxed problem to a local Dirichlet type of question has already been used in the context of homogenization or quasiconvexification theories. The main point proved in Section 3 (see Lemma 3.3) is that $m(u ; A)$ behaves as $\mathcal{F}(u ; A)$ when $A$ is a cube of small size. Then the bulk and the jump local densities of the energy can be recovered from $m(u,$.$) by using Besicovitch$ Differentiation Theorem (see Theorem 3.4). An explicit identification of these densities comes easily by means of a blow-up argument and using the Lipschitz behaviour of $m(u, A)$ with respect to the norm in $L^{1}(\partial A)$ of the trace of $u$ (see Lemma 3.1).
In Theorem 3.4 we obtain a representation formula of the form

$$
\begin{equation*}
\mathcal{F}(u ; A)=\int_{A} f(x, u, \nabla u) d x+\int_{S(u) \cap A} g\left(x, u^{+}, u^{-}, \nu_{u}\right) d \mathcal{H}^{N-1} \tag{1.1}
\end{equation*}
$$

for every $u$ in the space $\operatorname{SBV}\left(\Omega ; \mathbb{R}^{d}\right)$ of all functions with bounded variation whose distributional derivative may be written as
$D u=\nabla u \mathcal{L}^{N}+\left[\left(u^{+}-u^{-}\right) \otimes \nu_{u}\right] \mathcal{H}^{N-1}[S(u)$ (see [Am2]). Here, and in what
follows, $\mathcal{L}^{N}$ denotes the $N$-dimensional Lebesgue measure, and $\mathcal{H}^{N-1}$ stands for the $N$-1-dimensional Hausdorff measure (see Section 2). For general $B V$ functions we have also to take into account an extra term in the decomposition of $D u$, $D u=\nabla u \mathcal{L}^{N}+\left[\left(u^{+}-u^{-}\right) \otimes \nu_{u}\right] \mathcal{H}^{N-1}\lfloor S(u)+C(u)$, where $C(u)$ denotes the Cantor part of $D u$. The characterization of the density of $\mathcal{F}$ with respect to $C(u)$ seems to be very difficult to obtain in general (see [BDM] in the scalar case). Under an additional assumption of continuity of $\mathcal{F}$ with respect to vertical and horizontal translations (see condition (2.4)), we obtain in Theorem 3.10 the full integral representation for $u \in B V\left(\Omega ; \mathbb{R}^{d}\right)$,

$$
\begin{align*}
\mathcal{F}(u ; A)= & \int_{A} f(x, u, \nabla u) d x+\int_{S(u) \cap A} g\left(x, u^{+}, u^{-}, \nu_{u}\right) d \mathcal{H}^{N-1}  \tag{1.2}\\
& +\int_{A} f^{\infty}\left(x, u, \frac{d C(u)}{d|C(u)|}\right) d|C(u)|
\end{align*}
$$

In Section 4 we apply the latter characterizations to some specific situations. In Subsection 4.1 we provide a new integral representation of the relaxed energy for a discontinuous integrand with linear growth conditions and in the vectorial case, recovering the results of [FM1] and [FM2] in the case of non degenerate coercivity assumptions. The corresponding scalar case, previously treated by Bouchitté and Dal Maso [BDM], and by Braides and Coscia [BC], follows as a corollary: In Subsection 4.2 we extend the results of Barroso, Bouchitté, Buttazzo and Fonseca $[\mathrm{BBBF}]$ concerning the relaxation in $S B V$ of an energy involving bulk and interfacial contributions. In Subsection 4.3 we obtain the characterization of the homogenized energy associated with a sequence of free discontinuity problems with a linear growth condition. This problem was treated by Braides, Defranceschi and Vitali $[\mathrm{BDV}]$ in the case $p>1$.

## 2. Preliminaries.

Let $\Omega$ represent an open bounded subset of $\mathbb{R}^{N}$. In the sequel we use the standard notations for bounded variation, Sobolev and Lebesgue spaces, denoted, respectively, by $B V\left(\Omega ; \mathbb{R}^{d}\right), W^{1, p}\left(\Omega ; \mathbb{R}^{d}\right)$ and $L^{p}\left(\Omega ; \mathbb{R}^{d}\right) . \mathcal{A}(\Omega)$ stands for the family of all open subsets A of $\Omega$ with Lipschitz boundary $\partial A$, and $\mathcal{B}(\Omega)$ is the collection of all Borel subsets of $\Omega$. The Lebesgue measure and the Hausdorff ( $\mathrm{N}-1$ )-dimensional measure in $\mathbb{R}^{N}$ are designated by $\mathcal{L}^{N}$ and $\mathcal{H}^{N-1}$, respectively. $C$ will denote a generic constant which may vary from line to line.

To each $\nu \in S^{N-1}:=\left\{x \in \mathbb{R}^{N} \mid\|x\|=1\right\}$ we associate a rotation $R_{\nu}$ such that $R_{\nu}\left(e_{N}\right)=\nu$, where $\left(e_{i}\right)_{i=1, \cdots, N}$ stands for the canonical basis in $\mathbb{R}^{N}$. We may choose $\nu \mapsto R_{\nu}$ so that $R_{e_{N}}$ is the identity and $\nu \mapsto R_{\nu}\left(e_{i}\right)$ is continuous in $S^{N-1} \backslash\left\{e_{N}\right\}$, for all $i=1, \cdots, N-1$. We define $Q_{\nu}:=R_{\nu}(Q)$, where $Q:=\left\{x \in \mathbb{R}^{N}| | x \cdot e_{i} \mid<1 / 2, i=1, \cdots, N\right\}$ and we set $Q_{\nu}(x, \varepsilon):=x+\varepsilon Q_{\nu}$, for $\varepsilon>0$. We will omit the subscript $\nu$ whenever $\nu$ coincides with $e_{N}$.

In what concerns general $B V$ space theory we follow Evans and Gariepy [EG], Federer [F], Giusti [G], and Ziemer [Z]. We represent by $\nabla u$ the density of the
absolutely continuous part of $D u$ with respect to the Lebesgue measure (or Radon Nikodym derivative), and $S(u)$, the jump set, is the complement of the set of Lebesgue points, i.e. the set of points $x$ where the approximate upper limit $u_{i}^{+}(x)$ is different from the approximate lower limit $u_{i}^{-}(x)$, for some $i \in\{1, \ldots, d\}$, namely

$$
S(u)=\bigcup_{i=1}^{d}\left\{x \in \Omega \mid u_{i}^{-}(x)<u_{i}^{+}(x)\right\}
$$

Choosing a normal $\nu_{u}(x)$ to $S(u)$ at $x$ (defined uniquely, up to sign, for $\mathcal{H}^{N-1}$ a.e. $x$ ), we set $[u](x):=u^{+}(x)-u^{-}(x)$ the difference between the traces of $u$ at $x \in S(u)$, oriented by $\nu_{u}(x)$. Representing by $C(u)$ the Cantor part of the measure $D u$, the following decomposition holds :

$$
D u=\nabla u \mathcal{L}^{N}+\left([u] \otimes \nu_{u}\right) \mathcal{H}^{N-1}\lfloor S(u)+C(u)
$$

We represent by $S B V\left(\Omega ; \mathbb{R}^{d}\right)$ the space of special functions of bounded variation introduced by De Giorgi and Ambrosio (see [ADG]), i.e. the space of all functions in $B V\left(\Omega ; \mathbb{R}^{d}\right)$ such that $C(u)=0$.

In what follows we consider a functional

$$
\mathcal{F}: B V\left(\Omega ; \mathbb{R}^{d}\right) \times \mathcal{A}(\Omega) \longrightarrow[0,+\infty]
$$

satisfying

$$
\begin{equation*}
\mathcal{F}(u ; \cdot) \text { is the restriction to } \mathcal{A}(\Omega) \text { of a Radon measure, } \tag{2.1}
\end{equation*}
$$

$$
\begin{equation*}
\mathcal{F}(\cdot ; A) \text { is } L^{1}\left(A ; \mathbb{R}^{d}\right) \text { - lower semicontinuous } \tag{2.2}
\end{equation*}
$$

there exist $C>0$ such that

$$
\begin{equation*}
0 \leq \mathcal{F}(u ; A) \leq C\left(\mathcal{L}^{N}(A)+|D u|(A)\right) \tag{2.3}
\end{equation*}
$$

In order to characterize the density energy corresponding to the Cantor part of the measure $\mathcal{F}(u ; \cdot)$, we will need to assume further that the functional $\mathcal{F}$ depends continuously both on horizontal and vertical translations in the following sense :

There exists a modulus of continuity $\Phi(t)$ satisfying

$$
\begin{equation*}
|\mathcal{F}(u(\cdot-z)+b ; z+A)-\mathcal{F}(u ; A)| \leq \Phi(|b|+|z|)\left(\mathcal{L}^{N}(A)+|D u|(A)\right) \tag{2.4}
\end{equation*}
$$

for all $(u, A, b, z) \in B V\left(\Omega ; \mathbb{R}^{d}\right) \times \mathcal{A}(\Omega) \times \mathbb{R}^{d} \times \mathbb{R}^{N}$, such that $z+A \subset \Omega$.
Remark 2.1. Condition (2.2) implies that $\mathcal{F}$ is local, i.e.,
if $u=v \quad \mathcal{L}^{N}$ a.e. $x \in A$, then $\mathcal{F}(u ; A)=\mathcal{F}(v ; A) \quad$ for all $A \in \mathcal{A}(\Omega)$.

Remark 2.2. Without loss of generality we may assume that coercivity holds, and so we replace (2.3) by the condition

$$
\frac{1}{C}|D u|(A) \leq \mathcal{F}(u ; A) \leq C\left(\mathcal{L}^{N}(A)+|D u|(A)\right) \quad \text { for some } C>0
$$

Indeed, if we are able to identify the integral representation under (2.1), (2.2) and (2.3'), given $\mathcal{F}$ satisfying (2.1), (2.2) and (2.3), it suffices to define

$$
\mathcal{F}_{1}(u ; A):=\mathcal{F}(u ; A)+|D u|(A)
$$

By virtue of the lower semicontinuity property of the total variation, it is clear that $\mathcal{F}_{1}$ is under conditions (2.1), (2.2) and (2.3'), and so we are able to find densities $f_{1}, g_{1}, h_{1}$ such that

$$
\begin{aligned}
\mathcal{F}_{1}(u ; A)= & \int_{A} f_{1}(x, u, \nabla u) d x+\int_{S(u) \cap A} g_{1}\left(x, u^{+}, u^{-}, \nu_{u}\right) d \mathcal{H}^{N-1} \\
& +\int_{A} h_{1}\left(x, u, \frac{d C(u)}{d|C(u)|}\right) d|C(u)|
\end{aligned}
$$

We deduce that for every $u \in B V\left(\Omega ; \mathbb{R}^{d}\right)$ we have

$$
\begin{aligned}
\mathcal{F}(u: A)= & \int_{A}\left[f_{1}(x, u, \nabla u)-|\nabla u|\right] d x \\
& +\int_{S(u) \cap A}\left[g_{1}\left(x, u^{+}, u^{-}, \nu_{u}\right)-\left|u^{+}-u^{-}\right|\right] d \mathcal{H}^{N-1} \\
& +\int_{A}\left[h_{1}\left(x, u, \frac{d C(u)}{d|C(u)|}\right)-1\right] d|C(u)|
\end{aligned}
$$

which provides the representation formula (1.2).
We now state some technical results that will be used in the sequel. Given $(u ; A) \in B V\left(\Omega ; \mathbb{R}^{d}\right) \times \mathcal{A}(\Omega)$, we represent by $\operatorname{tr} u$ or $\left.u\right|_{\partial A}$ the trace of $u$ restricted to $A$. The proof of the first two lemmas may be found in $[\mathrm{G}]$.

Lemma 2.3. Let $A \in \mathcal{A}(\Omega)$ and let $u_{n}, u \in B V\left(A ; \mathbb{R}^{d}\right)$ be such that $u_{n} \rightarrow u$ in $L^{1}\left(A ; \mathbb{R}^{d}\right)$ and $\left|D u_{n}\right|(A) \rightarrow|D u|(A)$. Then

$$
\int_{\partial A}\left|\operatorname{tr} u_{n}-\operatorname{tr} u\right| d \mathcal{H}^{N-1} \rightarrow 0
$$

Lemma 2.4. Let $A \in \mathcal{A}(\Omega)$ and let $\theta \in L^{1}(\partial A)$. For every $\varepsilon>0$ there exists $w_{\varepsilon} \in W^{1.1}(A)$ and a constant $C$, depending only on $\partial A$, such that

$$
\left.w_{\varepsilon}\right|_{\partial A}=\theta, \quad \int_{A}\left|w_{\varepsilon}\right| d x \leq \varepsilon \int_{\partial A}|\theta| d \mathcal{H}^{N-1}, \int_{A}\left|\nabla w_{\varepsilon}\right| d x \leq C \int_{\partial A}|\theta| d \mathcal{H}^{N-1}
$$

Next we prove a density result in $B V$ under Dirichlet boundary conditions.

Lemma 2.5. Let $A \in \mathcal{A}(\Omega)$. Given $u \in B V\left(A ; \mathbb{R}^{d}\right)$ we may find $v_{n} \in W^{1,1}\left(A ; \mathbb{R}^{d}\right)$ such that

$$
\left.v_{n}\right|_{\partial A}=\left.u\right|_{\partial A}, \quad\left\|v_{n}-u\right\|_{L^{1}\left(A ; \mathbb{R}^{d}\right)} \rightarrow 0, \quad\left|D v_{n}\right|(A) \rightarrow|D u|(A)
$$

Proof. Let $\theta_{n} \in \mathcal{C}^{\infty}\left(A ; \mathbb{R}^{d}\right)$ satisfy $\theta_{n} \rightarrow u$ in $L^{1}\left(A ; \mathbb{R}^{d}\right)$ and $\int_{A}\left|\nabla \theta_{n}\right| d x \rightarrow$ $|D u|(A)$. By Lemma 2.3 we have

$$
\begin{equation*}
\int_{\partial A}\left|\operatorname{tr} \theta_{n}-\operatorname{tr} u\right| d \mathcal{H}^{N-1} \rightarrow 0 \tag{2.5}
\end{equation*}
$$

Using Lemma 2.4, for each $n$ consider $w_{n} \in W^{1,1}\left(A ; \mathbb{R}^{d}\right)$ such that

$$
\begin{align*}
& \left.w_{n}\right|_{\partial A}=\left.\left(\theta_{n}-u\right)\right|_{\partial A}, \quad \int_{A}\left|w_{n}\right| d x \leq \int_{\partial A}\left|\operatorname{tr} \theta_{n}-\operatorname{tr} u\right| d \mathcal{H}^{N-1} \\
& \int_{A}\left|\nabla w_{n}\right| d x \leq C \int_{\partial A}\left|\operatorname{tr} \theta_{n}-\operatorname{tr} u\right| d \mathcal{H}^{N-1} \tag{2.6}
\end{align*}
$$

Let $v_{n}:=\theta_{n}-w_{n}$. Then $\left.v_{n}\right|_{\partial A}=\left.u\right|_{\partial A}$ and

$$
\begin{equation*}
\left\|v_{n}-u\right\|_{L^{1}\left(A ; \mathbb{R}^{d}\right)} \leq\left\|\theta_{n}-u\right\|_{L^{1}\left(A ; \mathbb{R}^{d}\right)}+\left\|w_{n}\right\|_{L^{1}\left(A ; \mathbb{R}^{d}\right)} \tag{2.7}
\end{equation*}
$$

From (2.5) and (2.6) we conclude that

$$
w_{n} \rightarrow 0 \quad \text { in } W^{1,1}\left(A ; \mathbb{R}^{d}\right)
$$

and so, by (2.7) we have

$$
v_{n} \rightarrow u \quad \text { in } L^{1}\left(A ; \mathbb{R}^{d}\right), \lim _{n \rightarrow+\infty} \int_{A}\left|\nabla v_{n}\right| d x=\lim _{n \rightarrow+\infty} \int_{A}\left|\nabla \theta_{n}\right| d x=|D u|(A)
$$

The following result is a version of the Slicing Lemma of E. De Giorgi.
Lemma 2.6. Let $F: B V\left(\Omega ; \mathbb{R}^{d}\right) \times \mathcal{A}(\Omega) \rightarrow[0,+\infty]$ be a functional satisfying conditions (2.1), (2.2') and (2.3). Let $u \in B V\left(\Omega ; \mathbb{R}^{d}\right)$ and let $\left(v_{n}\right)$ be a sequence in $B V\left(\Omega ; \mathbb{R}^{d}\right)$ such that $v_{n} \rightarrow u$ in $L^{1}\left(\Omega ; \mathbb{R}^{d}\right)$. Then, for every $A \in \mathcal{A}(\Omega)$ we can find a sequence $w_{n} \in B V\left(\Omega ; \mathbb{R}^{d}\right)$ such that

$$
\left\|w_{n}-u\right\|_{L^{1}\left(\Omega ; \mathbb{R}^{d}\right)} \rightarrow 0, w_{n}=u \text { on } \partial A, \limsup _{n \rightarrow+\infty} F\left(w_{n} ; A\right) \leq \liminf _{n \rightarrow+\infty} F\left(v_{n} ; A\right)
$$

Proof. Let $v_{n} \rightarrow u$ in $L^{1}\left(\Omega ; \mathbb{R}^{d}\right)$. Up to a subsequence, we may assume that $\liminf _{n \rightarrow+\infty} F\left(v_{n} ; A\right)=\lim _{n \rightarrow+\infty} F\left(v_{n} ; A\right)$. For each $k \in \mathbb{N}$ define

$$
A_{k}:=\{x \in A \mid \operatorname{dist}(x, \partial A)>1 / k\}
$$

and consider the layer $L_{k}:=A_{k-1} \backslash A_{k}$. For each $n \in \mathbb{N}$ set $M_{n}:=n+\left|D v_{n}\right|(A)$.
Representing by $\left\lceil a \rrbracket\right.$ the integer part of $a \in \mathbb{R}$, we split each $L_{k}$ into $\llbracket M_{n} \rrbracket^{2}$ layers $L_{k, i}, i=1, \cdots,\left[M_{n}\right]^{2}$, of thickness $\left[k(k-1)\left[M_{n}\right]^{2}\right]^{-1}, L_{k}=\bigcup_{i} L_{k, i}$, and where the layers $L_{k, i}$ are labeled so that $L_{k, i}$ is closer to the boundary of $A$ than $L_{k, j}$ if $i>j, i, j \in\left\{1, \cdots,\left[M_{n}\right]^{2}\right\}$.

To each layer $L_{k, i}$ we assign a cut-off function $\varphi_{k, i}$ with $0 \leq \varphi_{k, i} \leq 1, \varphi_{k, i}=0$ in $\Omega \backslash\left[\bigcup_{j \leq i}\left(L_{k, j} \cup A_{k}\right)\right]$ and $\varphi_{k, i}=1$ in $\bigcup_{j<i}\left(L_{k, j} \cup A_{k}\right)$. We have $\left\|\nabla \varphi_{k, i}\right\|_{\infty}=$ $O\left(k^{2} \llbracket M_{n} \rrbracket^{2}\right)$.

Defining

$$
\begin{equation*}
w_{n, k, i}:=\varphi_{k, i} v_{n}+\left(1-\varphi_{k, i}\right) u \tag{2.8}
\end{equation*}
$$

and using (2.1) we will have

$$
\begin{aligned}
F\left(w_{n, k, i} ; A\right) & \leq F\left(v_{n} ; A\right)+F\left(u ; A \backslash A_{k}\right)+F\left(w_{n, k, i} ; L_{k, i}\right) \\
& \leq F\left(v_{n} ; A\right)+C\left(\mathcal{L}^{N}+|D u|\right)\left(A \backslash A_{k}\right)+C\left(\mathcal{L}^{N}+\left|D w_{n, k, i}\right|\right)\left(L_{k, i}\right)
\end{aligned}
$$

where we have used (2.3). On the other hand, for fixed $k$,

$$
\begin{align*}
\frac{1}{\llbracket M_{n} \rrbracket^{2}} \sum_{i}\left|D w_{n, k, i}\right|\left(L_{k, i}\right) \leq & \frac{C}{\llbracket M_{n} \rrbracket^{2}}\left(\left|D v_{n}\right|(A)+|D u|(A)\right) \\
& +\frac{1}{\llbracket M_{n} \rrbracket^{2}} O\left(k^{2} \llbracket M_{n} \rrbracket^{2}\right)\left\|v_{n}-u\right\|_{L^{1}\left(A: \mathbb{R}^{d}\right)} \tag{2.9}
\end{align*}
$$

Since the right hand side of (2.9) goes to zero as $n \rightarrow+\infty$, we can construct a sequence $n_{k} \rightarrow+\infty$ such that

$$
\begin{aligned}
& \left\|u_{n_{k}, k, i}-u\right\|_{L^{1}\left(A: \mathbb{R}^{d}\right)} \leq\left\|v_{n_{k}}-u\right\|_{L^{1}\left(A: \mathbb{R}^{d}\right)} \leq \frac{1}{k} \text { for all } i \in\left\{1, \cdots, \llbracket M_{n_{k}} \rrbracket^{2}\right\} \\
& \frac{1}{\llbracket M_{n_{k}} \rrbracket^{2}} \sum_{i}\left|D w_{n_{k}, k, i}\right|\left(L_{k, i}\right)<\frac{1}{k}
\end{aligned}
$$

and then choose $i_{k}$ such that

$$
\left|D w_{n_{k}, k, i_{k}}\right|\left(L_{k, i_{k}}\right)<\frac{1}{k}
$$

Defining $w_{k}:=w_{n_{k}, k, i_{k}}$ we obtain $w_{k} \rightarrow u$ in $L^{1}\left(\Omega ; \mathbb{R}^{d}\right)$,

$$
F\left(w_{k} ; A\right) \leq F\left(v_{n_{k}} ; A\right)+O(1 / k)
$$

and, consequently,

$$
\limsup _{k \rightarrow+\infty} F\left(w_{k} ; A\right) \leq \limsup _{k \rightarrow+\infty} F\left(v_{n_{k}} ; A\right)=\liminf _{n \rightarrow+\infty} F\left(v_{n} ; A\right),
$$

which completes the proof.
Remark 2.7. Having in mind the applications treated in Section 4, we mention some extensions of Lemma 2.6.

1) If the sequence $\left(v_{n}\right)$ is in $W^{1,1}\left(\Omega ; \mathbb{R}^{d}\right)$ (respectively in $S B V\left(\Omega ; \mathbb{R}^{d}\right)$ ), then the sequence $\left(w_{n}\right)$ can be constructed in $W^{1,1}\left(\Omega ; \mathbb{R}^{d}\right)$ (respectively in $S B V\left(\Omega ; \mathbb{R}^{d}\right)$ ).

Indeed, using Lemma 2.5 we can replace $u$ in (2.8) by a sequence $\left(u_{n}\right)$ in $W^{1,1}\left(\Omega ; \mathbb{R}^{d}\right)$ satisfying

$$
u_{n} \rightarrow u \text { in } L^{1}\left(\Omega ; \mathbb{R}^{d}\right), \quad u_{n}=u \text { on } \partial A, \text { and }\left|D u_{n}\right|(A) \rightarrow|D u|(A) .
$$

Then, by the lower semicontinuity of the total variation in open sets we obtain

$$
\begin{aligned}
\limsup _{n \rightarrow+\infty}\left|D u_{n}\right|\left(A \backslash A_{k}\right) & =\lim _{n \rightarrow+\infty}\left|D u_{n}\right|(A)-\liminf _{n \rightarrow+\infty}\left|D u_{n}\right|\left(A_{k}\right) \\
& \leq|D u|(A)-|D u|\left(A_{k}\right)=|D u|\left(A \backslash A_{k}\right)=O(1 / k)
\end{aligned}
$$

2) We can also extend the results stated in Lemma 2.6 and in the previous remark to a sequence of functionals ( $F_{n}$ ) satisfying conditions (2.1), (2.2') and (2.3) uniformly in $n$. In this case, if $u \in B V\left(\Omega ; \mathbb{R}^{d}\right)$ and $A \in \mathcal{A}(\Omega)$, for each sequence $v_{n} \rightarrow u$ in $L^{1}\left(\Omega ; \mathbb{R}^{d}\right)$ we can find a sequence of indexes $\left(n_{k}\right)$ and a sequence $w_{k} \in B V\left(\Omega ; \mathbb{R}^{d}\right)$ such that
$\left\|w_{k}-u\right\|_{L^{1}\left(\Omega: \mathbb{R}^{d}\right)} \rightarrow 0, w_{k}=u$ on $\partial A, \limsup _{k \rightarrow+\infty} F_{n_{k}}\left(w_{k} ; A\right) \leq \liminf _{n \rightarrow+\infty} F_{n}\left(v_{n} ; A\right)$.

Finally we state the following truncation lemma (see Lemma 3.7 in [BBBF])
Lemma 2.8. Let $F: B V\left(\Omega ; \mathbb{R}^{d}\right) \times \mathcal{A}(\Omega) \rightarrow[0,+\infty]$ be a functional satisfying conditions (2.1), (2.2') and (2.3). If $u_{0} \in B V\left(\Omega ; \mathbb{R}^{d}\right) \cap L^{\infty}\left(\Omega ; \mathbb{R}^{d}\right)$ and if $\varepsilon>0$ then, for every $R>0$ there exists $M=M\left(\varepsilon, R, C,\left\|u_{0}\right\|_{L^{\infty}\left(\Omega: \mathbb{R}^{d}\right)}\right)$ such that for every $u \in B V\left(\Omega ; \mathbb{R}^{d}\right)$ (resp. $u \in S B V\left(\Omega ; \mathbb{R}^{d}\right)$ or $u \in W^{1,1}\left(\Omega ; \mathbb{R}^{d}\right)$ ) with $\|u\|_{B V\left(\Omega ; \mathbb{R}^{d}\right)} \leq R$ and $u=u_{0}$ on $\partial \Omega$, there exists $\bar{u} \in B V\left(\Omega ; \mathbb{R}^{d}\right) \cap L^{\infty}\left(\Omega ; \mathbb{R}^{d}\right)$ (resp. $\bar{u} \in S B V\left(\Omega ; \mathbb{R}^{d}\right) \cap L^{\infty}\left(\Omega ; \mathbb{R}^{d}\right)$ or $\left.\bar{u} \in W^{1,1}\left(\Omega ; \mathbb{R}^{d}\right) \cap L^{\infty}\left(\Omega ; \mathbb{R}^{d}\right)\right)$ such that
i) $\|\bar{u}\|_{L^{x}\left(\Omega ; \mathbb{R}^{d}\right)} \leq M$;
ii) $\bar{u}=u_{0}$ on $\partial \Omega$;
iii) $|D \bar{u}|(\Omega) \leq|D u|(\Omega)$;
iv) $F(\bar{u} ; \Omega) \leq F(u ; \Omega)+\varepsilon$.

## 3. The General Method.

In this section we identify the bulk and jump densities of a functional $\mathcal{F}$ satisfying conditions (2.1), (2.2) and (2.3') (Theorem 3.4). In case condition (2.4) holds, we
can also characterize the Cantor part and conclude with the full representation of $\mathcal{F}$ (see Theorem 3.10).

Given $(u ; A) \in B V\left(\Omega ; \mathbb{R}^{d}\right) \times \mathcal{A}(\Omega)$ we introduce

$$
\begin{equation*}
m(u ; A):=\inf \left\{\mathcal{F}(v ; A)|v|_{\partial A}=\left.u\right|_{\partial A}, v \in B V\left(\Omega ; \mathbb{R}^{d}\right)\right\} \tag{3.1}
\end{equation*}
$$

The basic idea of our method consists in comparing, for fixed $x_{0} \in \Omega$, the asymptotic behaviors of $m\left(u ; Q\left(x_{0}, \varepsilon\right)\right)$ and $\mathcal{F}\left(u ; Q\left(x_{0}, \varepsilon\right)\right)$ when $\varepsilon$ goes to 0 . This is made clear in Lemma 3.3 below where, via a blow-up argument, it is shown that as $\varepsilon$ gets small we may conclude that relaxation reduces to solving a Dirichlet problem. An important tool of this method is Lemma 3.1, which allows us to replace $u$ by its limit obtained by a blow-up at $x_{0}$.

Lemma 3.1. There exists a constant $C$ such that

$$
\begin{equation*}
\left|m\left(u_{1} ; A\right)-m\left(u_{2} ; A\right)\right| \leq C \int_{\partial A}\left|\operatorname{tr}\left(u_{1}-u_{2}\right)\right| d \mathcal{H}^{N-1} \tag{3.2}
\end{equation*}
$$

for all $u_{1}, u_{2} \in B V\left(\Omega ; \mathbb{R}^{d}\right)$ and $A \in \mathcal{A}(\Omega)$.
Proof. Let $u_{1}, u_{2} \in B V\left(\Omega ; \mathbb{R}^{d}\right)$ and $A \in \mathcal{A}(\Omega)$. For $\delta>0$ small enough, set

$$
A_{\delta}:=\{x \in A \mid \operatorname{dist}(x, \partial A)>\delta\}
$$

Given $v \in B V\left(\Omega ; \mathbb{R}^{d}\right)$ with $\left.v\right|_{\partial A}=\left.u_{2}\right|_{\partial A}$, define $v_{\delta}$ such that $v_{\delta}=v$ in $A_{\delta}$, and $v_{\delta}=u_{1}$ in $\Omega \backslash A_{\delta}$. In view of (3.1) and (2.1) one has

$$
\begin{align*}
m\left(u_{1} ; A\right) & \leq \mathcal{F}\left(v_{\delta} ; A\right) \\
& =\mathcal{F}\left(v_{\delta} ; A_{\delta}\right)+\mathcal{F}\left(v_{\delta} ; A \backslash A_{\delta}\right)  \tag{3.3}\\
& \leq \mathcal{F}(v ; A)+\mathcal{F}\left(v_{\delta} ; A \backslash A_{\delta}\right)
\end{align*}
$$

From (2.3'), which still holds for Borel sets, we obtain

$$
\begin{equation*}
\mathcal{F}\left(v_{\delta} ; A \backslash A_{\delta}\right) \leq C \int_{A \backslash A_{\delta}}\left(1+\left|\nabla u_{1}\right|\right) d x+C\left|D_{s} u_{1}\right|\left(A \backslash \bar{A}_{\delta}\right)+C\left|D_{s} v_{\delta}\right|\left(\partial A_{\delta}\right) \tag{3.4}
\end{equation*}
$$

As $\delta$ goes to zero, one has immediately

$$
\begin{equation*}
\int_{A \backslash A_{\delta}}\left(1+\left|\nabla u_{1}\right|\right) d x \rightarrow 0, \quad\left|D_{s} u_{1}\right|\left(A \backslash \bar{A}_{\delta}\right) \rightarrow 0 \tag{3.5}
\end{equation*}
$$

and, using the definition of trace and Green's formula (see [EG], 5.4),

$$
\begin{equation*}
\left|D_{s} v_{\delta}\right|\left(\partial A_{\delta}\right)=\int_{\partial A_{\delta}}\left|\operatorname{tr}\left(\left.u_{1}\right|_{A \backslash \bar{A}_{\delta}}-\left.v\right|_{A_{\delta}}\right)\right| d \mathcal{H}^{N-1} \rightarrow \int_{\partial A}\left|\operatorname{tr}\left(u_{1}-u_{2}\right)\right| d \mathcal{H}^{N-1} \tag{3.6}
\end{equation*}
$$

From (3.3) - (3.6) we conclude that

$$
m\left(u_{1} ; A\right) \leq \mathcal{F}(\imath ; A)+C \int_{\partial A}\left|\operatorname{tr}\left(u_{1}-u_{2}\right)\right| d \mathcal{H}^{N-1}
$$

Taking the infimum over $v$ and interchanging the roles of $u_{1}$ and $u_{2}$, inequality (3.2) follows.

Fix $u \in B V\left(\Omega ; \mathbb{R}^{d}\right), \nu \in S^{N-1}$, and define $\mu:=\mathcal{L}^{N}+\left|D_{s} u\right|$. Let

$$
\begin{equation*}
\mathcal{A}_{\nu}:=\left\{Q_{\nu}(x, \varepsilon) \mid x \in \Omega, \varepsilon>0\right\} \tag{3.7}
\end{equation*}
$$

and for $\delta>0$ set

$$
\begin{array}{r}
m^{\delta}(u ; A):=\inf \left\{\sum_{i=1}^{\infty} m\left(u ; Q_{i}\right) \mid Q_{i} \in \mathcal{A}_{\nu}, Q_{i} \cap Q_{j}=\emptyset, Q_{i} \subset A\right. \\
\left.\operatorname{diam}\left(Q_{i}\right)<\delta, \mu\left(A \backslash \cup_{i=1}^{\infty} Q_{i}\right)=0\right\}
\end{array}
$$

Besicovitch's Covering Theorem guarantees the existence of such coverings of $A$. Given that $\delta \mapsto m^{\delta}(u ; A)$ is a decreasing function, we define

$$
\begin{aligned}
m^{*}(u ; A): & =\sup \left\{m^{\delta}(u ; A) \mid \delta>0\right\} \\
& =\lim _{\delta \rightarrow 0} m^{\delta}(u ; A)
\end{aligned}
$$

Lemma 3.2. Under hypotheses (2.1), (2.2) and (2.3'),

$$
\mathcal{F}(u ; A)=m^{*}(u ; A) .
$$

Proof. Since $\mathcal{F}(u ; \cdot)$ is a Radon measure (see (2.1)), and because $m(u ; A) \leq$ $\mathcal{F}(u ; A)$, the inequality $m^{*}(u ; A) \leq \mathcal{F}(u ; A)$ is obvious. We prove that

$$
\mathcal{F}(u ; A) \leq m^{*}(u ; A)
$$

Fix $\delta>0$ and let $\left(Q_{i}^{\delta}\right)$ be an admissible sequence in the sense of the definition of $m^{\delta}(u ; A)$, such that

$$
\begin{equation*}
\sum_{i=1}^{\infty} m\left(u ; Q_{i}^{\delta}\right)<m^{\delta}(u ; A)+\delta \tag{3.8}
\end{equation*}
$$

Using the definition of $m$, choose $v_{i}^{\delta} \in B V\left(\Omega ; \mathbb{R}^{d}\right)$ such that

$$
\begin{equation*}
\left.v_{i}^{\delta}\right|_{\partial Q_{i}^{\delta}}=\left.u\right|_{\partial Q_{i}^{\delta}}, \quad \mathcal{F}\left(v_{i}^{\delta} ; Q_{i}^{\delta}\right) \leq m\left(u ; Q_{i}^{\delta}\right)+\delta \mathcal{L}^{N}\left(Q_{i}^{\delta}\right) \tag{3.9}
\end{equation*}
$$

Set

$$
v^{\delta}:=\sum_{i=1}^{\infty} v_{i}^{\delta} \chi_{Q_{i}^{\varepsilon}}+u \chi_{N_{o}^{\delta}}
$$

where $N_{0}^{\delta}:=\Omega \backslash \cup_{i=1}^{\infty} Q_{i}^{\delta}$. From (3.8), (3.9) and the coercivity hypothesis (2.3'), it follows that $v^{\delta} \in B V\left(\Omega ; \mathbb{R}^{d}\right)\left({ }^{*}\right)$,

$$
\begin{align*}
& D v^{\delta}=\sum_{i=1}^{\infty} D v_{i}^{\delta}\left\lfloor Q_{i}^{\delta}+D u\left\lfloor N_{0}^{\delta}\right.\right.  \tag{3.10}\\
& \left|D v^{\delta}\right|\left\lfloor N^{\delta}=0, \quad \mu\left(N^{\delta}\right)=0\right.
\end{align*}
$$

where $N^{\delta}:=A \cap N_{0}^{\delta}$, and

$$
\mathcal{F}\left(v^{\delta} ; N^{\delta}\right) \leq C\left(\mathcal{L}^{N}\left(N^{\delta}\right)+\left|D v^{\delta}\right|\left(N^{\delta}\right)\right)=0
$$

Using (2.1), (3.8) and (3.9), we deduce that

$$
\begin{align*}
\mathcal{F}\left(v^{\delta} ; A\right) & =\sum_{i=1}^{\infty} \mathcal{F}\left(v_{i}^{\delta} ; Q_{i}^{\delta}\right)+\mathcal{F}\left(v^{\delta} ; N^{\delta}\right)  \tag{3.11}\\
& \leq m^{\delta}(u ; A)+\delta+\delta \mathcal{L}^{N}(A)
\end{align*}
$$

We claim that $v^{\delta} \rightarrow u$ in $L^{1}(A)$. If so, using hypothesis (2.2) we have

$$
\mathcal{F}(u ; A) \leq \liminf _{\delta \rightarrow 0} \mathcal{F}\left(v^{\delta} ; A\right)
$$

which, together with (3.11), yields

$$
\mathcal{F}(u ; A) \leq \liminf _{\delta \rightarrow 0} m^{\delta}(u ; A)=m^{*}(u ; A)
$$

It remains to prove the claim : $v^{\delta} \rightarrow u$ in $L^{1}(A)$. By Poincarés inequality there exists a constant $C$ such that

$$
\left\|v^{\delta}-u\right\|_{L^{1}\left(Q_{i}^{\delta}\right)} \leq C \delta\left|D v^{\delta}-D u\right|\left(Q_{i}^{\delta}\right),
$$

(*) For every $\varphi \in C_{0}(\Omega)$, integrating by parts on every $Q_{i}^{\delta}$ and recalling that $v_{i}^{\delta}=u$ on $\partial Q_{i}^{\delta}$, we can write

$$
\left\langle D\left(v^{\delta}-u\right), \varphi\right\rangle=-\sum_{i=1}^{\infty} \int_{Q_{i}^{\delta}}\left(v_{i}^{\delta}-u\right) \otimes \nabla \varphi d x=\sum_{i=1}^{\infty} \int_{Q_{i}^{\ell}} \varphi \cdot\left(D v_{i}^{\delta}-D u\right) .
$$

thus

$$
\begin{aligned}
\left\|v^{\delta}-u\right\|_{L^{1}(A)} & =\sum_{i=1}^{\infty}\left\|v_{i}^{\delta}-u\right\|_{L^{1}\left(Q_{i}^{\delta}\right)} \\
& \leq C \delta\left|D v^{\delta}-D u\right|\left(\cup_{i=1}^{\infty} Q_{i}^{\delta}\right) \\
& \leq C \delta\left(\left|D v^{\delta}\right|(A)+|D u|(A)\right)
\end{aligned}
$$

In view of the coercivity condition (2.3) and by (3.11), $\left|D v^{\delta}\right|(A)$ is bounded and we conclude that $\left\|v^{\delta}-u\right\|_{L^{1}(A)} \rightarrow 0$.

Lemma 3.3. Under (2.1),(2.2) and (2.3'), the following equality holds

$$
\begin{equation*}
\lim _{\varepsilon \rightarrow 0} \frac{\mathcal{F}\left(u ; Q_{\nu}\left(x_{0}, \varepsilon\right)\right)}{m\left(u ; Q_{\nu}\left(x_{0}, \varepsilon\right)\right)}=1, \quad \mu \text { a.e. } x_{0} \in \Omega \quad \text { and for all } \nu \in S^{N-1} . \tag{3.12}
\end{equation*}
$$

Proof. Since $m\left(u ; Q_{\nu}\left(x_{0}, \varepsilon\right)\right) \leq \mathcal{F}\left(u ; Q_{\nu}\left(x_{0}, \varepsilon\right)\right)$, we have

$$
1 \leq \liminf _{\varepsilon \rightarrow 0} \frac{\mathcal{F}\left(u ; Q_{\nu}\left(x_{0}, \varepsilon\right)\right)}{m\left(u ; Q_{\nu}\left(x_{0}, \varepsilon\right)\right)}
$$

We only need to prove that, $\mu$ a.e. $x_{0} \in \Omega$ and for all $\nu \in S^{N-1}$,

$$
\underset{\varepsilon \rightarrow 0}{\limsup } \frac{\mathcal{F}\left(u ; Q_{\nu}\left(x_{0}, \varepsilon\right)\right)}{m\left(u ; Q_{\nu}\left(x_{0}, \varepsilon\right)\right)} \leq 1
$$

For each $t>1$ let $E_{t}$ be defined by

$$
\begin{aligned}
& E_{t}:=\left\{x \in \Omega \mid \text { there exist } \nu \in S^{N-1} \text { and } \varepsilon_{h} \rightarrow 0\right. \text { such that } \\
& \left.\qquad \mathcal{F}\left(u ; Q_{\nu}\left(x, \varepsilon_{h}\right)\right)>t m\left(u ; Q_{\nu}\left(x, \varepsilon_{h}\right)\right) \text { for all } h\right\} .
\end{aligned}
$$

Our aim is to show that $\mu\left(E_{t}\right)=0$. Consider an open set $\omega$ and a compact set $K$ such that $K \subset E_{t} \subset \omega$. Fix $\delta>0$ and define

$$
\begin{gathered}
X^{\delta}:=\left\{Q_{\nu}(x, \varepsilon) \mid \varepsilon<\delta, x \in K, Q_{\nu}(x, \varepsilon) \subset \omega, \mathcal{F}\left(u ; Q_{\nu}(x, \varepsilon)\right)>t m\left(u ; Q_{\nu}(x, \varepsilon)\right)\right\} \\
Y^{\delta}:=\left\{Q_{\nu}(x, \varepsilon) \mid \varepsilon<\delta, Q_{\nu}(x, \varepsilon) \subset \omega \backslash K\right\} .
\end{gathered}
$$

By virtue of the definition of $E_{t}$, if $x \in K$ there exists $\varepsilon<\delta$ such that $Q_{\nu}(x, \varepsilon) \in X^{\delta}$ and so

$$
\omega=\left(\bigcup_{Q_{\nu}(x, \varepsilon) \in X^{\delta}} Q_{\nu}(x, \varepsilon)\right) \cup\left(\bigcup_{Q_{\nu}(x, \varepsilon) \in Y^{\delta}} Q_{\nu}(x, \varepsilon)\right) .
$$

Using Besicovich's Covering Theorem, we may find a subcovering of $\omega$ such that

$$
\omega=\left(\bigcup_{i \in I} Q_{i}^{X^{\delta}}\right) \cup\left(\bigcup_{j \in J} Q_{j}^{Y^{\delta}}\right) \cup N
$$

where $I$ and $J$ are countable, $Q_{i}^{X^{\delta}} \in X^{\delta}, Q_{j}^{Y^{\delta}} \in Y^{\delta}$, the sets $Q_{i}^{X^{\delta}}$ and $Q_{j}^{Y^{\delta}}$ are mutually disjoint, and $\mu(N)=0$. Since $m(u ; \cdot) \leq \mathcal{F}(u ; \cdot)$ and $\mathcal{F}(u ; \cdot)$ is absolutely continuous with respect to $\mu$, we have

$$
\begin{aligned}
\mathcal{F}(u ; \omega) & =\sum_{i \in I} \mathcal{F}\left(u ; Q_{i}^{X^{6}}\right)+\sum_{j \in J} \mathcal{F}\left(u ; Q_{j}^{Y^{\delta}}\right) \\
& \geq \sum_{i \in I} t m\left(u ; Q_{i}^{X^{6}}\right)+\sum_{i \in J} m\left(u ; Q_{j}^{Y^{\delta}}\right) \\
& =t\left(\sum_{i \in I} m\left(u ; Q_{i}^{X^{6}}\right)+\sum_{j \in J} m\left(u ; Q_{j}^{Y^{\delta}}\right)\right)+(1-t) \sum_{j \in J} m\left(u ; Q_{j}^{Y^{6}}\right) \\
& \geq t m^{\delta}(u ; \omega)+(1-t) \mathcal{F}(u ; \omega \backslash K),
\end{aligned}
$$

and letting $\delta \rightarrow 0$ we deduce that

$$
\begin{aligned}
\mathcal{F}(u ; \omega) & \geq t m^{*}(u ; \omega)+(1-t) \mathcal{F}(u ; \omega \backslash K) \\
& =t \mathcal{F}(u ; \omega)+(1-t) \mathcal{F}(u ; \omega \backslash K)
\end{aligned}
$$

where we have used Lemma 3.2. Letting $\omega \searrow E_{t}, K \nearrow E_{t}$, and using the regularity of $\mathcal{F}(u ; \cdot)$, we get $\mathcal{F}\left(u ; E_{t}\right)=0$, hence $\mu\left(E_{t}\right)=0$ due to the coercivity assumption.

We now prove the following representation theorem.
Theorem 3.4. Under hypotheses (2.1), (2.2) and (2.3'), for every $u \in S B V\left(\Omega ; \mathbb{R}^{d}\right)$ and $A \in \mathcal{A}(\Omega)$ we have

$$
\mathcal{F}(u ; A)=\int_{A} f(x, u, \nabla u) d x+\int_{S(u) \cap A} g\left(x, u^{+}, u^{-}, \nu_{u}\right) d \mathcal{H}^{N-1}
$$

where

$$
\begin{gather*}
f\left(x_{0}, a, \xi\right):=\limsup _{\varepsilon \rightarrow 0} \frac{m\left(a+\xi\left(\cdot-x_{0}\right) ; Q\left(x_{0}, \varepsilon\right)\right)}{\varepsilon^{N}},  \tag{3.13}\\
g\left(x_{0}, \lambda, \theta, \nu\right):=\limsup _{\varepsilon \rightarrow 0} \frac{m\left(u_{\lambda, \theta, \nu}\left(\cdot-x_{0}\right) ; Q_{\nu}\left(x_{0}, \varepsilon\right)\right)}{\varepsilon^{N-1}}, \tag{3.14}
\end{gather*}
$$

for all $x_{0} \in \Omega, a, \theta, \lambda \in \mathbb{R}^{d}, \xi \in \mathbb{R}^{d \times N}, \nu \in S^{N-1}$, and where

$$
u_{\lambda, \theta, \nu}(y):=\left\{\begin{array}{l}
\lambda \text { if } y \cdot \nu>0 \\
\theta \text { otherwise }
\end{array}\right.
$$

Remark 3.5. for $\mathcal{L}^{N}$ almost

1) If for all $(u, A, b) \in B V\left(\Omega ; \mathbb{R}^{d}\right) \times \mathcal{A}(\Omega) \times \mathbb{R}^{d}$ we have $\mathcal{F}(u+b ; A)=\mathcal{F}(u ; A)$, then $f=f(x, \xi)$ and $g=g(x, \lambda-\theta, \nu)$.
2) If for all $(u, A, z) \in B V\left(\Omega ; \mathbb{R}^{d}\right) \times \mathcal{A}(\Omega) \times \mathbb{R}^{N}$ we have $\mathcal{F}(u(\cdot-z) ; z+A)=\mathcal{F}(u ; A)$, then $f=f(a, \xi)$ and $g=g(\lambda, \theta, \nu)$.
3) In case both conditions 1) and 2) are satisfied we find that the upper-limits in (3.13) and (3.14) are indeed limits.

Remark 3.6. It is easy to check that the conclusions of Lemma 3.3 still hold if we replace the hypercube $Q_{\nu}\left(x_{0}, \varepsilon\right)$ by $K\left(x_{0}, \varepsilon\right):=x_{0}+\varepsilon K$, where $K$ is any bounded, open, convex subset of $\mathbb{R}^{N}$ containing the origin. This remark will be useful to obtain the characterization of the Cantor part of $\mathcal{F}(u ; A)$ when $u \in B V\left(\Omega ; \mathbb{R}^{d}\right)$.

Proof. We first prove (3.13). For $u \in B V\left(\Omega ; \mathbb{R}^{d}\right)$ and $\nu \in S^{N-1}$ (in particular for $\left.\nu=e_{N}\right)$ it is known that for $\mathcal{L}^{N}$ a.e. $x_{0} \in \Omega$

$$
\begin{gather*}
\lim _{\varepsilon \rightarrow 0} \frac{1}{\varepsilon^{N}}|D u|\left(Q_{\nu}\left(x_{0}, \varepsilon\right)\right)=\left|\nabla u\left(x_{0}\right)\right|, \quad \lim _{\varepsilon \rightarrow 0} \frac{1}{\varepsilon^{N}}\left|D_{s} u\right|\left(Q_{\nu}\left(x_{0}, \varepsilon\right)\right)=0  \tag{3.15}\\
\lim _{\varepsilon \rightarrow 0} \frac{1}{\varepsilon^{N+1}} \int_{Q_{\nu}\left(x_{0}, \varepsilon\right)}\left|u(x)-u\left(x_{0}\right)-\nabla u\left(x_{0}\right)\left(x-x_{0}\right)\right| d x=0  \tag{3.16}\\
\frac{d \mathcal{F}(u ; \cdot)}{d \mathcal{L}^{N}}\left(x_{0}\right)=\lim _{\varepsilon \rightarrow 0} \frac{\mathcal{F}\left(u ; Q_{\nu}\left(x_{0}, \varepsilon\right)\right)}{\varepsilon^{N}}
\end{gather*}
$$

and, in view of Lemma 3.3,

$$
\begin{equation*}
\frac{d \mathcal{F}(u ; \cdot)}{d \mathcal{L}^{N}}\left(x_{0}\right)=\lim _{\varepsilon \rightarrow 0} \frac{m\left(u ; Q_{\nu}\left(x_{0}, \varepsilon\right)\right)}{\varepsilon^{N}} \tag{3.17}
\end{equation*}
$$

Let

$$
u_{\varepsilon}(y):=\frac{u\left(x_{0}+\varepsilon y\right)-u\left(x_{0}\right)}{\varepsilon}
$$

By (3.16) we have $u_{\varepsilon} \rightarrow \nabla u\left(x_{0}\right) y$ in $L^{1}\left(Q_{\nu} ; \mathbb{R}^{d}\right)$. We claim that

$$
\begin{equation*}
\left|D u_{\varepsilon}\right|\left(Q_{\nu}\right) \rightarrow\left|\nabla u\left(x_{0}\right)\right| \tag{3.18}
\end{equation*}
$$

If so, by Lemma 2.3 we obtain

$$
\begin{aligned}
& \int_{\partial Q_{\nu}}\left|\operatorname{tr}\left(u_{\varepsilon}(y)-\nabla u\left(x_{0}\right) y\right)\right| d \mathcal{H}^{N-1}(y) \\
& \quad=\frac{1}{\varepsilon^{N}} \int_{\partial Q_{\nu}\left(x_{0}, \varepsilon\right)}\left|\operatorname{tr}\left[u(x)-u\left(x_{0}\right)-\nabla u\left(x_{0}\right)\left(x-x_{0}\right)\right]\right| d \mathcal{H}^{N-1}(x) \rightarrow 0
\end{aligned}
$$

and, consequently, using Lemma 3.1 we obtain from (3.17)

$$
\begin{aligned}
\frac{d \mathcal{F}(u ; \cdot)}{d \mathcal{L}^{N}}\left(x_{0}\right) & =\lim _{\varepsilon \rightarrow 0} \frac{m\left(u\left(x_{0}\right)+\nabla u\left(x_{0}\right)\left(x-x_{0}\right) ; Q_{\nu}\left(x_{0}, \varepsilon\right)\right)}{\varepsilon^{N}} \\
& =f\left(x_{0}, u\left(x_{0}\right), \nabla u\left(x_{0}\right)\right) .
\end{aligned}
$$

We now prove claim (3.18). By definition of $\left|D u_{\varepsilon}\right|\left(Q_{\nu}\right)$,

$$
\begin{aligned}
\left|D u_{\varepsilon}\right|\left(Q_{\nu}\right) & =\sup _{\substack{\phi \in C_{1}^{1}\left(Q_{\nu}\right) \\
\|\phi\|_{x} \leq 1}} \int_{Q_{\nu}} \frac{u\left(x_{0}+\varepsilon y\right)-u\left(x_{0}\right)}{\varepsilon} \operatorname{div} \phi(y) d y, \\
& =\sup _{\substack{\varphi \in C_{0}^{1}\left(Q_{\nu}\left(x_{0}, \varepsilon\right)\right) \\
\|\in\| x \leq 1}} \frac{1}{\varepsilon^{N}} \int_{Q_{\nu}\left(x_{0}, \varepsilon\right)}\left[u(x)-u\left(x_{0}\right)\right] \operatorname{div} \varphi(x) d x, \\
& =\frac{1}{\varepsilon^{N}}|D u|\left(Q_{\nu}\left(x_{0}, \varepsilon\right)\right),
\end{aligned}
$$

where we took $\varphi(x):=\phi\left(\frac{x-x_{0}}{\varepsilon}\right)$. Therefore, by (3.15) $\left|D u_{\varepsilon}\right|\left(Q_{\nu}\right)$ converges to $\left|\nabla u\left(x_{0}\right)\right|$, and the proof of the claim is complete.

Finally, we prove (3.14). For $u \in B V\left(\Omega ; \mathbb{R}^{d}\right)$ it is known that for $\mathcal{H}^{N-1}$ a.e. $x_{0} \in S(u)$

$$
\begin{gather*}
\left|[u]\left(x_{0}\right)\right|=\lim _{\varepsilon \rightarrow 0} \frac{1}{\varepsilon^{N-1}}|D u|\left(Q_{\nu}\left(x_{0}, \varepsilon\right)\right)  \tag{3.19}\\
\lim _{\varepsilon \rightarrow 0} \frac{1}{\varepsilon^{N}} \int_{Q_{\nu}^{+}\left(x_{0}, \varepsilon\right)}\left|u(x)-u^{+}\left(x_{0}\right)\right| d x=0  \tag{3.20}\\
\lim _{\varepsilon \rightarrow 0} \frac{1}{\varepsilon^{N}} \int_{Q_{\nu}^{-}\left(x_{0}, \varepsilon\right)}\left|u(x)-u^{-}\left(x_{0}\right)\right| d x=0 \tag{3.21}
\end{gather*}
$$

where $\nu=\nu_{u}\left(x_{0}\right)$ is the normal to $S(u), Q_{\nu}^{+}\left(x_{0}, \varepsilon\right):=\left\{x \in Q_{\nu}\left(x_{0}, \varepsilon\right) \mid\left(x-x_{0}\right)\right.$. $\left.\nu\left(x_{0}\right)>0\right\}$ and $Q_{\nu}^{-}\left(x_{0}, \varepsilon\right):=\left\{x \in Q_{\nu}\left(x_{0}, \varepsilon\right) \mid\left(x-x_{0}\right) \cdot \nu\left(x_{0}\right)<0\right\}$,

$$
\frac{d \mathcal{F}(u ; \cdot)}{d \mathcal{H}^{N-1}[S(u)}\left(x_{0}\right)=\lim _{\varepsilon \rightarrow 0} \frac{\mathcal{F}\left(u ; Q_{\nu}\left(x_{0}, \varepsilon\right)\right)}{\varepsilon^{N-1}}
$$

and, in view of Lemma 3.3,

$$
\begin{equation*}
\frac{d \mathcal{F}(u ; \cdot)}{d \mathcal{H}^{N-1}[S(u)}\left(x_{0}\right)=\lim _{\varepsilon \rightarrow 0} \frac{m\left(u ; Q_{\nu}\left(x_{0}, \varepsilon\right)\right)}{\varepsilon^{N-1}} \tag{3.22}
\end{equation*}
$$

Defining, for each $y \in Q_{\nu}$,

$$
u_{\varepsilon}(y):=u\left(x_{0}+\varepsilon y\right) \text { and } \bar{u}_{x_{0}, \nu}(y):=\left\{\begin{array}{l}
u^{+}\left(x_{0}\right) \text { if } y \cdot \nu>0 \\
u^{-}\left(x_{0}\right) \text { if } y \cdot \nu \leq 0
\end{array}\right.
$$

from (3.20) and (3.21) we have that $u_{\varepsilon} \rightarrow \bar{u}_{x_{0}, \nu}$ in $L^{1}\left(Q_{\nu}\right)$ and, by the same argument used to prove (3.18) and by (3.19), we obtain that

$$
\left.\left|D u_{\varepsilon}\right|\left(Q_{\nu}\right)=\frac{1}{\varepsilon^{N-1}}|D u|\left(Q_{\nu}\left(x_{0}, \varepsilon\right)\right) \rightarrow| | u\right]\left(x_{0}\right)\left|=\left|D \bar{u}_{x_{0}, \nu}\right|\left(Q_{\nu}\right)\right.
$$

In light of Lemma 2.3, we have

$$
\int_{\partial Q_{\nu}}\left|\operatorname{tr}\left(u_{\varepsilon}-\bar{u}_{x_{0}, \nu}\right)\right| d \mathcal{H}^{N-1}=\frac{1}{\varepsilon^{N-1}} \int_{\partial Q_{\nu}\left(x_{0}, \varepsilon\right)}\left|\operatorname{tr}\left(u-\bar{u}_{x_{0}, \nu}\left(\cdot-x_{0}\right)\right)\right| d \mathcal{H}^{N-1} \rightarrow 0
$$

and, by (3.22) and Lemma 3.1, we conclude that

$$
\begin{aligned}
\frac{d \mathcal{F}(u ; \cdot)}{d \mathcal{H}^{N-1}\lfloor S(u)}\left(x_{0}\right) & =\lim _{\varepsilon \rightarrow 0} \frac{m\left(\bar{u}_{x_{0}, \nu}\left(\cdot-x_{0}\right) ; Q_{\nu}\left(x_{0}, \varepsilon\right)\right)}{\varepsilon^{N-1}} \\
& =g\left(x_{0}, u^{+}\left(x_{0}\right), u^{-}\left(x_{0}\right), \nu_{u}\left(x_{0}\right)\right)
\end{aligned}
$$

In order to complete the integral representation on all $B V\left(\Omega ; \mathbb{R}^{d}\right)$, it remains to obtain the characterization of the energy density with respect to the Cantor part of $D u, C(u)$. By Lemma 3.3, this problem reduces to the computation of

$$
\begin{equation*}
\frac{d \mathcal{F}(u ; \cdot)}{d|C(u)|}\left(x_{0}\right)=\lim _{\varepsilon \rightarrow 0} \frac{m\left(u ; x_{0}+\varepsilon K\right)}{|D u|\left(x_{0}+\varepsilon K\right)} \tag{3.23}
\end{equation*}
$$

at $C(u)$-almost all $x_{0} \in \Omega$, where (see Remark 3.6) $K$ is any convex bounded open subset containing the origin in its interior. Recall that, by Alberti's result [A], the Cantor measure $C(u)$ is rank one, precisely,

$$
\begin{equation*}
\frac{d C(u)}{d|C(u)|}\left(x_{0}\right)=a_{u}\left(x_{0}\right) \otimes \nu_{u}\left(x_{0}\right) \tag{3.24}
\end{equation*}
$$

for $|C(u)|$ a.e. $x_{0}$ and for suitable $\left(a_{u}\left(x_{0}\right), \nu_{u}\left(x_{0}\right)\right) \in \mathbb{R}^{d} \times S^{N-1}$. In Lemma 3.7 below we will use (3.23) taking for $K$ the hypercube $Q_{\nu}^{(k)}$, with $\nu=\nu_{u}\left(x_{0}\right)$, obtained from $Q_{\nu}$ by a dilatation of amplitude $k(k \in \mathbb{N}$ will tend to $+\infty)$ in the directions orthogonal to $\nu$, precisely,

$$
Q_{\nu}^{(k)}=R_{\nu}\left(\left(-\frac{k}{2}, \frac{k}{2}\right)^{N-1} \times\left(-\frac{1}{2}, \frac{1}{2}\right)\right)
$$

where $R_{\nu}$ denotes a rotation such that $R_{\nu}\left(e_{N}\right)=\nu($ see Section 2).

Lemma 3.7. Given $u \in B V\left(\Omega ; \mathbb{R}^{d}\right)$, for $|C(u)|$ almost all $x_{0} \in \Omega$ there exists a double indexed sequence $\left(t_{\varepsilon}^{(k)}, b_{\varepsilon}^{(k)}\right) \in(0,+\infty) \times \mathbb{R}^{d}$ such that, for every $k$,

$$
\begin{align*}
& t_{\varepsilon}^{(k)} \rightarrow+\infty, \quad \varepsilon t_{\varepsilon}^{(k)} \rightarrow 0, \quad b_{\varepsilon}^{(k)} \rightarrow u\left(x_{0}\right), \text { as } \varepsilon \rightarrow 0 \\
& \text { and } \\
& \frac{d \mathcal{F}(u ; \cdot)}{d|C(u)|}\left(x_{0}\right)=\lim _{k \rightarrow+\infty} \limsup _{\varepsilon \rightarrow 0} \frac{m\left(b_{\varepsilon}^{(k)}+t_{\varepsilon}^{(k)} a \otimes \nu\left(\cdot-x_{0}\right) ; x_{0}+\varepsilon Q_{\nu}^{(k)}\right)}{k^{N-1} \varepsilon^{N} t_{\varepsilon}^{(k)}} \tag{3.25}
\end{align*}
$$

where $a=a_{u}\left(x_{0}\right)$ and $\nu=\nu_{u}\left(x_{0}\right)$ satisfy (3.24).
Proof. Let us apply (3.23) with $K=Q_{\nu}^{(k)}$ and set $Q_{\nu}^{(k)}\left(x_{0}, \varepsilon\right):=x_{0}+\varepsilon Q_{\nu}^{(k)}$. There exists a $|C(u)|$-negligible set $N, S(u) \subset N$, such that for all $x_{0} \in \Omega \backslash N$ and for all $k \in \mathbb{N}$

$$
\begin{gather*}
\frac{d \mathcal{F}(u ; \cdot)}{d|C(u)|}\left(x_{0}\right)=\lim _{\varepsilon \rightarrow 0} \frac{m\left(u ; Q_{\nu}^{(k)}\left(x_{0}, \varepsilon\right)\right)}{|D u|\left(Q_{\nu}^{(k)}\left(x_{0}, \varepsilon\right)\right)},  \tag{3.26}\\
t_{\varepsilon}^{(k)}:=\frac{|D u|\left(Q_{\nu}^{(k)}\left(x_{0}, \varepsilon\right)\right)}{\varepsilon^{N} k^{N-1}}, \quad t_{\varepsilon}^{(k)} \rightarrow+\infty \quad, \quad \varepsilon t_{\varepsilon}^{(k)} \rightarrow 0 . \tag{3.27}
\end{gather*}
$$

Condition $\varepsilon t_{\varepsilon}^{(k)} \rightarrow 0$ follows easily from the fact that $\mathcal{H}^{N-1}(B)<+\infty$ implies that $|C(u)|(B)=0$ (see Prop. 3.1 in [Am1]).

Define, for each $\varepsilon>0$ and $k \in \mathbb{N}$,

$$
\begin{align*}
& \theta_{\varepsilon}^{(k)}:=\frac{1}{\varepsilon^{N} k^{N-1}} \int_{Q_{\nu}^{(k)}\left(x_{0}, \varepsilon\right)} u(x) d x,  \tag{3.28}\\
& b_{\varepsilon}^{(k)}:=\frac{1}{\varepsilon^{N-1} k^{N-1}} \int_{x_{0}+\varepsilon \Pi_{\nu}^{(k)}\left(\frac{1}{2}\right)} u(x) d \mathcal{H}^{N-1}(x)-\varepsilon t_{\varepsilon}^{(k)} \frac{a}{2},  \tag{3.29}\\
& v_{\varepsilon}^{(k)}(x):=b_{\varepsilon}^{(k)}+t_{\varepsilon}^{(k)} a \otimes \nu\left(x-x_{0}\right),  \tag{3.30}\\
& A_{\varepsilon}^{(k)}:=\frac{m\left(u: Q_{\nu}^{(k)}\left(x_{0}, \varepsilon\right)\right)-m\left(v_{\varepsilon}^{(k)} ; Q_{\nu}^{(k)}\left(x_{0}, \varepsilon\right)\right)}{k^{N-1} \varepsilon^{N} t_{\varepsilon}^{(k)}} \tag{3.31}
\end{align*}
$$

where, for $t \in \mathbb{R}, \Pi_{\nu}^{(k)}(t):=\left\{y \in \mathbb{R}^{N}\left|y \cdot \nu=t,|y-(y \cdot \nu) \nu| \leq \frac{k}{2}\right\}\right.$.
Using Alberti's result on the blow-up of the Cantor part (see [A] and also [ADM], Theorem 2.3) and Lemma 5.1 in [L], we can also choose $N$ so that for all $x_{0} \in \Omega \backslash N$ there exists a sequence $\left(\varepsilon_{n}\right)$ tending to 0 and, for every $k$, a nondecreasing function $\Psi^{(k)}:\left(-\frac{1}{2}, \frac{1}{2}\right) \rightarrow \mathbb{R}$ such that the following conditions hold :

$$
\begin{align*}
& \Psi^{(k)}\left(\frac{1}{2}-0\right)-\Psi^{(k)}\left(-\frac{1}{2}+0\right)=1 \quad, \quad \int_{-\frac{1}{2}}^{\frac{1}{2}} \Psi^{(k)}(s) d s=0  \tag{3.32}\\
& u_{n}^{(k)}(y):=\frac{u\left(x_{0}+\varepsilon_{n} y\right)-\theta_{\varepsilon_{n}}^{(k)}}{\varepsilon_{n} t_{\varepsilon_{n}}^{(k)}} \rightarrow u_{0}^{(k)}(y):=\Psi^{(k)}(y \cdot \nu) a \operatorname{in} L^{1}\left(Q_{\nu}^{(k)} ; \mathbb{R}^{d}\right),  \tag{3.33}\\
& \lim _{n}\left|D u_{n}^{(k)}\right|\left(Q_{\nu}^{(k)}\right)=\left|D u_{0}^{(k)}\right|\left(Q_{\nu}^{(k)}\right)=k^{N-1}|a| . \tag{3.34}
\end{align*}
$$

We notice that the negligible set $N$ and the sequence $\left(\varepsilon_{n}\right)$ were chosen independently of $k$. Fix $x_{0} \in \Omega \backslash N$.

Owing to (3.26) and (3.31) we have that, for every $k \in \mathbb{N}$,

$$
\underset{\varepsilon \rightarrow 0}{\limsup } \frac{m\left(v_{\varepsilon}^{(k)} ; Q_{\nu}^{(k)}\left(x_{0}, \varepsilon\right)\right)}{k^{N-1} \varepsilon^{N} t_{\varepsilon}^{(k)}}=\frac{d \mathcal{F}(u ; \cdot)}{d|C(u)|}\left(x_{0}\right)-\liminf _{\varepsilon \rightarrow 0} A_{\varepsilon}^{(k)}
$$

which, together with (3.27) and (3.28), yields the result of Lemma 3.7 provided we show that

$$
\begin{align*}
& \text { (i) } \lim _{\varepsilon \rightarrow 0} b_{\varepsilon}^{(k)}=u\left(x_{0}\right) \\
& \text { (ii) } \lim _{k \rightarrow+\infty} \liminf _{\varepsilon \rightarrow 0}\left|A_{\varepsilon}^{(k)}\right|=0 \tag{3.35}
\end{align*}
$$

Step 1. We prove (3.35) (i). Since $x_{0} \notin S(u)$, we have that $\lim _{\varepsilon \rightarrow 0} \theta_{\varepsilon}^{(k)}=u\left(x_{0}\right)$. Then, in view of definitions (3.27), (3.28) and (3.29), it is enough to show that

$$
\begin{align*}
&\left|\frac{1}{\varepsilon^{N} k^{N-1}} \int_{Q_{\nu}^{(k)}\left(x_{0}, \varepsilon\right)} u(x) d x-\frac{1}{\varepsilon^{N-1} k^{N-1}} \int_{x_{0}+\varepsilon \Pi_{\nu}^{(k)}\left(\frac{1}{2}\right)} u(x) d \mathcal{H}^{N-1}(x)\right| \leq  \tag{3.36}\\
& \leq \frac{|D u|\left(Q_{\nu}^{(k)}\left(x_{0}, \varepsilon\right)\right)}{\varepsilon^{N-1} k^{N-1}}
\end{align*}
$$

With no loss of generality we prove (3.36) assuming that $u$ is smooth. This extends to a general $u \in B V\left(Q_{\nu}^{(k)}\left(x_{0}, \varepsilon\right) ; \mathbb{R}^{d}\right)$ by considering a sequence $\left(u_{n}\right)$ in $C^{\infty}\left(Q_{\nu}^{(k)}\left(x_{0}, \varepsilon\right) ; \mathbb{R}^{d}\right)$ such that $u_{n} \rightarrow u$ in $L^{1}\left(Q_{\nu}^{(k)}\left(x_{0}, \varepsilon\right) ; \mathbb{R}^{d}\right),\left|\nabla u_{n}\right|\left(Q_{\nu}^{(k)}\left(x_{0}, \varepsilon\right)\right) \rightarrow$ $|D u|\left(Q_{\nu}^{(k)}\left(x_{0}, \varepsilon\right)\right)$ and passing to the limit as $n \rightarrow+\infty$ in the corresponding inequality (3.36).

Setting, for each $t \in(-1 / 2,1 / 2)$,

$$
\alpha(t):=\int_{\Pi_{\nu}^{(k)}(t)} u\left(x_{0}+\varepsilon x\right) d \mathcal{H}^{N-1}(x)
$$

changing variables and using Fubini's Theorem we have that

$$
\begin{aligned}
& \left.\left|\frac{1}{\varepsilon^{N}} \int_{Q_{\nu}^{(k)}\left(x_{0}, \varepsilon\right)} u(x) d x-\frac{1}{\varepsilon^{N-1}} \int_{x_{0}+\varepsilon \Pi_{\nu}^{(k)}\left(\frac{1}{2}\right)} u(x) d \mathcal{H}^{N-1}(x)\right|=\left|\int_{-1 / 2}^{1 / 2}\right| \alpha(t)-\alpha(1 / 2)\right] d t \mid \\
& =\left|\int_{-1 / 2}^{1 / 2} \int_{t}^{1 / 2} \alpha^{\prime}(s) d s d t\right|=\left|\int_{-1 / 2}^{1 / 2} \int_{t}^{1 / 2} \int_{\Pi_{\nu}^{(k)}(s)} \nabla u\left(x_{0}+\varepsilon x\right) \varepsilon x d \mathcal{H}^{N-1}(x) d s d t\right| \\
& \leq \varepsilon \int_{-1 / 2}^{1 / 2} \int_{\Pi_{\nu}^{(k)}(t)}\left|\nabla u\left(x_{0}+\varepsilon x\right)\right||x| d \mathcal{H}^{N-1}(x) d t \leq O\left(k^{N-1}\right) \frac{|D u|\left(Q_{\nu}^{(k)}\left(x_{0}, \varepsilon\right)\right)}{\varepsilon^{N-1}} .
\end{aligned}
$$

Step 2. We prove (3.35) (ii). By Lemma 3.1, and using the change of variables $y=\frac{x-x_{0}}{\varepsilon_{n}}$, we have

$$
\begin{align*}
\left|A_{\varepsilon_{n}}^{(k)}\right| & \leq C \frac{\int_{\partial Q_{\nu}^{(k)}\left(x_{0}, \varepsilon_{n}\right)}\left|u(x)-v_{\varepsilon_{n}}^{(k)}(x)\right| d \mathcal{H}^{N-1}(x)}{k^{N-1} \varepsilon_{n}^{N} t_{\varepsilon_{n}}^{(k)}} \\
& \leq \frac{C}{k^{N-1}} \int_{\partial Q_{\nu}^{(k)}}\left|u_{n}^{(k)}(y)-a(y \cdot \nu)+c_{n}^{(k)}\right| d \mathcal{H}^{N-1}(y) \tag{3.37}
\end{align*}
$$

where $c_{n}^{(k)}:=\frac{\theta_{\varepsilon_{n}}^{(k)}-b_{\varepsilon_{n}}^{(k)}}{\varepsilon_{n} t_{\varepsilon_{n}}^{(k)}}=\frac{a}{2}-\frac{1}{k^{N-1}} \int_{\Pi_{\nu}^{(k)}\left(\frac{1}{2}\right)} u_{n}^{(k)} d \mathcal{H}^{N-1}$.
By (3.33), (3.34) and Lemma 2.3, we have the strong convergence of the trace of $u_{n}^{(k)}$ to the trace of $\Psi^{(k)}(y \cdot \nu) a$ on $\Pi_{\nu}^{(k)}\left(\frac{1}{2}\right)$ and so

$$
\begin{aligned}
\lim _{n \rightarrow+\infty} c_{n}^{(k)} & =\lim _{n \rightarrow+\infty}\left(\frac{a}{2}-\frac{1}{k^{N-1}} \int_{\Pi_{\nu}^{(k)}\left(\frac{1}{2}\right)} u_{n}^{(k)} d \mathcal{H}^{N-1}(y)\right) \\
& =\frac{a}{2}-\frac{1}{k^{N-1}} \int_{\Pi_{\nu}^{(k)}\left(\frac{1}{2}\right)} \Psi^{(k)}(y \cdot \nu) a d \mathcal{H}^{N-1}(y) \\
& =-a\left(\Psi^{(k)}\left(\frac{1}{2}\right)-\frac{1}{2}\right)
\end{aligned}
$$

Thus, from (3.37) we deduce

$$
\limsup _{n \rightarrow+\infty}\left|A_{\varepsilon_{n}}^{(k)}\right| \leq \frac{C|a|}{k^{N-1}} \int_{\partial Q_{\nu}^{(k)}}\left|\Psi^{(k)}(y \cdot \nu)-y \cdot \nu-\Psi^{(k)}\left(\frac{1}{2}\right)+\frac{1}{2}\right| d \mathcal{H}^{N-1}(y)
$$

and by (3.32) the function $\left|\Psi^{(k)}(y \cdot \nu)-y \cdot \nu-\Psi^{(k)}\left(\frac{1}{2}\right)+\frac{1}{2}\right|$ vanishes on the facets $\Pi_{\nu}^{(k)}\left( \pm \frac{1}{2}\right)$ and is bounded. We conclude that

$$
\limsup _{k \rightarrow+\infty} \liminf _{\varepsilon \rightarrow 0}\left|A_{\varepsilon}^{(k)}\right| \leq \lim _{k \rightarrow \infty} \limsup _{n \rightarrow+\infty}\left|A_{\varepsilon_{n}}^{(k)}\right| \leq \frac{C}{k^{N-1}}|a| k^{N-2}=0
$$

In order to identify the right hand side of (3.25), we assume now that the continuity assumption (2.4) holds, that is (see Section 2) there exists a modulus of continuity $\Phi(t)$ such that for all $(u, A, b, z) \in B V\left(\Omega ; \mathbb{R}^{d}\right) \times \mathcal{A}(\Omega) \times \mathbb{R}^{d} \times \mathbb{R}^{N}$, with $z+A \subset \Omega$,

$$
|\mathcal{F}(u(\cdot-z)+b ; z+A)-\mathcal{F}(u ; A)| \leq \Phi(|b|+|z|)\left(\mathcal{L}^{N}(A)+|D u|(A)\right)
$$

Remark 3.8. An immediate consequence of (2.4) and of the growth condition (2.3) is that the integrands $f\left(x_{0}, u_{0}, \xi\right)$ and $g\left(x_{0}, \lambda, \theta, \nu\right)$ defined by (3.13) and (3.14) are continuous with respect to $x_{0}$ and $u_{0}$. In fact, applying (2.4) with $A=Q_{\nu}\left(x_{0}, \varepsilon\right)$ and $u$ such that $u(x)=u_{0}+\xi\left(x-x_{0}\right)$ on $\partial Q_{\nu}\left(x_{0}, \varepsilon\right)$, we obtain

$$
\begin{aligned}
& \mid m\left(u_{0}+b+\xi\left(\cdot-z-x_{0}\right) ; Q_{\nu}\left(z+x_{0}, \varepsilon\right)\right)- m\left(u_{0}+\xi\left(\cdot-x_{0}\right) ; Q_{\nu}\left(x_{0}, \varepsilon\right)\right) \mid \\
& \leq \Phi(|b|+|z|)(1+|\xi|) \varepsilon^{N}
\end{aligned}
$$

Dividing by $\varepsilon^{N}$ and passing to the limit as $\varepsilon \rightarrow 0$, we are led to

$$
\begin{equation*}
\left|f\left(x_{0}+z, u_{0}+b, \xi\right)-f\left(x_{0}, u_{0}, \xi\right)\right| \leq \Phi(|b|+|z|)(1+|\xi|) \tag{3.38}
\end{equation*}
$$

Similarly, we obtain

$$
\left|g\left(x_{0}+z, \lambda+b, \theta+b, \nu\right)-g\left(x_{0}, \lambda, \theta, \nu\right)\right| \leq \Phi(|b|+|z|)|\theta-\lambda|
$$

On the other hand, from (2.4) and the coercivity assumption (2.3'), we can also infer that

$$
\begin{equation*}
|m(u(\cdot-z)+b ; z+A)-m(u ; A)| \leq \Phi(|b|+|z|)\left(\mathcal{L}^{N}(A)+C m(u ; A)\right) \tag{3.39}
\end{equation*}
$$

We notice that, since $\mathcal{F}(\cdot ; \Omega)$ is weakly lower semicontinuous on $W^{1.1}\left(A ; \mathbb{R}^{d}\right)$ and coincides with the functional $u \in W^{1,1}\left(A ; \mathbb{R}^{d}\right) \rightarrow \int_{A} f(x, u, \nabla u) d x$ (see Theorem 3.4), the integrand $f\left(x_{0}, u_{0}, \cdot\right)$ must be quasiconvex for every $\left(x_{0}, u_{0}\right) \in \Omega \times \mathbb{R}^{d}$ (see, for example, $[\mathrm{D}]$ ). Thus, defining the recession function $f^{\infty}$ by

$$
\begin{equation*}
f^{\infty}\left(x_{0}, u_{0}, \xi\right):=\limsup _{t \rightarrow+\infty} \frac{f\left(x_{0}, u_{0}, t \xi\right)}{t} \tag{3.40}
\end{equation*}
$$

the right hand side of (3.40) is actually a limit whenever $\xi$ is a rank one tensor.
Lemma 3.9. Let $(a, \nu) \in \mathbb{R}^{d} \times S^{N-1},\left(x_{0}, u_{0}\right) \in \Omega \times \mathbb{R}^{d}$ and let $\left(\varepsilon_{n}, t_{n}\right)$ be a sequence such that $\varepsilon_{n} \rightarrow 0, t_{n} \rightarrow+\infty$ and $\varepsilon_{n} t_{n} \rightarrow 0$. If (2.4) holds and if $f$ is defined by (3.13) then

$$
\liminf _{n \rightarrow+\infty} \frac{m\left(u_{0}+t_{n} a \otimes \nu\left(\cdot-x_{0}\right) ; x_{0}+\varepsilon_{n} Q_{\nu}^{(k)}\right)}{t_{n} \varepsilon_{n}^{N} k^{N-1}} \geq f\left(x_{0}, u_{0}, a \otimes \nu\right)-f\left(x_{0}, u_{0}, 0\right)
$$

We leave the proof of this lemma to the end of this section. Now we are able to present the full representation of $\mathcal{F}$ on $B V\left(\Omega ; \mathbb{R}^{d}\right)$.

Theorem 3.10. Under hypotheses (2.1), (2.2),(2.3') and (2.4), we have for every $u \in B V\left(\Omega ; \mathbb{R}^{d}\right)$

$$
\begin{aligned}
\mathcal{F}(u ; A)= & \int_{A} f(x, u, \nabla u) d x+\int_{S(u) \cap A} g\left(x, u^{+}, u^{-}, \nu_{u}\right) d \mathcal{H}^{N-1} \\
& +\int_{A} f^{\infty}\left(x, u, \frac{d C(u)}{d|C(u)|}\right) d|C(u)|
\end{aligned}
$$

where $f, g, f^{\infty}$ are defined by (3.13), (3.14) and (3.40), respectively.
Proof. By Theorem 3.4 it remains to prove that for $|C(u)|$ a.e. $x \in \Omega$

$$
\frac{d \mathcal{F}(u ; \cdot)}{d|C(u)|}(x)=f^{\infty}\left(x, u(x), \frac{d C(u)}{d|C(u)|}(x)\right)
$$

Let $x_{0}$ be a point of approximate continuity of $u$ where $\frac{d C(u)}{d|C(u)|}\left(x_{0}\right)=a_{u}\left(x_{0}\right) \otimes \nu_{u}\left(x_{0}\right)$ and set $u_{0}:=u\left(x_{0}\right)$. By Lemma 3.7 and taking into account (3.39), it is enough to show that for every fixed $k \in \mathbb{N}, a=a_{u}\left(x_{0}\right)$ and $\nu=\nu_{u}\left(x_{0}\right)$ one has

$$
\begin{equation*}
\lim _{n \rightarrow+\infty} \frac{m\left(u_{0}+t_{n} a \otimes \nu\left(\cdot-x_{0}\right) ; x_{0}+\varepsilon_{n} Q_{\nu}^{(k)}\right)}{t_{n} \varepsilon_{n}^{N} k^{N-1}}=f^{\infty}\left(x_{0}, u_{0}, a \otimes \nu\right) \tag{3.41}
\end{equation*}
$$

where, for simplicity of notation, we have deleted the superscript ( $k$ ) from $t_{n}^{(k)}$. One inequality is easy. Indeed, by Theorem 3.4 we can write

$$
\begin{aligned}
m\left(u_{0}+t_{n} a \otimes \nu\left(\cdot-x_{0}\right) ; x_{0}+\varepsilon_{n} Q_{\nu}^{(k)}\right) & \leq \mathcal{F}\left(u_{0}+t_{n} a \otimes \nu\left(\cdot-x_{0}\right) ; x_{0}+\varepsilon_{n} Q_{\nu}^{(k)}\right) \\
& \leq \int_{x_{0}+\varepsilon_{n} Q_{\nu}^{(k)}} f\left(x, u_{0}+t_{n} a \otimes \nu\left(x-x_{0}\right), t_{n} a \otimes \nu\right) d x
\end{aligned}
$$

so that, by (3.38),

$$
\begin{align*}
\limsup _{n \rightarrow+\infty} \frac{m\left(u_{0}+t_{n} a \otimes \nu\left(\cdot-x_{0}\right) ; x_{0}+\varepsilon_{n} Q_{\nu}^{(k)}\right)}{t_{n} \varepsilon_{n}^{N} k^{N-1}} & \leq \limsup _{n \rightarrow+\infty} \frac{f\left(x_{0} \cdot u_{0}, t_{n} a \otimes \nu\right)}{t_{n}} \\
& \leq f^{\infty}\left(x_{0}, u_{0}, a \otimes \nu\right) \tag{3.42}
\end{align*}
$$

To prove the opposite inequality, we apply Lemma 3.9 after replacing $\left(t_{n}, a\right)$ by $\left(\frac{t_{n}}{t}, t a\right)$ for any $t>0$ fixed. We get

$$
\liminf _{n \rightarrow \infty} \frac{m\left(u_{0}+t_{n} a \otimes \nu\left(x-x_{0}\right) ; x_{0}+\varepsilon_{n} Q_{\nu}^{(k)}\right)}{t_{n} \varepsilon_{n}^{N} k^{N-1}} \geq \frac{f\left(x_{0}, u_{0}, t a \otimes \nu\right)-f\left(x_{0}, u_{0}, 0\right)}{t}
$$

Letting $t$ tend to $+\infty$ and taking into account (3.42), we obtain (3.41).

Proof of Lemma 3.9. Set $\alpha_{n}:=m\left(u_{0}+t_{n} a \otimes \nu\left(\cdot-x_{0}\right) ; x_{0}+\varepsilon_{n} Q_{\nu}^{(k)}\right)$ and $Q_{\nu}^{(k)}\left(x_{0}, \varepsilon\right):=x_{0}+\varepsilon Q_{\nu}^{(k)}$. By the coercivity hypothesis (2.3'), we have $\alpha_{n} \geq$ $\frac{1}{C} t_{n}|a| \varepsilon_{n}^{N} k^{N-1}$, and by (2.3) and since $t_{n}$ tends to $+\infty$, we have $\limsup _{n \rightarrow+\infty} \frac{\alpha_{n}}{t_{n} \varepsilon_{n}^{N}}<$ $+\infty$. Choosing $C>0$ large enough, we may assume that

$$
\begin{equation*}
0<\alpha_{n} \leq C \varepsilon_{n}^{N} t_{n} \tag{3.43}
\end{equation*}
$$

Fix $\eta>1$. By the definition of the set function $m$, there exists a function $z_{n} \in B V\left(Q_{\nu}^{(k)}\left(x_{0}, \varepsilon_{n}\right) ; \mathbb{R}^{d}\right)$ such that

$$
\begin{equation*}
\mathcal{F}\left(z_{n} ; Q_{\nu}^{(k)}\left(x_{0}, \varepsilon_{n}\right)\right)<\eta \alpha_{n}, z_{n}=u_{0}+t_{n} a \otimes \nu\left(\cdot-x_{0}\right) \quad \text { on } \partial Q_{\nu}^{(k)}\left(x_{0}, \varepsilon_{n}\right) \tag{3.44}
\end{equation*}
$$

Taking into account the continuity assumption (2.4) and the coercivity (2.3'), we can choose $\rho_{0}$ small enough so that

$$
\begin{equation*}
|b|+|\tau|<2 \rho_{0} \Rightarrow \mathcal{F}\left(z_{n}(\cdot-\tau)+b ; Q_{\nu}^{(k)}\left(x_{0}+\tau, \varepsilon_{n}\right)\right)<\eta^{2} \alpha_{n}+\Phi\left(2 \rho_{0}\right) \varepsilon_{n}^{N} k^{N-1} \tag{3.45}
\end{equation*}
$$

Without loss of generality, we suppose that $x_{0}=0$ and $\nu=e_{N}$. Let us extend $z_{n}$ to $\left(-k \varepsilon_{n} / 2, k \varepsilon_{n} / 2\right)^{N-1} \times \mathbb{R}$ by setting

$$
z_{n}:=u_{0}+\frac{a}{2} \varepsilon_{n} t_{n} \quad \text { if } x_{N}>\frac{\varepsilon_{n}}{2}, \quad z_{n}:=u_{0}-\frac{a}{2} \varepsilon_{n} t_{n} \quad \text { if } x_{N}<-\frac{\varepsilon_{n}}{2}
$$

and define a function $w_{n}$ on the whole $\mathbb{R}^{N}$ by considering, for every $(i, j) \in$ $\mathbb{Z}^{N-1} \times \mathbb{Z}$, the hypercube

$$
Q_{n}^{i, j}:=\left(\left(i-\frac{1}{2}\right) k \varepsilon_{n},\left(i+\frac{1}{2}\right) k \varepsilon_{n}\right)^{N-1} \times\left(\left(j-\frac{1}{2}\right) \varepsilon_{n} t_{n},\left(j+\frac{1}{2}\right) \varepsilon_{n} t_{n}\right)
$$

and defining

$$
w_{n}\left(x^{\prime}, x_{N}\right):=z_{n}\left(x^{\prime}-i k \varepsilon_{n}, x_{N}-j \varepsilon_{n} t_{n}\right)+a j \varepsilon_{n} t_{n},\left(x^{\prime}, x_{N}\right) \in Q_{n}^{i, j}
$$

Also, we introduce a family of piecewise affine functions

$$
v_{n}\left(x^{\prime}, x_{N}\right):=\varphi_{n}\left(x_{N}-j \varepsilon_{n} t_{n}\right)+a j \varepsilon_{n} t_{n},\left(x^{\prime}, x_{N}\right) \in Q_{n}^{i, j}
$$

where

$$
\varphi_{n}(s):= \begin{cases}u_{0}+a t_{n} \frac{\varepsilon_{n}}{2} & \text { if } s>\frac{\varepsilon_{n}}{2} \\ u_{0}+a t_{n} s & \text { if }|s|<\frac{\varepsilon_{n}}{2} \\ u_{0}-a t_{n} \frac{\varepsilon_{n}}{2} & \text { if } s<-\frac{\varepsilon_{n}}{2}\end{cases}
$$

Fix $\rho>0$ such that $0<\rho<\rho_{0}$ and denote

$$
I_{n}^{\rho}:=\left\{(i, j) \in \mathbb{Z}^{N-1} \times \mathbb{Z} \mid Q_{n}^{i, j} \cap Q_{\rho} \neq \emptyset\right\}, \quad Q_{\rho}:=(-\rho / 2, \rho / 2)^{N}
$$

If $N_{n}$ denotes the cardinality of $I_{n}^{\rho}$, it is clear that

$$
\begin{equation*}
\lim _{n \rightarrow+\infty} N_{n} \varepsilon_{n}^{N} t_{n} k^{N-1}=\rho^{N} \tag{3.46}
\end{equation*}
$$

Since $w_{n}$ agrees with $z_{n}\left(\cdot-\tau_{n}\right)+a j t_{n} \varepsilon_{n}$ on $Q_{n}^{i, j}$, with $\tau_{n}:=\left(i k \varepsilon_{n}, j t_{n} \varepsilon_{n}\right)$, and it coincides with $v_{n}$ on $Q_{n}^{i, j} \cap\left\{\left|x_{N}-j \varepsilon_{n} t_{n}\right|>\varepsilon_{n} / 2\right\}$, we have, for all $n \geq n_{0}$,

$$
\mathcal{F}\left(w_{n} ; Q_{n}^{i, j}\right)<\eta^{2} \alpha_{n}+\Phi\left(2 \rho_{0}\right) \varepsilon_{n}^{N} k^{N-1}+\mathcal{F}\left(v_{n} ; Q_{n}^{i, j}\right) \quad \text { for all }(i, j) \in I_{n}^{\rho}, \quad \text { (3.47) }
$$

where we have used (3.45) and the fact that $Q_{\nu}^{(k)}\left(x_{0}+\tau_{n} ; \varepsilon_{n}\right)=Q_{n}^{i, j} \cap\left\{\left|x_{N}-j \varepsilon_{n} t_{n}\right|<\right.$ $\left.\frac{\varepsilon_{n}}{2}\right\}$. Now $v_{n}$ is continuous and piecewise affine on $Q_{n}^{i, j}$, thus by the integral representation of Theorem 3.4 we can write $\mathcal{F}\left(v_{n} ; Q_{n}^{i, j}\right)=\int_{Q_{n}^{i, j}} f\left(x, v_{n}, 0\right) d x$. Summing (3.47) with respect to $(i, j) \in I_{n}^{\rho}$ and using the additivity of $\mathcal{F}$, we get

$$
\mathcal{F}\left(w_{n}, Q_{\rho}\right) \leq N_{n}\left(\eta^{2} \alpha_{n}+\Phi\left(2 \rho_{0}\right) \varepsilon_{n}^{N} k^{N-1}\right)+\int_{Q_{\rho}} f\left(x, v_{n}, 0\right) d x
$$

Passing to the limit, as $n \rightarrow+\infty$ and then as $\eta \rightarrow 1$, in the previous inequality, using (3.46) and recalling that $t_{n} \rightarrow+\infty$, we obtain

$$
\begin{equation*}
\liminf _{n \rightarrow+\infty} \frac{\alpha_{n}}{\varepsilon_{n}^{N} t_{n} k^{N-1}} \geq \liminf _{n \rightarrow+\infty} \frac{\mathcal{F}\left(w_{n}, Q_{\rho}\right)}{\rho^{N}}-\limsup _{n \rightarrow \infty} \frac{1}{\rho^{N}} \int_{Q_{\rho}} f\left(x, v_{n}, 0\right) d x \tag{3.48}
\end{equation*}
$$

A simple computation shows that

$$
\begin{equation*}
\lim _{n \rightarrow+\infty}\left\|v_{n}-v_{0}\right\|_{L^{1}\left(Q_{p}: \mathbb{R}^{d}\right)}=0, \quad \text { where } \quad v_{0}\left(x^{\prime}, x_{N}\right):=u_{0}+a x_{N} \tag{3.49}
\end{equation*}
$$

Hence, by (3.38), we have

$$
\begin{equation*}
\lim _{n \rightarrow+\infty} \int_{Q_{\rho}} f\left(x, v_{n}, 0\right) d x=\int_{Q_{\rho}} f\left(x, v_{0}, 0\right) d x \tag{3.50}
\end{equation*}
$$

On the other hand, using Poincaré's inequality in each $Q_{n}^{i, j} \cap\left\{\left|x_{N}-j \varepsilon_{n} t_{n}\right|<\right.$ $\left.\varepsilon_{n} / 2\right\}$ (with Poincaré constant $C \varepsilon_{n}$ ), we obtain

$$
\begin{aligned}
\int_{Q_{\rho}}\left|w_{n}(x)-v_{n}(x)\right| d x & \leq \sum_{(i, j) \in I_{n}^{\rho}} \int_{Q_{n}^{\prime, 3} \cap\left\{\left|x_{N}-j \varepsilon_{n} t_{n}\right|<\varepsilon_{n} / 2\right\}}\left|w_{n}(x)-v_{n}(x)\right| d x \\
& \leq \sum_{(i, j) \in I_{n}^{\rho}} C \varepsilon_{n} \int_{Q_{n}^{2, j} \cap\left\{\left|x_{N}-j \varepsilon_{n} t_{n}\right|<\varepsilon_{n} / 2\right\}}\left|D w_{n}-D v_{n}\right| \\
& \leq \sum_{(i, j) \in I_{n}^{\rho}} C \varepsilon_{n}\left(\int_{Q_{\nu}^{(k)}\left(x_{0}, \varepsilon_{n}\right)}\left|D z_{n}\right|+|a| t_{n} k^{N-1} \varepsilon_{n}^{N}\right) \\
& \leq C^{\prime} \rho^{N} \varepsilon_{n} .
\end{aligned}
$$

where we have used (3.43), (3.44), (3.46) and the coercivity hypothesis (2.3'). We conclude that

$$
\lim _{n \rightarrow+\infty} \int_{Q_{\rho}}\left|w_{n}(x)-v_{n}(x)\right| \rightarrow 0
$$

which, together with (3.49), yields

$$
\lim _{n \rightarrow+\infty}\left\|w_{n}-v_{0}\right\|_{L^{2}\left(Q_{\rho}\right)}=0
$$

Finally, by (3.48), (3.50) and by the lower semicontinuity property of $\mathcal{F}\left(\cdot ; Q_{\rho}\right)$, we deduce that

$$
\begin{aligned}
\liminf _{n \rightarrow+\infty} \frac{\alpha_{n}}{\varepsilon_{n}^{N} t_{n} k^{N-1}} & \geq \frac{\mathcal{F}\left(v_{0}, Q_{\rho}\right)}{\rho^{N}}-\frac{1}{\rho^{N}} \int_{Q_{\rho}} f\left(x, v_{0}(x), 0\right) d x \\
& =\frac{1}{\rho^{N}} \int_{Q_{\rho}}\left[f\left(x, v_{0}(x), a \otimes \nu\right)-f\left(x, v_{0}(x), 0\right)\right] d x
\end{aligned}
$$

The conclusion follows by letting $\rho$ tend to 0 and using (3.38).

## 4. Applications.

We apply the characterization of the relaxed energy obtained in Section 3 to particular situations where we are able to obtain a more explicit formula for the relaxed energy densities.

### 4.1. Relaxed Energy for Discontinuous Integrands.

Here the functional $\mathcal{F}$ is the relaxed energy corresponding to an integrand $f_{0}$ satisfying the following hypotheses :
(H1)

$$
f_{0}: \Omega \times \mathbb{R}^{d} \times \mathbb{R}^{d \times N} \rightarrow[0,+\infty) \text { is a Borel integrand; }
$$

(H2) there exists $C>0$ such that

$$
\frac{1}{C}|\xi| \leq f_{0}(x, u . \xi) \leq C(1+|\xi|)
$$

for all $(x, u, \xi) \in \Omega \times \mathbb{R}^{d} \times \mathbb{R}^{d \times N}$;
(H3) for every $\varepsilon>0$ there exists $\delta>0$ such that

$$
|u-v|<\delta \Rightarrow\left|f_{0}(x, u, \xi)-f_{0}(x, v, \xi)\right| \leq C \varepsilon(1+|\xi|)
$$

for all $(x, u, v, \xi) \in \Omega \times\left(\mathbb{R}^{d}\right)^{2} \times \mathbb{R}^{d \times N}$;
(H4) there exist $C>0,0<m<1, L>0$ such that

$$
\left|f_{0}^{\infty}(x, u, \xi)-\frac{f_{0}(x, u, t \xi)}{t}\right| \leq \frac{C}{t^{m}}
$$

for all $\xi \in \mathbb{R}^{d \times N},\|\xi\|=1, t>L$, and for all $(x, u) \in \Omega \times \mathbb{R}^{d}$, where the recession function $f_{0}^{\infty}$ is defined by

$$
f_{0}^{\infty}(x, u, \xi):=\limsup _{t \rightarrow+\infty} \frac{f_{0}(x, u, t \xi)}{t}
$$

The functional $\mathcal{F}: B V\left(\Omega ; \mathbb{R}^{d}\right) \times \mathcal{A}(\Omega) \rightarrow[0,+\infty)$ is defined by

$$
\begin{align*}
\mathcal{F}(u ; A):=\inf \left\{\liminf _{n \rightarrow+\infty} \int_{A} f_{0}\left(x, u_{n}(x), \nabla u_{n}(x)\right) d x \mid\right. & u_{n}
\end{align*} \rightarrow u \text { in } L^{1}\left(\Omega ; \mathbb{R}^{d}\right),
$$

Lemma 4.1.1. Under hypothesis ( H 1 ) and (H2), the functional $\mathcal{F}$ defined by (4.1.1) satisfies conditions (2.1), (2.2) and (2.3').

We omit the proof of this lemma since it is quite similar to the one presented in Section 4.3 for the more general case of the $\Gamma$-limit of a sequence of functionals.

Thus we may apply the representation Theorem 3.4 and Lemma 3.7 to our case. In order to obtain a more explicit characterization of the energies, we need to identify $m(u ; A)$, as introduced in (3.1). Given $(u ; A) \in B V\left(\Omega ; \mathbb{R}^{d}\right) \times \mathcal{A}(\Omega)$ define

$$
m_{0}(u ; A):=\inf \left\{\int_{A} f_{0}(x, v(x), \nabla v(x)) d x\left|v \in W^{1,1}\left(\Omega ; \mathbb{R}^{d}\right), v\right|_{\partial A}=\left.u\right|_{\partial A}\right\}
$$

Lemma 4.1.2. Under hypotheses (H1) and (H2), for all $(u ; A) \in B V\left(\Omega ; \mathbb{R}^{d}\right) \times$ $\mathcal{A}(\Omega)$

$$
m_{0}(u ; A)=m(u ; A)
$$

Proof. The inequality $m_{0}(u ; A) \geq m(u ; A)$ is trivial since for every $v \in$ $W^{1,1}\left(\Omega ; \mathbb{R}^{d}\right)$ with $v=u$ on $\partial A$ we have $\int_{A} f_{0}(x, v(x), \nabla v(x)) d x \geq \mathcal{F}(v ; A) \geq$ $m(u ; A)$.

Conversely; given $\varepsilon>0$ let $v \in B V\left(\Omega ; \mathbb{R}^{d}\right)$ be such that $\left.v\right|_{\partial A}=\left.u\right|_{\partial A}$ and

$$
\begin{equation*}
m(u ; A) \geq \mathcal{F}(v ; A)-\varepsilon \tag{4.1.2}
\end{equation*}
$$

Let $\left(v_{n}\right)$ be a sequence in $W^{1,1}\left(\Omega ; \mathbb{R}^{d}\right)$ converging to $v$ in $L^{1}\left(\Omega ; \mathbb{R}^{d}\right)$ such that

$$
\begin{equation*}
\mathcal{F}(v ; A)=\lim _{n \rightarrow+\infty} \int_{A} f_{0}\left(x, v_{n}(x), \nabla v_{n}(x)\right) d x \tag{4.1.3}
\end{equation*}
$$

Using Lemma 2.6 and Remark 2.7, consider $w_{n} \in W^{1,1}\left(A ; \mathbb{R}^{d}\right)$ such that $w_{n}=$ $v=u$ on $\partial A,\left\|w_{n}-v\right\|_{L^{1}\left(A ; \mathbb{R}^{d}\right)} \rightarrow 0$ and

$$
\limsup _{n \rightarrow+\infty} \int_{A} f_{0}\left(x, w_{n}(x), \nabla w_{n}(x)\right) d x \leq \lim _{n \rightarrow+\infty} \int_{A} f_{0}\left(x, v_{n}(x), \nabla v_{n}(x)\right) d x
$$

From (4.1.2) and (4.1.3) we conclude that

$$
m(u ; A) \geq \limsup _{n \rightarrow+\infty} \int_{A} f_{0}\left(x, w_{n}(x), \nabla w_{n}(x)\right) d x-\varepsilon \geq m_{0}(u ; A)-\varepsilon
$$

Letting $\varepsilon$ go to zero the result follows.
We now prove the following representation theorem.

Theorem 4.1.3. Under hypotheses (H1), (H2), (H3) and (H4), the functional $\mathcal{F}$, defined by (4.1.1) and evaluated at $(u, A) \in B V\left(\Omega ; \mathbb{R}^{d}\right) \times \mathcal{A}(\Omega)$, is given by

$$
\begin{align*}
\mathcal{F}(u ; A)= & \int_{A} f(x, u, \nabla u) d x+\int_{S(u) \cap A} g\left(x, u^{+}, u^{-}, \nu_{u}\right) d \mathcal{H}^{N-1}  \tag{4.1.4}\\
& +\int_{A} h\left(x, u, a_{u}, \nu_{u}\right) d|C(u)|
\end{align*}
$$

where $\nu_{u}(x)$ agrees with the unit normal to $S(u)$ at $x$ for $\mathcal{H}^{N-1}$ a.e. $x \in S(u)$ and with the unit vector that, together with $a_{u}$, satisfies (3.24) for $C(u)$ a.e. $x \in \Omega \backslash S(u)$. The energy densities are defined as
$h\left(x_{0}, u_{0}, a, \nu\right):=\limsup _{k \rightarrow+\infty} \limsup _{\varepsilon \rightarrow 0}$

$$
\inf _{\substack{v \in \mathcal{W}^{\prime}, 1,1\left(Q_{\nu}^{(k)}: \mathbb{F}^{d}\right) \\ v(y)=a(\nu, y) \text { on } \theta Q_{\nu}^{(k)}}}\left\{\frac{1}{k^{N-1}} \int_{Q_{\nu}^{(k)}} f_{0}^{\infty}\left(x_{0}+\varepsilon y, u_{0}, \nabla v(y)\right) d y\right\},
$$

with

$$
u_{\lambda, \theta, \nu}(y):=\left\{\begin{array}{l}
\lambda \text { if } y \cdot \nu>0 \\
\theta \text { otherwise }
\end{array}\right.
$$

for all $\left(x_{0}, u_{0}\right) \in \Omega \times \mathbb{R}^{d},(\lambda, \theta) \in\left(\mathbb{R}^{d}\right)^{2}, a \in \mathbb{R}^{d}$ and $\nu \in S^{N-1}$.
Remark 4.1.4 In general $\mathcal{F}$ does not verify the continuity condition (2.4), and so we cannot apply Theorem 3.10 to identify the Cantor part. Instead, we use Lemma 3.7 together with hypotheses (H3) and (H4). Note, however, that if $f_{0}$ is continuous with respect to $(x, u)$ then $f$ will coincide with the quasiconvex envelope of $f_{0}, h$ will agree with $f^{\infty}$ and we will recover the representation theorem of [FM1] and [FM2] or [ADM], under coercivity hypotheses. We remark that it is not necessary to assume (H3) and (H4) to obtain the representation of $\mathcal{F}$ on $\operatorname{SBV}\left(\Omega ; \mathbb{R}^{d}\right)$ which will hold like in Theorem 3.4 with $f$ defined by

$$
\begin{equation*}
f\left(x_{0}, u_{0}, \xi\right):=\limsup _{\varepsilon \rightarrow 0} \inf _{\substack{v \in \mathcal{W}, 1,1\left(Q: F^{d}\right) \\ v(\nu)=\{v \text { onoQ }}}\left\{\int_{Q} f_{0}\left(x_{0}+\varepsilon y, u_{0}+\varepsilon v(y), \nabla v(y)\right) d y\right\} \tag{4.1.5'}
\end{equation*}
$$

in place of (4.1.5), and with $g$ defined by

$$
g\left(x_{0}, \lambda, \theta, \nu\right):=\limsup _{\varepsilon \rightarrow 0} \inf _{\substack{v \in W^{1,1}\left(Q_{\nu}: \boldsymbol{R}^{d}\right) \\ v=u_{\lambda, ~}, \nu \\ \text { on } \theta Q_{\nu}}}\left\{\int_{Q_{\nu}} \varepsilon f_{0}\left(x_{0}+\varepsilon y, v(y), \frac{1}{\varepsilon} \nabla v(y)\right) d y\right\},
$$

instead of (4.1.6).
Proof of Theorem 4.1.3. Using Lemma 4.1.2 and (3.13), the density $f$ is given by

Using the change of variables $x=x_{0}+\varepsilon y$, and considering as test functions $w(y):=\frac{v\left(x_{0}+\varepsilon y\right)-u_{0}}{\varepsilon}$, we get

Hypotheses (H2) and (H3), combined with Lemma 2.8, allow us to obtain (4.1.5). In fact. due to the coercivity hypothesis (H2), both infima in the right hand sides of (4.1.5) and (4.1.8) are attained on

$$
E_{R}=\left\{w \in W^{1.1}\left(Q ; \mathbb{R}^{d}\right) \cdot u=\xi y \text { on } \partial Q,\left\|\nabla u^{\prime}\right\|_{L^{1}\left(Q: \mathbb{R}^{d}\right)} \leq R\right\}
$$

for a convenient $R$, independent of $\varepsilon$. In view of this, using Lemma 2.8 for each $n \in \mathbb{N}$ we can find $M_{n}$. independent of $\varepsilon$, such that
and

On the other hand, for fixed $n$ and using (H3) we get that

By (4.1.8), (4.1.9), (4.1.10) and (4.1.11) we obtain (4.1.5) up to an error of order $\frac{2}{n}$. It suffices to let $n \rightarrow+\infty$.

Using (3.14) and Lemma 4.1.2, the density $g$ is given by

$$
g\left(x_{0}, \lambda, \theta, \nu\right)=\limsup _{\varepsilon \rightarrow 0} \frac{1}{\varepsilon^{N-1}} \inf _{\substack{v \in \in^{1,1}\left(Q_{\nu}\left(x_{0}, \varepsilon\right) ; \mathbb{R}^{d}\right) \\ v(x)=u_{\lambda, \theta}, \nu\left(x-x_{0}\right) \operatorname{Ron}^{2} Q_{\nu}\left(x_{0}, \varepsilon\right)}} \int_{Q_{\nu}\left(x_{0}, \varepsilon\right)} f_{0}(x, v(x), \nabla v(x)) d x .
$$

For $y \in Q_{\nu}$, define $\tilde{v}_{\varepsilon}(y):=v\left(x_{0}+\varepsilon y\right)$. Thus $\tilde{v}_{\varepsilon}(y)=u_{\lambda, \theta, \nu}(y)$ for $\mathcal{H}^{N-1}$ a.e. $y \in \partial Q_{\nu}$, and
$\frac{1}{\varepsilon^{N-1}} \int_{Q_{\nu}\left(x_{0}, \varepsilon\right)} f_{0}(x, v(x), \nabla v(x)) d x=\int_{Q_{\nu}} \varepsilon f_{0}\left(x_{0}+\varepsilon y, \tilde{v}_{\varepsilon}(y), \frac{1}{\varepsilon} \nabla \tilde{v}_{\varepsilon}(y)\right) d y$, consequently,

$$
\begin{equation*}
g\left(x_{0}, \lambda, \theta, \nu\right)=\limsup \inf _{\varepsilon \rightarrow 0} \inf _{\substack{v \in \mathcal{W}^{1,1,1}\left(Q_{\nu}, F^{d}\right) \\ v=u_{\lambda, \theta, \nu}}} \int_{Q_{\nu}} \varepsilon f_{0}\left(x_{0}+\varepsilon y, v(y), \frac{1}{\varepsilon} \nabla v(y)\right) d y \tag{4.1.12}
\end{equation*}
$$

Hypothesis (H4) yields

$$
\begin{align*}
& \int_{Q_{\nu}} \varepsilon f_{0}\left(x_{0}+\varepsilon y, v(y), \frac{1}{\varepsilon} \nabla v(y)\right) d y=\zeta_{\varepsilon}(v)+\int_{Q_{\nu}} f_{0}^{\infty}\left(x_{0}+\varepsilon y, v(y), \nabla v(y)\right) d y \\
& \left|\zeta_{\varepsilon}(v)\right| \leq C \varepsilon^{m}\|\nabla v\|_{L^{2}\left(Q_{\nu} ; \mathbb{R}^{d}\right)}^{1-m} \tag{4.1.13}
\end{align*}
$$

Since the function $f_{0}^{\infty}$ also satisfies hypotheses (H2) (with the same constant $C$ ), one sees easily that both infima in the right hand sides of (4.1.6) and (4.1.12) are attained on

$$
E_{R}=\left\{v \in W^{1,1}\left(Q_{\nu} ; \mathbb{R}^{d}\right),\left.v\right|_{\partial Q_{\nu}}=\left.u_{\lambda, \theta, \nu}\right|_{\partial Q_{\nu}},\|\nabla v\|_{L^{1}\left(Q_{\nu} ; \mathbb{R}^{d}\right)} \leq R\right\}
$$

for a convenient $R$, independent of $\varepsilon$. Thus, taking the infima in (4.1.13), one obtains that

$$
\begin{aligned}
&\left|\inf _{v \in E_{R}} \int_{Q_{\nu}} \varepsilon f_{0}\left(x_{0}+\varepsilon y, v, \frac{1}{\varepsilon} \nabla v\right) d y-\inf _{v \in E_{R}} \int_{Q_{\nu}} f_{0}^{\infty}\left(x_{0}+\varepsilon y, v, \nabla v\right) d y\right| \\
& \leq \sup _{v \in E_{R}}\left|\zeta_{\varepsilon}(v)\right| \\
& \leq C \varepsilon^{m} R^{1-m}
\end{aligned}
$$

Passing to the limit, as $\varepsilon$ goes to zero, (4.1.6) follows.
Finally, we show (4.1.7). In view of Lemma 3.7 and by Lemma 4.1.2, we have, for $|C(u)|$ almost all $x_{0} \in \Omega$ and for a suitable sequence ( $b_{\varepsilon}^{(k)}, t_{\varepsilon}^{(k)}$ ) converging to $\left(u_{0},+\infty\right)$,

$$
\begin{aligned}
& h\left(x_{0}, u_{0}, a, \nu\right)=\lim _{k \rightarrow+\infty} \limsup _{\varepsilon \rightarrow 0} \frac{m_{0}\left(b_{\varepsilon}^{(k)}+t_{\varepsilon}^{(k)}(a \otimes \nu)\left(\cdot-x_{0}\right) ; x_{0}+\varepsilon Q_{\nu}^{(k)}\right)}{t_{\varepsilon}^{(k)} \varepsilon^{N} k^{N-1}} \\
& =\lim _{k \rightarrow+\infty} \limsup _{\varepsilon \rightarrow 0} \frac{1}{k^{N-1}} \\
& \inf _{\substack{w \in \mathcal{N}^{1,1}\left(Q_{\nu}^{(k)} ; \boldsymbol{R}^{d}\right) \\
w(\nu)=a(\nu \cdot \nu) \text { on } \theta Q_{\nu}^{(k)}}} \int_{Q_{\nu}^{(k)} \frac{1}{t_{\varepsilon}^{(k)}} f_{0}\left(x_{0}+\varepsilon y, b_{\varepsilon}^{(k)}+\varepsilon t_{\varepsilon}^{(k)} w(y), t_{\varepsilon}^{(k)} \nabla w(y)\right) d y .} .
\end{aligned}
$$

Using as before hypotheses (H2), (H3) and Lemma 2.8, we are led to

$$
h\left(x_{0}, u_{0}, a, \nu\right)=\lim _{k \rightarrow+\infty} \limsup _{\varepsilon \rightarrow 0} \frac{1}{k^{N-1}}
$$

Then (4.1.7) follows from (H2) and (H4).

### 4.2 Relaxation of bulk and interfacial energies.

We consider the functional defined for each $A \in \mathcal{A}(\Omega)$ by

$$
F(u ; A):=\left\{\begin{array}{lr}
\int_{A} f_{0}(x, u, \nabla u) d x  \tag{4.2.1}\\
+\int_{S(u) \cap A} g_{0}\left(x, u^{+}, u^{-}, \nu_{u}\right) d \mathcal{H}^{N-1} & \text { if } u \in S B V\left(\Omega ; \mathbb{R}^{d}\right) \\
+\infty & \text { otherwise }
\end{array}\right.
$$

where the densities $f_{0}$ and $g_{0}$ are continuous integrands satisfying the following hypotheses:
(H1) $f_{0}: \Omega \times \mathbb{R}^{N} \times \mathbb{R}^{d \times N} \rightarrow[0,+\infty)$ is a continuous function, and

$$
\frac{1}{C}|\xi| \leq f_{0}(x, u, \xi) \leq C(1+|\xi|)
$$

for all $(x, u, \xi) \in \Omega \times \mathbb{R}^{d} \times \mathbb{R}^{d \times N}$ and for some $C>0$;
(H2) for every $\varepsilon>0$ there exists $\delta>0$ such that

$$
|x-y|+|u-v|<\delta \Rightarrow\left|f_{0}(x, u, \xi)-f(y, v, \xi)\right| \leq C \varepsilon(1+|\xi|)
$$

for all $(x, y, u, v, \xi) \in \Omega^{2} \times\left(\mathbb{R}^{d}\right)^{2} \times \mathbb{R}^{d \times N}$;
(H3) $g_{0}: \Omega \times\left(\mathbb{R}^{d}\right)^{2} \times S^{N-1} \rightarrow[0,+\infty)$ is a continuous function, and

$$
\frac{1}{C}|\lambda-\theta| \leq g_{0}(x, \lambda, \theta, \nu) \leq C(1+|\lambda-\theta|)
$$

for all $(x, \lambda, \theta, \nu) \in \Omega \times\left(\mathbb{R}^{d}\right)^{2} \times S^{N-1} ;$
(H4) for every $\varepsilon>0$ there exists $\delta>0$ such that

$$
|x-y|+|z|<\delta \Rightarrow\left|g_{0}(x, \lambda+z, \theta+z, \nu)-g_{0}(y, \lambda, \theta, \nu)\right| \leq C \varepsilon|\lambda-\theta|
$$

for all $(x, y, \lambda, \theta, z, \nu) \in \Omega^{2} \times\left(\mathbb{R}^{d}\right)^{3} \times S^{N-1}$.
Our aim is to identify the relaxation of $F$ defined for each open subset $A \in \mathcal{A}(\Omega)$ as

$$
\begin{equation*}
\mathcal{F}(u, A):=\inf \left\{\liminf _{n \rightarrow+\infty} F\left(u_{n} ; A\right) \mid u_{n} \rightarrow u \text { in } L^{1}\left(\Omega ; \mathbb{R}^{d}\right)\right\} \tag{4.2.2}
\end{equation*}
$$

Theorem 4.2.1. Under hypotheses (H1), (H2), (H3) and (H4), the functional $\mathcal{F}$, defined by (4.2.2), is given by

$$
\begin{aligned}
\mathcal{F}(u ; A)= & \int_{A} f(x, u, \nabla u) d x+\int_{S(u) \cap A} g\left(x, u^{+}, u^{-}, \nu_{u}\right) d \mathcal{H}^{N-1} \\
& +\int_{A} f^{\infty}\left(x, u, \frac{d C(u)}{d|C(u)|}\right) d|C(u)|
\end{aligned}
$$

where, for all $x_{0} \in \Omega$, for all $\left(u_{0}, \xi\right) \in \mathbb{R}^{d} \times \mathbb{R}^{d \times N}$ and for all $(\lambda, \theta, \nu) \in\left(\mathbb{R}^{d}\right)^{2} \times S^{N-1}$,

$$
\begin{align*}
& f\left(x_{0}, u_{0}, \xi\right):=\limsup _{\varepsilon \rightarrow 0} \inf _{\substack{\left.v \in S B v Q: \xi^{d}\right) \\
v \mid \theta Q \in v}}\left\{\int_{Q} f_{0}\left(x_{0}, u_{0}, \nabla v(y)\right) d y\right. \\
& \left.+\int_{Q \cap S(v)} \frac{g_{0}\left(x_{0}, u_{0}+\varepsilon v^{+}(y), u_{0}+\varepsilon v^{-}(y), \nu_{v}(y)\right)}{\varepsilon} d \mathcal{H}^{N-1}(y)\right\},(4  \tag{4.2.3}\\
& g\left(x_{0}, \lambda, \theta, \nu\right):=\limsup _{\varepsilon \rightarrow 0} \inf _{\substack{v \in S B v\left(Q_{\nu} ; \mathbb{R}^{d}\right) \\
v\left|O Q_{\nu}=u_{\lambda, \nu}\right| \theta Q_{\nu}}}\left\{\int_{Q_{\nu}} \varepsilon f_{0}\left(x_{0}, v(y), \frac{1}{\varepsilon} \nabla v(y)\right) d y\right. \\
& \left.+g_{0}\left(x_{0}, v^{+}(y), v^{-}(y), \nu_{v}(y)\right) d \mathcal{H}^{N-1}(y)\right\} \tag{4.2.4}
\end{align*}
$$

where

$$
u_{\lambda, \theta, \nu}(y):=\left\{\begin{array}{l}
\lambda \text { if } y \cdot \nu>0 \\
\theta \text { otherwise }
\end{array}\right.
$$

Remark 4.2.2 Let us define

$$
\begin{aligned}
& f_{0}^{\infty}\left(x_{0}, u_{0}, \xi\right):=\lim _{\varepsilon \rightarrow 0} \varepsilon f_{0}\left(x_{0}, u_{0}, \frac{1}{\varepsilon} \xi\right) \\
& \bar{g}_{0}\left(x_{0}, u_{0}, \lambda, \theta, \nu\right):=\lim _{\varepsilon \rightarrow 0} \frac{1}{\varepsilon} g_{0}\left(x_{0}, u_{0}+\varepsilon \lambda, u_{0}+\varepsilon \theta, \nu\right)
\end{aligned}
$$

Using hypothesis (H4), one can easily see that $\bar{g}_{0}$ satisfies the invariance property $\bar{g}_{0}\left(x_{0}, u_{0}, \lambda+z, \theta+z, \nu\right)=\bar{g}_{0}\left(x_{0}, u_{0}, \lambda, \theta, \nu\right)$ for every $z \in \mathbb{R}^{d}$, therefore it can be written as

$$
\bar{g}_{0}\left(x_{0}, u_{0}, \lambda, \theta, \nu\right)=: \widehat{g}_{0}\left(x_{0}, u_{0}, \lambda-\theta, \nu\right)
$$

for a suitable function $\widehat{g}_{0}: \Omega \times \mathbb{R}^{d} \times \mathbb{R}^{d} \times S^{N-1}$.
Let us assume, in addition, that the following estimates hold

$$
\begin{aligned}
& \left|f_{0}^{\infty}\left(x_{0}, u_{0}, \xi\right)-\varepsilon f_{0}\left(x_{0}, u_{0}, \frac{1}{\varepsilon} \xi\right)\right| \leq C \varepsilon^{m}|\xi|^{1-m} \\
& \left|\widehat{g}_{0}\left(x, u_{0}, \lambda-\theta, \nu\right)-\frac{1}{\varepsilon} g_{0}\left(x, u_{0}, \varepsilon \lambda, \varepsilon \theta, \nu\right)\right| \leq C \varepsilon^{\alpha}|\lambda-\theta|^{1+\alpha}
\end{aligned}
$$

for suitable $\alpha, m \in(0,1)$ and $\varepsilon<\varepsilon_{0}$, and for all $x_{0} \in \mathbb{R}^{N}, \xi \in \mathbb{R}^{d \times N}, u_{0}, \lambda, \theta \in$ $\mathbb{R}^{d}, \nu \in S^{N-1}$.

Then, as in Section 4.1, it is possible to verify that formulas (4.2.3) and (4.2.4) can be rewritten as

$$
\begin{align*}
& \left.+\int_{Q \cap S(v)} \widehat{g}_{0}\left(x_{0}, u_{0},[v](y), \nu_{v}(y)\right) d H^{N-1}(y)\right\}, \\
& g\left(x_{0}, \lambda, \theta, \nu\right)=\inf _{\substack{v \in S B v\left(Q_{i: F^{d}}\right) \\
v i \theta Q_{\nu}=u_{\lambda, \nu}: \theta Q_{\nu}}}\left\{\int_{Q_{\nu}} f_{0}^{\infty}\left(x_{0}, v(y), \nabla v(y)\right) d y\right. \\
& \left.+g_{0}\left(x_{0}, v^{+}(y), v^{-}(y), \nu_{v}(y)\right) d \mathcal{H}^{N-1}(y)\right\} .
\end{align*}
$$

As a particular case we recover the characterizations of bulk and jump densities obtained in $[\mathrm{BBBF}]$ where it is assumed that $f_{0}=f_{0}\left(x_{0}, \xi\right)$ and $g_{0}=g_{0}\left(x_{0}, \lambda-\right.$ $\theta, \nu)$.

Proof. As in the proof of Lemma 4.3.4 of Section 4.3 it can be shown that the functional $\mathcal{F}$ defined by (4.2.2) satisfies conditions (2.1),(2.2) and (2.3'). In addition, assumptions (H2) and (H4) yield condition (2.4). Therefore, we may use Theorem 3.10 to obtain the integral representation of $\mathcal{F}$ on all $B V\left(\Omega ; \mathbb{R}^{d}\right)$, and it remains to indentify the integrands $f$ and $g$ given by (3.13) and (3.14), respectively.

By Lemma 2.6 and Remark 2.7 1), we obtain that for every $(u, A) \in B V(\Omega) \times$ $\mathcal{A}(\Omega)$ the function $m(u ; A)$ defined in (3.1) agrees with

$$
m_{0}(u ; A):=\inf \left\{F(v ; A)|v|_{\partial A}=\left.u\right|_{\partial A}\right\}
$$

Replacing $m$ by $m_{0}$ in (3.13) we have

$$
\begin{aligned}
& f\left(x_{0}, a, \xi\right)=\limsup _{\varepsilon \rightarrow 0} \inf \left\{\frac{1}{\varepsilon^{N}} \int_{Q\left(x_{0}, \varepsilon\right)} f_{0}(x, w(x), \nabla w(x)) d x\right. \\
& \left.+\frac{1}{\varepsilon^{N}} \int_{Q\left(x_{0}, \varepsilon\right) \cap S(w)} g_{0}\left(x, w^{+}(x), w^{-}(x), \nu_{w}(x)\right) d \mathcal{H}^{N-1}(x) \right\rvert\, \\
& w \in\left.S B V\left(Q\left(x_{0}, \varepsilon\right) ; \mathbb{R}^{d}\right), v(x)=a+\xi\left(x-x_{0}\right) \text { on } \partial Q\left(x_{0}, \varepsilon\right)\right\}
\end{aligned}
$$

Using the change of variables $y=\frac{x-x_{0}}{\varepsilon}$, and setting $v(y):=\varepsilon w\left(\frac{x-x_{0}}{\varepsilon}\right)-a$, we are led to

$$
\begin{gather*}
f\left(x_{0}, a, \xi\right)=\limsup _{\varepsilon \rightarrow 0} \inf \left\{\int_{Q} f_{0}\left(x_{0}+\varepsilon y, a+\varepsilon v(y), \nabla v(y)\right) d y\right. \\
\left.+\frac{1}{\varepsilon} \int_{Q \cap S(v)} g_{0}\left(x_{0}+\varepsilon y, a+v^{+}(y), a+v^{-}(y), \nu_{v}(y)\right) d \mathcal{H}^{N-1}(y) \right\rvert\,  \tag{4.2.5}\\
\left.v \in \operatorname{SBV}\left(Q ; \mathbb{R}^{d}\right), v(y)=\xi y \text { on } \partial Q\right\}
\end{gather*}
$$

Similarly, replacing $m$ by $m_{0}$ in (3.14), changing variables and setting now $v(y):=w\left(\frac{x-x_{0}}{\varepsilon}\right)$, we get

$$
\begin{align*}
& g\left(x_{0}, \lambda, \theta, \nu\right)= \limsup _{\varepsilon \rightarrow 0} \inf \\
&\left\{\int_{Q_{\nu}} \varepsilon f_{0}\left(x_{0}+\varepsilon y, v(y), \frac{\nabla v(y)}{\varepsilon}\right) d y\right.  \tag{4.2.6}\\
&+\int_{Q_{\nu} \cap S(v)} g_{0}\left(x_{0}+\varepsilon y, v^{+}(y), v^{-}(y), \nu_{v}(y)\right) d \mathcal{H}^{N-1}(y) \mid \\
&\left.v \in S B V\left(Q_{\nu} ; \mathbb{R}^{d}\right), v(y)=u_{\lambda, \nu}(y) \text { on } \partial Q_{\nu}\right\} .
\end{align*}
$$

By the coercivity condition ( $2.3^{\prime}$ ), it turns out that sequences ( $v_{\varepsilon}$ ) approaching the minimum in the right hand sides of (4.2.5) and (4.2.6) are uniformly bounded in $B V\left(\Omega ; \mathbb{R}^{d}\right)$. Thus with the help of the continuity assumptions ( H 2$)$ and ( H 4$)$, we can replace $f_{0}\left(x_{0}+\varepsilon y, \cdot, \cdot\right)$ by $f\left(x_{0}, \cdot, \cdot\right)$ in (4.2.5), and $g_{0}\left(x_{0}+\varepsilon y, \cdot, \cdot, \cdot\right)$ by $g_{0}\left(x_{0}, \cdot, \cdot, \cdot\right)$ in (4.2.6). This concludes the proof of Theorem 4.4.

### 4.3 Homogenization.

In what follows $\delta$ will stand for a positive parameter, converging to zero. For each $A \in \mathcal{A}(\Omega)$ consider the functionals $F_{\delta}(\cdot ; A)$ defined in $B V\left(\Omega ; \mathbb{R}^{d}\right)$ by

$$
F_{\delta}(u ; A):=\left\{\begin{array}{l}
\int_{A} f_{0}\left(\frac{x}{\delta}, \nabla u(x)\right) d x  \tag{4.3.1}\\
\quad+\int_{S(u) \cap A} g_{0}\left(\frac{x}{\delta},[u](x), \nu_{u}(x)\right) d \mathcal{H}^{N-1}(x) \text { if } u \in S B V\left(\Omega ; \mathbb{R}^{d}\right) \\
+\infty
\end{array}\right.
$$

where the densities $f_{0}$ and $g_{0}$ satisfy the following hypotheses:
(H1) $f_{0}: \mathbb{R}^{N} \times \mathbb{R}^{d \times N} \rightarrow[0,+\infty)$ is a Borel function, $Q$-periodic in the first argument, and

$$
\frac{1}{C}|\xi| \leq f_{0}(x, \xi) \leq C(1+|\xi|)
$$

for all $\xi \in \mathbb{R}^{d \times N}$, for all $x \in \mathbb{R}^{N}$, and for some $C>0$;
(H2) there exist $m, L, 0<m<1, L>0$, such that

$$
\left|f_{0}^{\infty}(x, \xi)-\frac{f_{0}(x, t \xi)}{t}\right| \leq \frac{C}{t^{m}}
$$

for all $\xi \in \mathbb{R}^{d \times N},\|\xi\|=1, t>L$, and for all $x \in \mathbb{R}^{N}$, where the recession function $f_{0}^{\infty}$ is defined by

$$
f_{0}^{\infty}(x, \xi):=\limsup _{t \rightarrow+\infty} \frac{f_{0}(x, t \xi)}{t}
$$

(H3) $g_{0}: \mathbb{R}^{N} \times \mathbb{R}^{d} \times S^{N-1} \rightarrow[0,+\infty)$ is a Borel function, $Q$-periodic in the first argument, satisfying

$$
\frac{1}{C}|\lambda| \leq g_{0}(x, \lambda, \nu) \leq C|\lambda|
$$

for all $x \in \mathbb{R}^{N}, \lambda \in \mathbb{R}^{d}$ and $\nu \in S^{N-1}$;
(H4) there exist $\alpha, l, 0<\alpha<1, l>0$, such that

$$
\left|\bar{g}_{0}(x, \lambda, \nu)-\frac{g_{0}(x, t \lambda, \nu)}{t}\right| \leq C t^{\alpha}
$$

for all $x \in \mathbb{R}^{N}, \lambda \in \mathbb{R}^{d},\|\lambda\|=1, \nu \in S^{N-1}, t<l$, where $\bar{g}_{0}$ is defined by

$$
\bar{g}_{0}(x, \lambda, \nu):=\limsup _{t \rightarrow 0} \frac{g_{0}(x, t \lambda, \nu)}{t}
$$

We recall the following definitions (see [DM]) :
We say that a functional $F: B V\left(\Omega ; \mathbb{R}^{d}\right) \rightarrow[0,+\infty]$ is the $\Gamma$-lower limit (respectively $\Gamma$-upper limit) of a sequence of functionals $F_{n}: B V\left(\Omega ; \mathbb{R}^{d}\right) \rightarrow[0,+\infty]$ for the $L^{1}\left(\Omega ; \mathbb{R}^{d}\right)$ topology if
i) given $u \in B V\left(\Omega ; \mathbb{R}^{d}\right)$ and $\left(u_{n}\right)$ in $B V\left(\Omega ; \mathbb{R}^{d}\right), u_{n} \rightarrow u$ in $L^{1}\left(\Omega ; \mathbb{R}^{d}\right)$, then

$$
F(u) \leq \liminf _{n \rightarrow+\infty} F_{n}\left(u_{n}\right) \quad\left(\text { respectively } F(u) \leq \limsup _{n \rightarrow+\infty} F_{n}\left(u_{n}\right)\right)
$$

ii) for each $u \in B V\left(\Omega ; \mathbb{R}^{d}\right)$ there exists $\left(\bar{u}_{n}\right)$ in $B V\left(\Omega ; \mathbb{R}^{d}\right)$ such that $\bar{u}_{n} \rightarrow u$ in $L^{1}\left(\Omega ; \mathbb{R}^{d}\right)$ and

$$
F(u)=\liminf _{n \rightarrow+\infty} F_{n}\left(\bar{u}_{n}\right) \quad\left(\text { respectively } F(u)=\limsup _{n \rightarrow+\infty} F_{n}\left(u_{n}\right)\right)
$$

We write

$$
\left.F=\Gamma-\liminf _{n \rightarrow+\infty} F_{n} \quad \text { (respectively } F=\Gamma-\limsup _{n \rightarrow+\infty} F_{n}\right) .
$$

We say that $\left(F_{n}\right) \Gamma$-converges to $F$ if the $\Gamma$ - lower limit and $\Gamma$ - upper limit coincide, or, equivalently, if condition i) for the $\Gamma$ - lower limit and the following condition iii) are both satisfied,
iii) for each $u \in B V\left(\Omega ; \mathbb{R}^{d}\right)$ there exists $\left(\bar{u}_{n}\right)$ in $B V\left(\Omega ; \mathbb{R}^{d}\right)$ such that $\bar{u}_{n} \rightarrow u$ in $L^{1}\left(\Omega ; \mathbb{R}^{d}\right)$ and

$$
F(u)=\lim _{n \rightarrow+\infty} F_{n}\left(\bar{u}_{n}\right)
$$

We write

$$
F=\Gamma-\lim _{n \rightarrow+\infty} F_{n}
$$

Remark 4.3.1. Since $L^{1}\left(\Omega ; \mathbb{R}^{d}\right)$ is a separable metric space, we can deduce from Kuratowski's Compactness Theorem (see [DM]) that a sequence ( $F_{n}$ ) $\Gamma$-converges to $F$ if and only if $F=\Gamma-\liminf _{k \rightarrow+\infty} F_{n_{k}}$, for any sequence of indexes $n_{k} \rightarrow+\infty$.

Given $A \in \mathcal{A}(\Omega)$, we define

$$
\mathcal{F}^{-}(\cdot ; A)=\Gamma-\liminf _{\delta \rightarrow 0} F_{\delta}(\cdot ; A) \text { and } \mathcal{F}^{+}(\cdot ; A)=\Gamma-\operatorname{lim\operatorname {sup}} F_{\delta \rightarrow 0}(\cdot ; A)
$$

Theorem 4.3.2. Under hypotheses (H1) - (H4) we have $\mathcal{F}^{-}=\mathcal{F}^{+}=\mathcal{F}$ where, for each $u \in B V\left(\Omega ; \mathbb{R}^{N}\right)$ and $A \in \mathcal{A}(\Omega), \mathcal{F}$ is defined by

$$
\begin{equation*}
\mathcal{F}(u ; A):=\int_{A} f(\nabla u) d x+\int_{S(u) \cap A} g\left([u], \nu_{u}\right) d \mathcal{H}^{N-1}+\int_{A} f^{\infty}\left(\frac{d C(u)}{d|C(u)|}\right) d|C(u)| \tag{4.3.2}
\end{equation*}
$$

$$
\begin{align*}
& f(\xi):=\lim _{T \rightarrow+\infty} \frac{1}{T^{N}} \inf _{\substack{\left.u \in S V \backslash T Q: F^{d}\right) \\
u=\xi \in \operatorname{ron} \theta(T Q)}}\left\{\int_{T Q} f_{0}(x, \nabla u) d x+\int_{S(u) \cap T Q} \bar{g}_{0}\left(x,[u], \nu_{u}\right) d \mathcal{H}^{N-1}\right\}, \\
& g(\lambda, \nu):=\lim _{T \rightarrow+\infty} \frac{1}{T^{N-1}} \inf _{\substack{\begin{subarray}{c}{\in S B V\left(T Q_{\mathcal{L}}: \mathbb{R}^{d}\right) \\
u=u_{\lambda, \nu} \cap \cap\left(T Q_{\nu}\right)} }}\end{subarray}}\left\{\int_{T Q_{\nu}} f_{0}^{\infty}(x, \nabla u) d x\right.  \tag{4.3.3}\\
& \left.+\int_{S(u) \cap T Q_{\nu}} g_{0}\left(x,[u], \nu_{u}\right) d \mathcal{H}^{N-1}\right\}, \tag{4.3.4}
\end{align*}
$$

where $u_{\lambda, \nu}(y):= \begin{cases}\lambda & \text { if } y \cdot \nu>0 \\ 0 & \text { otherwise } .\end{cases}$
According to Remark 4.3.1, in order to prove Theorem 4.3.2 it is enough to show that for any given sequence $\delta_{n} \rightarrow 0$ the $\Gamma$-lower limit of $\left(F_{\delta_{n}}(\cdot ; A)\right)$ agrees, for every $A \in \mathcal{A}(\Omega)$, with the functional $\mathcal{F}(u ; \cdot)$ defined in Theorem 4.3.2. Having this in mind, and in order to simplify the notations, we will represent the sequence $\left(\delta_{n}\right)$ by the parameter $\delta$.

Lemma 4.3.3. The functional $\mathcal{F}^{-}$satisfies

$$
\mathcal{F}^{-}(u(\cdot-h) ; A+h)=\mathcal{F}^{-}(u ; A) \quad \text { and } \quad \mathcal{F}^{-}(u+a ; A)=\mathcal{F}^{-}(u ; A)
$$

for all $u \in B V\left(\Omega ; \mathbb{R}^{d}\right), A \in \mathcal{A}(\Omega), h \in \mathbb{R}^{N}$, and $a \in \mathbb{R}^{d}$.
For the proof of this lemma we refer to [BDV], Lemma 3.7.
Lemma 4.3.4. Under hypotheses (H1)-(H4), $\mathcal{F}^{-}$satisfies conditions (2.1), (2.2), (2.3') and (2.4).

Proof. Condition (2.4) is an immediate consequence of Lemma 4.3.3.
We prove (2.2). Since the $\Gamma$-lower limit of a sequence of the functionals is lower semicontinuous (c.f. [DM]), $\mathcal{F}^{-}(\cdot ; A)$ is $L^{1}\left(\Omega ; \mathbb{R}^{d}\right)$ lower semicontinuous. In view of the local character of $\mathcal{F}^{-}$, easily deduced from its definition, we conclude that $\mathcal{F}^{-}(\cdot ; A)$ is also $L^{1}\left(A ; \mathbb{R}^{d}\right)$ lower semicontinuous.

In order to prove (2.3'), and by (H1) and (H3), we consider the double inequality

$$
\frac{1}{C}|D u|(A) \leq F_{\delta}(u: A) \leq C\left(\mathcal{L}^{N}(A)+|D u|(A)\right)
$$

for all $(u, A) \in S B V\left(\Omega ; \mathbb{R}^{d}\right) \times \mathcal{A}(\Omega)$, and we pass to the $\Gamma$ - lower limit in each member.

Finally we prove (2.1). We claim that for every $u \in B V\left(\Omega ; \mathbb{R}^{d}\right)$ and for every $A, B, C$ in $\mathcal{A}(\Omega)$, the following implication holds :

$$
\begin{equation*}
C \subset \subset B \subset \subset A \Rightarrow \mathcal{F}^{-}(u ; A) \leq \mathcal{F}^{-}(u ; B)+\mathcal{F}^{-}(u ; A \backslash \bar{C}) \tag{4.3.5}
\end{equation*}
$$

In fact, let $\left(v_{\delta}\right)$ and $\left(w_{\delta}\right)$ be two sequences converging to $u$ in $L^{1}\left(\Omega ; \mathbb{R}^{d}\right)$ and such that

$$
\liminf _{\delta \rightarrow 0} F_{\delta}\left(v_{\delta} ; B\right)=\mathcal{F}^{-}(u ; B) \text { and } \liminf _{\delta \rightarrow 0} F_{\delta}\left(w_{\delta} ; A \backslash \bar{C}\right)=\mathcal{F}^{-}(u ; A \backslash \bar{C})
$$

By means of hypotheses (H1) and (H3) we can apply Lemma 2.6 and Remark 2.7 to the sequence ( $F_{\delta}$ ), and find two other sequences $\left(w_{\delta}^{\prime}\right)$ and $\left(v_{\delta}^{\prime}\right)$ in $\operatorname{SBV}\left(\Omega ; \mathbb{R}^{d}\right)$, both converging to $u$ in $L^{1}\left(\Omega ; \mathbb{R}^{d}\right), w_{\delta}^{\prime}=v_{\delta}^{\prime}=u$ on $\Sigma$ and

$$
\begin{aligned}
& \limsup _{\delta \rightarrow 0} F_{\delta}\left(w_{\delta}^{\prime} ; A \backslash \bar{B}_{\rho}\right) \leq \liminf _{\delta \rightarrow 0} F_{\delta}\left(w_{\delta} ; A \backslash \bar{B}_{\rho}\right), \\
& \underset{\delta \rightarrow 0}{\limsup F_{\delta}\left(v_{\delta}^{\prime} ; B_{\rho}\right) \leq \liminf _{\delta \rightarrow 0} F_{\delta}\left(v_{\delta} ; B_{\rho}\right),}
\end{aligned}
$$

where

$$
\Sigma:=\{x \in B \backslash \bar{C} \mid \operatorname{dist}(x, \partial B)=\rho\} \text { and } B_{\rho}:=\{x \in B \mid \operatorname{dist}(x, \partial B)>\rho\}
$$

for some $0<\rho<\operatorname{dist}(\partial B, C)$ and such that $\left|D_{s} u\right|(\Sigma)=0$. Defining $\overline{v_{\delta}}=w_{\delta}^{\prime}$ in $\Omega \backslash \bar{B}_{\rho}$ and $\overline{v_{\delta}}=v_{\delta}^{\prime}$ in $B_{\rho}$, we get $\overline{v_{\delta}} \rightarrow u$ in $L^{1}\left(\Omega ; \mathbb{R}^{d}\right)$. Since $B_{\rho} \subset B$ and $A \backslash \bar{B}_{\rho} \subset A \backslash \bar{C}$, we also obtain

$$
\begin{aligned}
\mathcal{F}^{-}(u ; A) & \leq \liminf _{\delta \rightarrow 0} F_{\delta}\left(\bar{v}_{\delta} ; A\right)=\underset{\delta \rightarrow 0}{\liminf }\left[F_{\delta}\left(v_{\delta}^{\prime} ; B_{\rho}\right)+F_{\delta}\left(w_{\delta}^{\prime} ; A \backslash \bar{B}_{\rho}\right)\right] \\
& \leq \liminf _{\delta \rightarrow 0} F_{\delta}\left(v_{\delta}^{\prime} ; B_{\rho}\right)+\underset{\delta \rightarrow 0}{\limsup } F_{\delta}\left(w_{\delta}^{\prime} ; A \backslash \bar{B}_{\rho}\right) \\
& \leq \liminf _{\delta \rightarrow 0} F_{\delta}\left(v_{\delta} ; B\right)+\liminf _{\delta \rightarrow 0} F_{\delta}\left(w_{\delta} ; A \backslash \bar{C}\right) \\
& =\mathcal{F}^{-}(u ; B)+\mathcal{F}^{-}(u ; A \backslash \bar{C}),
\end{aligned}
$$

which proves (4.3.5).
Now consider $\left(u_{\delta}\right)$ in $S B V\left(\Omega ; \mathbb{R}^{d}\right)$ such that

$$
\mathcal{F}^{-}(u ; \Omega)=\liminf _{\delta \rightarrow 0} F_{\delta}\left(u_{\delta} ; \Omega\right)
$$

Let $\mu$ be the Radon measure on the compact $\bar{\Omega}$ defined as the weak limit, up to a subsequence, of $\left(f_{0}\left(\dot{\bar{\delta}}, \nabla u_{\delta}\right) \mathcal{L}^{N}\left\lfloor\Omega+g_{0}\left(\dot{\bar{\delta}},\left[u_{\delta}\right], \nu_{u_{\delta}}\right) \mathcal{H}^{N-1}\left\lfloor\left(S\left(u_{\delta}\right) \cap \Omega\right)\right)\right.\right.$ as $\delta \rightarrow 0$. We have

$$
\begin{equation*}
\mathcal{F}^{-}(u ; \Omega)=\mu(\bar{\Omega}) \tag{4.3.6}
\end{equation*}
$$

and, by definition of $\mathcal{F}^{-}$, for all $A \in \mathcal{A}(\Omega)$,

$$
\begin{equation*}
\mathcal{F}^{-}(u ; A) \leq \liminf _{\delta \rightarrow 0} F_{\delta}\left(u_{\delta} ; A\right) \leq \mu(\bar{A}) . \tag{4.3.7}
\end{equation*}
$$

Let $B \in \mathcal{A}(\Omega)$ and $\varepsilon>0$ be fixed and consider $C \in \mathcal{A}(\Omega), C \subset \subset B$ such that $\mu(B \backslash C)<\varepsilon$. We get

$$
\mu(B) \leq \mu(C)+\varepsilon=\mu(\bar{\Omega})-\mu(\bar{\Omega} \backslash C)+\varepsilon .
$$

In view of (4.3.6), applying (4.3.7) with $A=\Omega \backslash \bar{C}$ and (4.3.5) with $A=\Omega$, it follows that

$$
\mu(B) \leq \mathcal{F}^{-}(u ; \Omega)-\mathcal{F}^{-}(u ; \Omega \backslash \bar{C})+\varepsilon \leq \mathcal{F}^{-}(u ; B)+\varepsilon .
$$

Letting $\varepsilon \rightarrow 0$, we conclude that

$$
\mu(B) \leq \mathcal{F}^{-}(u ; B) \leq \mu(\bar{B})
$$

for all $B \in \mathcal{A}(\Omega)$.
In order to prove that $\mathcal{F}^{-}(u ; A)=\mu(A)$ for all $A \in \mathcal{A}(\Omega)$, we fix again $\varepsilon>0$ and choose $C, B \in \mathcal{A}(\Omega)$ such that $C \subset \subset B \subset \subset A$ and $\mathcal{L}^{N}(A \backslash \bar{C})+|D u|(A \backslash \bar{C})<\varepsilon / C$. By (4.3.5), (4.3.7), and since $\mathcal{F}^{-}$satisfies (2.3),

$$
\mathcal{F}^{-}(u ; A) \leq \mathcal{F}^{-}(u ; A \backslash \bar{C})+\mathcal{F}^{-}(u ; B) \leq \varepsilon+\mu(\bar{B}) \leq \varepsilon+\mu(A)
$$

We complete the proof by letting $\varepsilon \rightarrow 0$.

Lemma 4.3.4 enables us to apply Theorems 3.4 and 3.9, which, together with Remark 3.5, yield
$\mathcal{F}^{-}(u ; A)=\int_{A} f^{-}(\nabla u) d x+\int_{S(u) \cap A} g^{-}\left([u], \nu_{u}\right) d \mathcal{H}^{N-1}+\int_{A}\left(f^{-}\right)^{\infty}\left(\frac{d C(u)}{d|C(u)|}\right) d|C(u)|$,
where $f^{-}: \mathbb{R}^{d \times N} \rightarrow[0,+\infty)$ and $g^{-}: \mathbb{R}^{d} \times S^{N-1} \rightarrow[0,+\infty)$ are given by (3.13) and (3.14). In order to prove that $f^{-}=f$ and $g^{-}=g$, as defined in (4.3.3) and (4.3.4), respectively, we introduce (c.f. (3.1))

$$
m(u: A):=\inf \left\{\mathcal{F}^{-}(v ; A)|v|_{\partial A}=\left.u\right|_{\partial A}, v \in B V\left(\Omega ; \mathbb{R}^{d}\right)\right\}
$$

and, for each $\delta>0$,

$$
m_{\delta}(u ; A):=\inf \left\{F_{\delta}(v ; A)|v|_{\partial A}=\left.u\right|_{\partial A}, v \in B V\left(\Omega ; \mathbb{R}^{d}\right)\right\}
$$

Lemma 4.3.5. For each $u \in B V\left(\Omega ; \mathbb{R}^{N}\right), x_{0} \in \Omega, \nu \in S^{N-1}$, we have

$$
\liminf _{\delta \rightarrow 0} m_{\delta}\left(u ; Q_{\nu}\left(x_{0}, t\right)\right)=m\left(u ; Q_{\nu}\left(x_{0}, t\right)\right)
$$

for almost all $t>0$ such that $Q_{\nu}\left(x_{0}, t\right) \subset \Omega$.
Proof. We divide the proof into two steps.
Step 1. We show that

$$
\begin{equation*}
\liminf _{\delta \rightarrow 0} m_{\delta}\left(u ; Q_{\nu}\left(x_{0}, t\right)\right) \leq m\left(u ; Q_{\nu}\left(x_{0}, t\right)\right) \tag{4.3.8}
\end{equation*}
$$

for all $t>0$ such that $Q_{\nu}\left(x_{0}, t\right) \subset \Omega$. Fix $A \in \mathcal{A}(\Omega), \varepsilon>0$, and let $v \in B V\left(\Omega ; \mathbb{R}^{d}\right)$ be such that

$$
m(u ; A)>\mathcal{F}^{-}(v ; A)-\varepsilon \text { and } v=u \text { on } \partial A
$$

Let $\left(v_{\delta}\right)$ be such that $\mathcal{F}^{-}(v ; A)=\liminf _{\delta \rightarrow 0} F_{\delta}\left(v_{\delta} ; A\right)$. Using Lemma 2.6 and Remark 2.72 ), we can find another sequence ( $\tilde{v}_{\delta}$ ) satisfying $\tilde{v}_{\delta}=u$ on $\partial A$ and such that

$$
\mathcal{F}^{-}(v ; A)=\liminf _{\delta \rightarrow 0} F_{\delta}\left(\tilde{v}_{\delta} ; A\right)
$$

Since $m_{\delta}(u ; A) \leq F_{\delta}\left(\tilde{v}_{\delta} ; A\right)$, we have

$$
\liminf _{\delta \rightarrow 0} m_{\delta}(u ; A)-\varepsilon \leq \mathcal{F}^{-}(v ; A)-\varepsilon<m(u ; A)
$$

Letting $\varepsilon$ go to zero we conclude (4.3.8).
Step 2. We prove that for almost all $t \in(0, T)$ such that $Q_{\nu}\left(x_{0}, T\right) \subset \Omega$,

$$
\begin{equation*}
\liminf _{\delta \rightarrow 0} m_{\delta}\left(u ; Q_{\nu}\left(x_{0}, t\right)\right) \geq m\left(u ; Q_{\nu}\left(x_{0}, t\right)\right) \tag{4.3.9}
\end{equation*}
$$

We claim that $t \mapsto m\left(u ; Q_{\nu}\left(x_{0}, t\right)\right)$ is a measurable function. Indeed,

$$
m\left(u ; Q_{\nu}\left(x_{0}, t^{\prime}\right)\right) \leq m\left(u ; Q_{\nu}\left(x_{0}, t\right)\right)+C(1+|D u|)\left(Q_{\nu}\left(x_{0}, t^{\prime}\right) \backslash Q_{\nu}\left(x_{0}, t\right)\right)
$$

for $t>t^{\prime}$, and so $\limsup _{t^{\prime} \backslash t} m\left(u ; Q_{\nu}\left(x_{0}, t^{\prime}\right)\right) \leq m\left(u ; Q_{\nu}\left(x_{0}, t\right)\right)$. This implies the measurability of $t \mapsto m\left(u ; Q_{\nu}\left(x_{0}, t\right)\right)$. Define

$$
E:=\left\{t_{0} \in(0, T) \mid t \mapsto m\left(u ; Q_{\nu}\left(x_{0}, t\right)\right)\right.
$$ is approximately continuous at $\left.t_{0}\right\}$.

Recalling that a measurable finite function is approximately continuous almost everywhere (see $[E G]$ ), we have that $\mathcal{L}^{1}((0, T) \backslash E)=0$. The conclusion of step 2 follows from the two following claims.
Claim 1. For each $t \in E$,

$$
\underset{t^{\prime} \backslash t}{\lim \sup } m\left(u ; Q_{\nu}\left(x_{0}, t^{\prime}\right)\right) \geq m\left(u ; Q_{\nu}\left(x_{0}, t\right)\right)
$$

This is a consequence of the approximate continuity of the function $m\left(u, Q_{\nu}\left(x_{0}, \cdot\right)\right)$ at $t$, which implies that, for every $\varepsilon>0$, the set

$$
\left\{t^{\prime} \in(t, T) \mid m\left(u ; Q_{\nu}\left(x_{0}, t^{\prime}\right)\right)<m\left(u ; Q_{\nu}\left(x_{0}, t\right)\right)-\varepsilon\right\}
$$

has Lebesgue density at $t$ equal to 0 , i.e.

$$
\lim _{\delta \rightarrow 0} \frac{1}{\delta} \mathcal{L}^{1}\left(\left\{t^{\prime} \in(t, t+\delta) \mid m\left(u ; Q_{\nu}\left(x_{0}, t^{\prime}\right)\right)<m\left(u ; Q_{\nu}\left(x_{0}, t\right)\right)-\varepsilon\right\}=0\right)
$$

Therefore, there exists a sequence $t_{n} \searrow t$ such that

$$
m\left(u ; Q_{\nu}\left(x_{0}, t_{n}\right)\right) \geq m\left(u ; Q_{\nu}\left(x_{0}, t\right)\right)-\varepsilon
$$

The claim 1 follows by letting first $n \rightarrow+\infty$ and then $\varepsilon \rightarrow 0$.
Claim 2. For every $t>0$,

$$
\underset{\delta \rightarrow 0}{\liminf } m_{\delta}\left(u ; Q_{\nu}\left(x_{0}, t\right)\right) \geq \underset{t^{\prime} \backslash t}{\limsup } m\left(u ; Q_{\nu}\left(x_{0}, t^{\prime}\right)\right)
$$

For each $\delta>0$ choose $u_{\delta}$ satisfying $u_{\delta}=u$ on $\partial Q_{\nu}\left(x_{0}, t\right)$ and

$$
m_{\delta}\left(u ; Q_{\nu}\left(x_{0}, t\right)\right)>F_{\delta}\left(u_{\delta} ; Q_{\nu}\left(x_{0}, t\right)\right)-\delta
$$

For $t^{\prime}>t$ consider the extension $\tilde{u}_{\delta}$ of $u_{\delta}, \tilde{u}_{\delta}:=u_{\delta}$ in $Q_{\nu}\left(x_{0}, t\right)$ and $\tilde{u}_{\delta}:=\tilde{u}$ in $Q_{\nu}\left(x_{0}, t^{\prime}\right) \backslash Q_{\nu}\left(x_{0}, t\right)$, where $\tilde{u} \in W^{1,1}\left(Q_{\nu}\left(x_{0}, t^{\prime}\right) \backslash Q_{\nu}\left(x_{0}, t\right) ; \mathbb{R}^{d}\right)$ and $\tilde{u}=u$ on $\partial Q_{\nu}\left(x_{0}, t^{\prime}\right) \cup \partial Q_{\nu}\left(x_{0}, t\right)$ (see Lemma 2.5). We have

$$
m_{\delta}\left(u ; Q_{\nu}\left(x_{0}, t\right)\right)>F_{\delta}\left(\tilde{u}_{\delta} ; Q_{\nu}\left(x_{0}, t^{\prime}\right)\right)-C \int_{Q_{\nu}\left(x_{0}, t^{\prime}\right) \backslash \overline{Q_{\nu}\left(x_{0}, t\right)}}(1+|\nabla \tilde{u}|) d x-\delta
$$

Using the coercivity conditions ( H 1 ) and ( H 3 ), together with Poincarés inequality, we infer that the sequence ( $\tilde{u}_{\delta}$ ) is bounded in $B V\left(\left(Q_{\nu}\left(x_{0}, t^{\prime}\right) ; \mathbb{R}^{d}\right)\right.$. Let $v$ be defined as the limit, up to a subsequence, of $\bar{u}_{\delta}$ in $L^{1}\left(Q_{\nu}\left(x_{0}, t^{\prime}\right) ; \mathbb{R}^{d}\right)$. Since by construction $v=\tilde{u}=u$ on $\partial Q_{\nu}\left(x_{0}, t^{\prime}\right)$, we obtain

$$
\begin{aligned}
\liminf _{\delta \rightarrow 0} m_{\delta}\left(u ; Q_{\nu}\left(x_{0}, t\right)\right) & \geq \mathcal{F}^{-}\left(v ; Q_{\nu}\left(x_{0}, t^{\prime}\right)\right)-C \int_{Q_{\nu}\left(x_{0}, t^{\prime}\right) \backslash \overline{Q_{\nu}\left(x_{0}, t\right)}}(1+|\nabla \tilde{u}|) d x \\
& \geq m\left(u ; Q_{\nu}\left(x_{0}, t^{\prime}\right)\right)-C \int_{Q_{\nu}\left(x_{0}, t^{\prime}\right) \backslash \overline{Q_{\nu}\left(x_{0}, t\right)}}(1+|\nabla \tilde{u}|) d x,
\end{aligned}
$$

The claim is proved by letting $t^{\prime} \searrow t$.

The following lemma is due to C. Licht and G. Michaille (see [LM], Theorem 3.1 and its proof). We refer to Section 2 for the definition of the class $\mathcal{A}$.

Lemma 4.3.6. Let $p \geq 1$ and let $S: \mathcal{A}\left(\mathbb{R}^{p}\right) \rightarrow \mathbb{R}^{+}$be such that
i) there exists $C>0$ such that $S(A) \leq C \mathcal{L}^{p}(A)$,
ii) $S(C) \leq S(A)+S(B)$, for all $A, B, C \in \mathcal{A}\left(\mathbb{R}^{p}\right), A \cap B=\emptyset, \bar{C}=\bar{A} \cup \bar{B}$,
iii) there exist $\mathcal{T} \subset \mathbb{R}^{p}$ and $M>0$ such that $\mathcal{T}+[0, M)^{p}=\mathbb{R}^{p}$ and

$$
S(A+\tau)=S(A) \text { for all } A \in \mathcal{A}\left(\mathbb{R}^{p}\right) \text { and } \tau \in \mathcal{T}
$$

Then, for any cube $A$ of the form $[a, b)^{p}$ there exists the limit of the sequence $\left(\frac{S(s A)}{\mathcal{L}^{p}(s A)}\right)$, as $s \rightarrow+\infty$, and

$$
\lim _{s \rightarrow+\infty} \frac{S(s A)}{\mathcal{L}^{p}(s A)}=\lim _{s \rightarrow+\infty} \frac{S\left([0, s)^{p}\right)}{s^{p}}
$$

Futhermore, if $\left\{S_{L}\right\}_{L}$ is a family of set functions satisfying i) - iii) for $C, \mathcal{T}$ and $M$ independent of $L$, the above limits are attained uniformly in $L$.

Lemma 4.3.7. The limits in the right hand side of (4.3.3) and (4.3.4) exist and

$$
\begin{align*}
& f^{-}(\xi)=f(\xi)  \tag{4.3.10}\\
& g^{-}(\lambda, \nu)=g(\lambda, \nu) \tag{4.3.11}
\end{align*}
$$

Proof.
Part 1. First we prove the existence of the limit in the right hand side of (4.3.3) and then we prove (4.3.10).

Let us define, for $\varepsilon, T>0$ and $(w, A) \in B V\left(\Omega ; \mathbb{R}^{d}\right) \times \mathcal{A}(\Omega)$,

$$
\begin{align*}
& F_{\varepsilon, T}(w ; A):=\int_{A} f_{0}(y T, \nabla w) d y+\frac{1}{\varepsilon} \int_{S(w) \cap A} g_{0}\left(y T, \varepsilon[w], \nu_{w}\right) d \mathcal{H}^{N-1}  \tag{4.3.12}\\
& F_{0, T}(w ; A):=\int_{A} f_{0}(y T, \nabla w) d y+\int_{S(w) \cap A} \bar{g}_{0}\left(y T,[w], \nu_{w}\right) d \mathcal{H}^{N-1} \tag{4.3.13}
\end{align*}
$$

and

$$
\begin{equation*}
m_{0, T}(\xi x ; A):=\inf \left\{F_{0, T}(w ; A) \mid w \in S B V\left(A ; \mathbb{R}^{d}\right), w=\xi x \text { on } \partial A\right\} \tag{4.3.14}
\end{equation*}
$$

For $A \in \mathcal{A}(\Omega)$ set

$$
S(A):=m_{0,1}(\xi x ; A)
$$

In view of the periodicity hypotheses (H1) and (H3), we may apply Lemma 4.3.6 to obtain

$$
\begin{equation*}
\lim _{T \rightarrow+\infty} \frac{S(T Q)}{T^{N}}=\lim _{T \rightarrow+\infty} \frac{1}{T^{N}} m_{0,1}(\xi x ; T Q)=f(\xi) \tag{4.3.15}
\end{equation*}
$$

which proves the existence of the limit in the right hand side of (4.3.3).
From (3.13) and in view of Remark 3.5, proving (4.3.10) is equivalent to asserting that

$$
\lim _{\varepsilon \rightarrow 0} \frac{m(\xi x ; \varepsilon Q)}{\varepsilon^{N}}=f(\xi)
$$

or, by virtue of Lemma 4.3.5, it suffices to prove that

$$
\lim _{\varepsilon \rightarrow 0} \liminf _{\delta \rightarrow 0} \frac{m_{\delta}(\xi x ; \varepsilon Q)}{\varepsilon^{N}}=f(\xi)
$$

for a suitable subsequence still denoted by $\varepsilon$.
Step 1. We show that

$$
\alpha:=\lim _{\varepsilon \rightarrow 0} \liminf _{\delta \rightarrow 0} \frac{m_{\delta}(\xi x ; \varepsilon Q)}{\varepsilon^{N}} \geq f(\xi) .
$$

We have

$$
\alpha=\lim _{\varepsilon \rightarrow 0} \lim _{n} \frac{m_{\delta_{n, \varepsilon}}(\xi x ; \varepsilon Q)}{\varepsilon^{N}}
$$

where, for each $\varepsilon>0, \delta_{n, \varepsilon} \xrightarrow[n \rightarrow+\infty]{ } 0$. We extract a diagonal subsequence $\delta(\varepsilon)$ such that $T_{\varepsilon}:=\varepsilon / \delta(\varepsilon) \longrightarrow+\infty$ and

$$
\alpha=\lim _{\varepsilon \rightarrow 0} \frac{m_{\delta(\varepsilon)}(\xi x ; \varepsilon Q)}{\varepsilon^{N}}=\lim _{\varepsilon \rightarrow 0} \frac{1}{\varepsilon^{N}} F_{\delta(\varepsilon)}\left(v_{\varepsilon} ; \varepsilon Q\right)
$$

for suitable $v_{\varepsilon} \in S B V\left(\Omega ; \mathbb{R}^{d}\right), v_{\varepsilon}=\xi x$ on $\partial(\varepsilon Q)$. Changing variables and writing $\bar{v}_{\varepsilon}(y):=\frac{1}{\varepsilon} v_{\varepsilon}(\varepsilon y)$, we have

$$
\begin{equation*}
\alpha=\lim _{\varepsilon \rightarrow 0} F_{\varepsilon, T_{c}}\left(\bar{v}_{\varepsilon} ; Q\right) \tag{4.3.16}
\end{equation*}
$$

Due to the coercivity hypotheses (H1) and (H3), together with (4.3.16), we have $\sup _{\varepsilon}\left\|\bar{v}_{\varepsilon}\right\|_{B V\left(Q: \mathbb{R}^{d}\right)}=\bar{C}<+\infty$. Since $\bar{v}_{\varepsilon}(y)=\xi y$ on $\partial Q$, using Lemma 2.8 with $u_{0}^{\varepsilon}=\xi y$, for fixed $\eta>0$ we may find $M_{\eta}=M\left(\eta, \bar{C}, C,\|\xi y\|_{L^{\infty}\left(Q: \mathbb{R}^{d}\right)}\right)$ and for each $\varepsilon$ we may find $w_{\varepsilon} \in B V\left(Q ; \mathbb{R}^{d}\right) \cap L^{\infty}\left(Q ; \mathbb{R}^{d}\right)$ such that

$$
\left\|w_{\varepsilon}\right\|_{L^{\infty}\left(Q: \mathbb{R}^{d}\right)} \leq M_{\eta}, \quad w_{\varepsilon}(y)=\xi y \text { on } \partial Q, \quad\left|D w_{\varepsilon}\right|(Q) \leq \bar{C}
$$

and

$$
\begin{equation*}
\lim _{\varepsilon \rightarrow 0} F_{\varepsilon, T_{\varepsilon}}\left(\bar{v}_{\varepsilon} ; Q\right) \geq \limsup _{\varepsilon \rightarrow 0} F_{\varepsilon, T_{\varepsilon}}\left(w_{\varepsilon} ; Q\right)-\eta \tag{4.3.17}
\end{equation*}
$$

By (H4) we have

$$
\begin{aligned}
& \limsup _{\varepsilon \rightarrow 0} \int_{S\left(w_{c}\right) \cap Q}\left|\frac{1}{\varepsilon} g_{0}\left(y T_{\varepsilon}, \varepsilon\left[w_{\varepsilon}\right], \nu_{w_{c}}\right)-\bar{g}_{0}\left(y T_{\varepsilon},\left[w_{\varepsilon}\right], \nu_{w_{c}}\right)\right| d \mathcal{H}^{N-1} \\
& \left.\leq \limsup _{\varepsilon \rightarrow 0} C \varepsilon^{\alpha} \int_{S\left(w_{c}\right) \cap Q}| | w_{\varepsilon}\right]\left.\right|^{\alpha+1} d \mathcal{H}^{N-1} \\
& \leq \limsup _{\varepsilon \rightarrow 0} C \bar{C} \varepsilon^{\alpha} M_{\eta}^{\alpha}=0
\end{aligned}
$$

Setting $\bar{w}_{\varepsilon}(y):=T_{\varepsilon} w_{\varepsilon}\left(y / T_{\varepsilon}\right)$, we deduce from (4.3.15), (4.3.16) and (4.3.17) that

$$
\begin{aligned}
& \alpha \geq \limsup _{\varepsilon \rightarrow 0} F_{0, T_{\varepsilon}}\left(w_{\varepsilon} ; Q\right)-\eta=\underset{\varepsilon \rightarrow 0}{\limsup } \frac{1}{T_{\varepsilon}^{N}} F_{0.1}\left(\bar{w}_{\varepsilon} ; T_{\varepsilon} Q\right)-\eta \\
& \geq \limsup _{\varepsilon \rightarrow 0} \frac{1}{T_{\varepsilon}^{N}} m_{0,1}\left(\xi x ; T_{\varepsilon} Q\right)-\eta=\lim _{T \rightarrow+\infty} \frac{1}{T^{N}} m_{0,1}(\xi x ; T Q)-\eta=f(\xi)-\eta .
\end{aligned}
$$

To conclude the proof of the first step it suffices to let $\eta$ tend to zero.
Step 2. We prove that

$$
\lim _{\varepsilon \rightarrow 0} \liminf _{\delta \rightarrow 0} \frac{m_{\delta}(\xi x ; \varepsilon Q)}{\varepsilon^{N}} \leq f(\xi)
$$

Let $u_{T} \in S B V\left(\Omega ; \mathbb{R}^{d}\right), u_{T}=\xi x$ on $\partial(T Q)$ be such that

$$
f(\xi)=\lim _{T \rightarrow+\infty} \frac{1}{T^{N}} F_{0,1}\left(u_{T} ; T Q\right)
$$

Setting $\bar{u}_{T}(y):=\frac{1}{T} u_{T}(y T)$, we obtain

$$
f(\xi)=\lim _{T \rightarrow+\infty} F_{0, T}\left(\bar{u}_{T} ; Q\right)
$$

and so, just as in Step 1, given $\eta>0$ we may replace $\bar{u}_{T}$ by $w_{T}$ such that $w_{T}=\xi y$ on $\partial Q$ and $\sup _{T}\left\|w_{T}\right\|_{L^{\infty}\left(Q: \mathbf{R}^{d}\right)}=\bar{C}<+\infty$. We have

$$
\begin{aligned}
f(\xi) & \geq \liminf _{T \rightarrow+\infty} F_{0, T}\left(w_{T} ; Q\right)-\eta=\limsup _{\varepsilon \rightarrow 0} \liminf _{T \rightarrow+\infty} F_{\varepsilon, T}\left(w_{T} ; Q\right)-\eta \\
& =\limsup _{\varepsilon \rightarrow 0} \liminf _{T \rightarrow+\infty} \frac{1}{\varepsilon^{N}} F_{\varepsilon / T}\left(w_{T, \varepsilon} ; \varepsilon Q\right)-\eta \\
& \geq \limsup _{\varepsilon \rightarrow 0} \liminf _{\delta \rightarrow 0} \frac{1}{\varepsilon^{N}} m_{\delta}(\xi x ; \varepsilon Q)-\eta
\end{aligned}
$$

where $w_{T, \varepsilon}(y):=\varepsilon w_{T}(y / \varepsilon)$.
Part 2. We prove the existence of the limit in the right hand side of (4.3.4) and we prove (4.3.11).

For $\varepsilon, T>0$ and $(u, A) \in B V\left(\Omega ; \mathbb{R}^{d}\right) \times \mathcal{A}(\Omega)$ define

$$
\begin{gather*}
G_{\varepsilon, T}(w ; A):=\varepsilon \int_{A} f_{0}\left(y T, \frac{1}{\varepsilon} \nabla w\right) d y+\int_{S(w) \cap A} g_{0}\left(y T,[w], \nu_{w}\right) d \mathcal{H}^{N-1},  \tag{4.3.18}\\
G_{0, T}(w ; A):=\int_{A} f_{0}^{\infty}(y T, \nabla w) d y+\int_{S(w) \cap A} g_{0}\left(y T,[w], \nu_{w}\right) d \mathcal{H}^{N-1} \tag{4.3.19}
\end{gather*}
$$

and

$$
\begin{equation*}
m_{0, T}\left(u_{\lambda, \nu} ; A\right):=\inf \left\{G_{0, T}(w ; A) \mid w \in S B V\left(A ; \mathbb{R}^{d}\right), w=u_{\lambda, \nu} \text { on } \partial A\right\} \tag{4.3.20}
\end{equation*}
$$

From (3.14) and in view of Remark 3.5, to prove (4.3.11) is equivalent to assert that

$$
\lim _{\varepsilon \rightarrow 0} \frac{m\left(u_{\lambda, \nu} ; \varepsilon Q_{\nu}\right)}{\varepsilon^{N-1}}=g(\lambda, \nu)
$$

Then, by virtue of Lemma 4.3.5, it suffices to show that

$$
\begin{equation*}
\lim _{\varepsilon \rightarrow 0} \liminf _{\delta \rightarrow 0} \frac{m_{\delta}\left(u_{\lambda, \nu} ; \varepsilon Q_{\nu}\right)}{\varepsilon^{N-1}}=g(\lambda, \nu) \tag{4.3.21}
\end{equation*}
$$

for a suitable subsequence still denoted by $\varepsilon$. Provided we establish the existence of

$$
\begin{equation*}
\lim _{T \rightarrow+\infty} \frac{1}{T^{N-1}} m_{0,1}\left(u_{\lambda, \nu} ; T Q_{\nu}\right) \tag{4.3.22}
\end{equation*}
$$

the proof of (4.3.21) is quite similar to the one presented in Steps 1 and 2 of Part 1 . Indeed, it is enough to replace the functional $F_{\varepsilon, T}$ by $G_{\varepsilon, T}, F_{0, T}$ by $G_{0, T}$, and to use hypothesis (H2) instead of (H4).

We prove the existence of the limit (4.3.22) in three steps.
Step 1. We recall that, for $\nu \in S^{N-1}, R_{\nu}$ denotes a rotation satisfying $R_{\nu}\left(e_{N}\right)=\nu$ and $\nu \mapsto R_{\nu}\left(e_{i}\right)$ is continuous in $S^{N-1} \backslash\left\{e_{N}\right\}$, for all $i=1, \cdots, N-1$ (see Section 2). As in [BDV], define $S^{*}$ to be the set of all $\nu \in S^{N-1}$ such that $R_{\nu}\left(e_{i}\right)=\gamma_{i} z_{i}$, for some $\gamma_{i} \in \mathbb{R} \backslash\{0\}, z_{i} \in \mathbb{Z}^{N}, i=1, \cdots, N-1$. The set $S^{*}$ is dense in $S^{N-1}$. Let

$$
Q_{\nu}^{T, L}:=R_{\nu}\left(\left\{x \in \mathbb{R}^{N}| | x_{N} \mid<L / 2 \text { and }\left|x_{i}\right|<T / 2, \text { for } i=1, \cdots, N-1\right\}\right)
$$

Fix $\nu \in S^{*}, L>0$ and define

$$
\mathcal{T}(\nu):=\left\{\left.\sum_{i=1}^{N-1} \frac{\lambda_{i}}{\gamma_{i}} e_{i} \right\rvert\, \lambda_{i} \in \mathbb{Z}, R_{\nu}\left(e_{i}\right)=\gamma_{i} z_{i}, \gamma_{i} \in \mathbb{R} \backslash\{0\}, z_{i} \in \mathbb{Z}^{N}\right\}
$$

For each open subset $A \subset \mathbb{R}^{N-1}$ with Lipschitz boundary, set

$$
S_{L}(A, \nu):=m_{0.1}\left(u_{\lambda, \nu} ; R_{\nu}\left(A \times I_{L}\right)\right)
$$

where $I_{L}=(-L / 2, L / 2)$. In view of the periodicity hypotheses (H1) and (H3) we have that, for $C$ independent of $L$,

$$
\begin{equation*}
S_{L}(A+\tau, \nu)=S_{L}(A, \nu) \text { and } S_{L}(A, \nu) \leq C \mathcal{L}^{N-1}(A) \tag{4.3.23}
\end{equation*}
$$

for all $A \in \mathcal{A}(\Omega), \tau \in \mathcal{T}(\nu)$, and also $\mathcal{T}(\nu)+[0, M)^{N-1}=\mathbb{R}^{N-1}$, where $M:=\max _{1 \leq i \leq N-1} \gamma_{i}$. Applying Lemma 4.3.6, with $p=N-1$, we conclude that

$$
\begin{equation*}
\lim _{T \rightarrow+\infty} \frac{1}{T^{N-1}} m_{0,1}\left(u_{\lambda, \nu} ; Q_{\nu}^{T, L}\right) \tag{4.3.24}
\end{equation*}
$$

exists and is finite.
Step 2. We prove that, for all $\nu \in S^{*}$,

$$
\begin{equation*}
\lim _{T \rightarrow+\infty} \frac{1}{T^{N-1}} m_{0,1}\left(u_{\lambda, \nu} ; T Q_{\nu}\right)=g(\lambda, \nu) \tag{4.3.25}
\end{equation*}
$$

In fact,

$$
\begin{align*}
\liminf _{T \rightarrow+\infty} \frac{1}{T^{N-1}} m_{0,1}\left(u_{\lambda, \nu} ; T Q_{\nu}\right) & \geq \liminf _{T \rightarrow+\infty} \inf _{L>0} \frac{1}{T^{N-1}} m_{0,1}\left(u_{\lambda, \nu} ; Q_{\nu}^{T, L}\right)  \tag{4.3.26}\\
& =\inf _{L>0} \lim _{T \rightarrow+\infty} \frac{1}{T^{N-1}} m_{0,1}\left(u_{\lambda, \nu} ; Q_{\nu}^{T, L}\right)
\end{align*}
$$

having in mind that, since the limit in (4.3.24) is uniform in $L$, we can interchange the infimum in $L$ with the limit as $T$ goes to $+\infty$.

Conversely, fix $L$ and let $T>L$. Using again, for each test function in $Q_{\nu}^{T, L}$, the extension by $u_{\lambda, \nu}$ to the whole $T Q_{\nu}$, we obtain

$$
\frac{1}{T^{N-1}} m_{0,1}\left(u_{\lambda, \nu} ; Q_{\nu}^{T, L}\right) \geq \frac{1}{T^{N-1}} m_{0,1}\left(u_{\lambda, \nu} ; T Q_{\nu}\right)
$$

and, consequently,

$$
\begin{equation*}
\inf _{L>0} \lim _{T \rightarrow+\infty} \frac{1}{T^{N-1}} m_{0,1}\left(u_{\lambda, \nu} ; Q_{\nu}^{T, L}\right) \geq \limsup _{T \rightarrow+\infty} \frac{1}{T^{N-1}} m_{0,1}\left(u_{\lambda, \nu} ; T Q_{\nu}\right) \tag{4.3.27}
\end{equation*}
$$

From (4.3.26) and (4.3.27) we conclude the proof of Step 2.
Step 3. We extend the proof of existence of the limit (4.3.22) to all $\nu \in S^{N-1}$. In view of the continuity of $\nu \mapsto R_{\nu}$, for each $\nu \in S^{N-1} \backslash\left\{e_{N}\right\}$ and $\varepsilon>0$ we may find $\nu_{\varepsilon} \in S^{*}$ and $\eta$ satisfying $1<\eta<\varepsilon+1$, such that

$$
\begin{gather*}
(1 / \eta) Q_{\nu_{\varepsilon}} \subset Q_{\nu} \subset \eta Q_{\nu_{\varepsilon}} \\
\mathcal{H}^{N-1}\left(\partial\left(\frac{1}{\eta} Q_{\nu_{\varepsilon}}\right) \cap\left\{x \in \mathbb{R}^{N} \mid x \cdot \nu_{\varepsilon}<0\right\} \cap\left\{x \in \mathbb{R}^{N} \mid x \cdot \nu>0\right\}\right)+ \\
\mathcal{H}^{N-1}\left(\partial\left(\frac{1}{\eta} Q_{\nu_{\epsilon}}\right) \cap\left\{x \in \mathbb{R}^{N} \mid x \cdot \nu_{\varepsilon}>0\right\} \cap\left\{x \in \mathbb{R}^{N} \mid x \cdot \nu<0\right\}\right)+  \tag{4.3.28}\\
\mathcal{H}^{N-1}\left(\left[Q_{\nu} \backslash\left(\frac{1}{\eta} Q_{\nu_{\varepsilon}}\right)\right] \cap\left\{x \in \mathbb{R}^{N} \mid x \cdot \nu=0\right\}\right)<\varepsilon
\end{gather*}
$$

and analogous estimates hold with $\eta Q_{\nu_{\epsilon}}$ in place of $Q_{\nu}$ and $Q_{\nu}$ in place of $\frac{1}{\eta} Q_{\nu_{\varepsilon}}$.
Given $T>0$, extending each test function defined in $(T / \eta) Q_{\nu_{\epsilon}}$ to $T Q_{\nu}$ by $u_{\lambda, \nu}$, and taking into account estimates (4.3.28) and hypothesis (H3), it follows that

$$
\frac{1}{T^{N-1}} m_{0,1}\left(u_{\lambda, \nu} ; T Q_{\nu}\right) \leq \frac{1}{(T / \eta)^{N-1}} m_{0,1}\left(u_{\lambda, \nu_{c}} ;(T / \eta) Q_{\nu_{c}}\right)+C|\lambda| \varepsilon
$$

Therefore, using Step 2 to justify the existence of the limit as $T$ tends to $+\infty$ in the right hand side of the previous inequality, we get

$$
\begin{align*}
\limsup _{T \rightarrow+\infty} \frac{1}{T^{N-1}} m_{0,1}\left(u_{\lambda, \nu} ; T Q_{\nu}\right) & \leq \lim _{T \rightarrow+\infty} \frac{1}{(T / \eta)^{N-1}} m_{0,1}\left(u_{\lambda, \nu_{c}} ;(T / \eta) Q_{\nu_{c}}\right)+O(\varepsilon) \\
& =\lim _{T \rightarrow+\infty} \frac{1}{T^{N-1}} m_{0,1}\left(u_{\lambda, \nu_{c}} ; T Q_{\nu_{c}}\right)+O(\varepsilon) \tag{4.3.29}
\end{align*}
$$

Similar reasoning concerning the inclusion $Q_{\nu} \subset \eta Q_{\nu_{c}}$ leads to

$$
\begin{align*}
\liminf _{T \rightarrow+\infty} \frac{1}{T^{N-1}} m_{0,1}\left(u_{\lambda, \nu} ; T Q_{\nu}\right) & \geq \lim _{T \rightarrow+\infty} \frac{1}{(\eta T)^{N-1}} m_{0,1}\left(u_{\lambda, \nu_{c}} ; \eta T Q_{\nu_{\epsilon}}\right)-O(\varepsilon) \\
& =\lim _{T \rightarrow+\infty} \frac{1}{T^{N-1}} m_{0,1}\left(u_{\lambda, \nu_{c}} ; T Q_{\nu_{c}}\right)-O(\varepsilon) \tag{4.3.30}
\end{align*}
$$

Letting $\varepsilon$ go to zero in (4.3.29) and (4.3.30), we conclude the proof of Step 3.
Acknowledgments. The research of G. Bouchitté was partially supported by JNICT-MENESR $97 / 166$. The research of I. Fonseca was partially supported by the Army Research Office and the National Science Foundation through the Center for Nonlinear Analysis, and by the National Science Foundation under Grants No. DMS-9201215 and DMS-9500531. The research of L. Mascarenhas was partially supported by JNICT-PRAXIS XXI, FEDER-PRAXIS/2/2.1/MAT/125/94, PRAXIS-FEDER/3/3.1/CTM/10/94, H.C.M.ERBCHRXCT940536, and JNICT-MENESR 97/166.

The authors acknowlege the hospitality of the Universities of Toulon (ANLA), Carnegie Mellon (CNA) and Lisbon (CMAF), where the present work was undertaken.

## References.

[A] Alberti, G. Rank-one property for derivatives of functions with bounded variation. Proc. Royal Soc. Edin. A-123 (1993), 239-274.
[Am1] Ambrosio L. A compactness theorem for a special class of functions of bounded variation. Boll.Un.Mat.Ital. 3B 7 (1989), 857-881.
[Am2] Ambrosio L. On the lower semicontinuity of quasi-convex integrals in SBV. Nonlinear Anal. 23 (1994), 405-425.
[ADG] Ambrosio, L. and E. De Giorgi. Un nuovo tipo di funzionale del calcolo delle variazioni. Atti. Accad. Naz. Lincei Rend. Cl. Sci. Fis. Mat. Natur. 82 (1988), 199-210.
[ADM] Ambrosio, L. and G. Dal Maso. On the relaxation in $B V\left(\Omega ; \mathbb{R}^{m}\right)$ of quasiconvex integrals, J. Funct. Anal. 109 (1992), 76-97.
[BBBF] Barroso, A. C., G. Bouchitté, G. Buttazzo and I. Fonseca. Relaxation in $B V\left(\Omega, \mathbb{R}^{p}\right)$ of energies involving bulk and surface energy contributions. Arch. Rat. Mech. Anal. 135 (1996), 107-173.
[BC] Braides, A. and A. Coscia. The interaction between bulk energy and surface energy in multiple integrals. Proc. Royal Soc. Edin. 124A (1994), 737-756.
[BDM] Bouchitté, G. and G. Dal Maso. Integral representation and relaxation of convex local functionals on $B V(\Omega)$. Ann. Scuola Norm. Sup. Pisa 20 (1993), 483-533.
[BDV] Braides, A., A. Defranceschi, and E. Vitali. Homogenization of free discontinuity problems. Ref. S.I.S.S.A.199/94/M.

JUL $1: 3 \mathrm{BH}$
[D] Dacorogna, B. Direct Methods in the Calculus of Variations, Applied Math. Sciences 78, Springer-Verlag, 1989.
[DM] Dal Maso, G. An Introduction to 「-Convergence. Birkhäuser, Boston, 1993.
[EG] Evans, L. C. and R. F. Gariepy. Measure Theory and Fine Properties of Functions, CRC Press, 1992.
[F] Federer, H. Geometric Measure Theory. Springer (2nd. edi.), 1996.
[FM1] Fonseca, I. and S. Müller. Quasiconvex integrands and lower semicontinuity in $L^{1}$. SIAM J. Mathematical Analysis 23 (1992), 1081-1098.
[FM2] Fonseca, I. and S. Müller. Relaxation of quasiconvex functionals in $B V\left(\Omega, \mathbf{R}^{p}\right)$ for integrands $f(x, u, \nabla u)$. Arch. Rational Mech. Anal. 123 (1993), 1-49.
[G] Giusti, E. Minimal Surfaces and Functions of Bounded variations. Birkhäuser, Boston, 1984.
[L] Larsen, C.J. Quasiconvexification in $W^{1,1}$ and optimal jump microstructure in $B V$ relaxation. C.N.A. Research report no. 95-NA-024.
[LM] Licht, C. and G. Michaille. Global-local subadditive ergodic theorems and application to homogenization in plasticity. Research report no. 1997/04, Département des Sciences Mathematiques, Université Monpellier II.
[Z] Ziemer, W. P. Weakly Differentiable Functions. Springer-Verlag, Berlin, 1989.

